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Publication date: 2013


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Full-Scale Field Test of a Blade-Integrated Dual-Telescope Wind Lidar
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Introduction
In recent years the use of wind lidars mounted directly on wind turbines has received increasing attention. One aim of turbine-mounted wind lidars is to use them for provision in connection with advanced feed-forward control systems for load reduction and power optimization. To date, main attention has been on control schemes where measurements of wind speeds and direction upwind are used for yaw and speed optimization.

In this study we experimentally investigate the feasibility of using lidars integrated in the turbine blades for alleviating loads and also for active individual pitch control. The measurement campaign ran from July 13 through August 24 2012. At the same time a spinner lidar intended for measuring the inflow in a two-dimensional plane upwind was installed in the turbine and the first results from these experiments will be presented in another EWEA 2013 contribution (PO. ID 126).

Mounting of lidar
The dual-telescope wind lidar consists of two small telescope units with 1° optics connected to a modified ZephIR 300 continuous-wave Doppler lidar² through fibre optic cables. The ZephIR lidar is installed in the spinner of a Vestas NM80 turbine and the telescopes are mounted on either side of one of the blades 16.2 m from the centre of rotation. The two telescopes’ beam axes are converging with approximately 10° angle, resulting in an intersection at 5 m in front of the blade along the cord extension line where also the focus of the laser beams lie. By using an optical switch, operating at a switch rate of 10 Hz, the line-of-sight wind speeds can be measured alternately from the two telescopes.

Results
Figure 1. Example of a normalised Doppler spectrum obtained by telescope T2. The spectrum is seen to contain two distinct peaks located at 24.4 MHz and 25.2 MHz, respectively. The first peak is due to reflections from the ground when the telescope is pointing downwards and if not filtered out this can lead to erroneous wind speed estimations. The second peak is the wind signal which is the combined effect of the wind and the motion of the blade.

Figure 2. Time series of the speed measured by the two telescopes over one a minute period. The measured speeds are seen to oscillate in excellent agreement with each other and also with the rotation period of the turbine. The peaks in wind speed coincide with measurement at the highest point of the rotation, where the wind speed is highest due to shear. Also noticed is a band between 18.0 m/s and 18.5 m/s where no measurements were obtained by Telescope 2. This is due to wind signals coinciding with ground signals and these are therefore filtered out.

Figure 3. Angle-of-attack (AOA) calculated from the speed measurements shown above. In the beginning of the time series the AOA oscillates around 5° and increases to around 75° in the end. An oscillation with the same frequency as above can be seen, although also some noise is present. Missing data points are seen to appear when the ground signal filter has removed the wind signal from telescope T2. This highlights the importance of high data availability.

Conclusions
We present here what we believe are the first successful wind speed measurements from a dual-telescope lidar installed on the blade of an operating wind turbine. The results show a variation in AOA in the blades cut through the shear profile. The full-scale field test performed in the summer of 2012 has clearly demonstrated the possibility of integrating lidar telescopes into turbine blades as well as the capability of the lidar to measure the required wind speeds and to operate in the challenging environment of a rotating spinner and vibrating blade. The use of two separate telescopes allows a direct measurement of the blade’s AOA demonstrating its potential use in future advanced control systems.

Acknowledgements
Steen Andreasen (IPU, Lyngby, Denmark) is gratefully acknowledged for the mechanical design of the 2D scan head of the blade lidar telescopes. Karen Enevoldsen, Per Hansen, Kasper Hjorth Hansen and Claus Brian Munk Pedersen (DTU Wind Energy) are gratefully acknowledged for their skilled assistance with communication software and remote control. Lars Christensen and Michael Rasmussen (DTU Wind Energy) are gratefully acknowledged for their assistance with installation of the lidars in the NM80 test turbine. Dong Energy (Denmark) is gratefully acknowledged for providing access to the NM 80 test turbine at Tjæreborg Energy during the last periods summer and autumn 2012. Vestas Service team is acknowledged for safe control and operation of the NM80 test turbine during the experimental demonstration period.

The technology has been developed as part of the Danish research infrastructure facility activities under the auspices of WindScanner.dk, Danish Agency for Science, Technology and Innovation, respectively. The Infrastructure Grant 2009 Grant No. 2136-08-0022 and the project was financially supported by the Danish Advanced Technology Foundation; Grant 049-2009-3: “Integration of Wind LIDARs In Wind Turbines for Improved Productivity and Control.”

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