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Topological Insulators by Topology Optimization

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An acoustic topological insulator (TI) is synthesized using topology optimization, a free material inverse design method. The TI appears spontaneously from the optimization process without imposing explicit requirements on the existence of pseudospin-1/2 states at the TI interface edge, or the Chern number of the topological phases. The resulting TI is passive, consisting of acoustically hard members placed in an air background and has an operational bandwidth of $\approx 12.5\%$ showing high transmission. Further analysis demonstrates confinement of more than $99\%$ of the total field intensity in the TI within at most six lattice constants from the TI interface. The proposed design hereby outperforms a reference from recent literature regarding energy transmission, field confinement, and operational bandwidth.

As outlined above, significant effort has been invested in the design of TIs, leading to excellent results and new discoveries. The design procedures have, however, hitherto mainly been based on intuition and the bottom-up approach of band-structure engineering. Such approaches do not consider the finite size of the physical structure, disregarding the coupling into and out of the TI. Further, approaches based on intuition are unlikely to lead to optimal designs, possibly leaving a large performance potential untapped.

Inspired by Ref. [18], this Letter proposes a fundamentally different, optimization-based approach capable of designing topological insulators: a top-down approach based on inverse design where the backscattering protected energy transport is targeted directly, with no explicit requirements on the underlying mechanisms. Hence, the approach does not impose explicit requirements on the preexistence of pseudospin-1/2 edge states, nor on the Chern numbers of the topological phases, nor on band symmetry inversion in reciprocal space. These properties appear spontaneously during the design process. A TI designed using the proposed approach is analyzed and demonstrated to suppress backscattering from geometric defects while facilitating spin-dependent, directional energy transport and strong field confinement.

The proposed approach considers a carefully configured finite material slab, illuminated by an acoustic source, placed in a homogeneous background medium. It utilizes density-based topology optimization [23] to solve the inverse design problem starting from an initial guess provided by the user and is inspired by Ref. [24]. It is noted that while the topology optimization method and the topological insulator share the word “topology,” the two uses are not directly related. In topology optimization the word refers to the ultimate spatial design freedom that
approach used previously. Pseudospin-turn bypassing the indirect, bottom-up band-engineering energy transport. By this systematic approach, we directly side, i.e., directional and hence backscattering protected modes that can propagate in directions where medium 1

allows the algorithm to choose the structural topology which optimizes the objective function. Several recent works have demonstrated the benefit of using topology optimization in the design of exotic metamaterials and crystals, such as multifunctional optical metagratings [25], elastic metamaterials with negative effective material parameters [26], and self-collimating phononic crystals [27]. Further, two review papers [28,29] of inverse design works have demonstrated the benefit of using topology optimization in the design of exotic metamaterials and symmetries.

The physics is modeled using a Helmholtz-type equation,

$$\nabla \cdot \left( C_1 \frac{\alpha_0 - ic\alpha}{\alpha_0} \nabla \Psi \right) + C_2 \left( \frac{\alpha_0 - ic\alpha}{\alpha_0} \right)^3 \Psi = -p_S, \quad (1)$$

where $C_1(r)$ and $C_2(r)$ are material-dependent parameters, $i$ is the imaginary unit, $\alpha(r)$ is an attenuation parameter, $\omega_0 = 2\pi f_0$ is the free-space angular frequency, $c$ is the free-space wave speed, $\Psi(r)$ is the state field, and $r$ is the spatial position. For the acoustic case, $\Psi = p$, where $p(r)$ is the sound pressure, and $\{C_1, C_2\} = \{(1/\rho), (1/\kappa)\}$, where $\rho(r)$ and $\kappa(r)$ are the density and bulk modulus, respectively. Material parameters for air and aluminium are used [31]. The impedance contrast between the two ensuring that vibrations exited in the solid are negligible, and thus Eq. (1) accurately captures the physics, as verified in Refs. [32,33].

The design problem is formulated as a continuous constrained optimization problem and solved using density-based topology optimization. A spatial design field $\xi(r) \in [0, 1] \quad \forall \ r \in \Omega_{\text{IR},1} \cup \Omega_{\text{IR},2}$ is introduced to control the periodic material distributions in $\Omega_{\text{IR},1}$ and $\Omega_{\text{IR},2}$ by interpolating $C_1$ and $C_2$ between the material parameters as
\[ C_i^{-1}(r) = C_{i_{\mu}}^{-1} + \xi(r) \delta(C_{i_{\text{min}} \mu}^{-1} - C_{i_{\text{max}} \mu}^{-1}), \quad i \in \{1, 2\}. \] (2)

Figure 1(b) shows the base design cells in which the material distribution is manipulated to solve the optimization problem. The content of each base cell is duplicated throughout \( \Omega_{\text{dR},1} \) and \( \Omega_{\text{dR},2} \) to construct the material distribution (topological phases) used when solving Eq. (1). For the example treated in this Letter, \( C3v \) symmetry is imposed on both base cells. The designable region is colored gray and the mirror symmetries are shown using dashed lines. An example of a design for one phase and its symmetry is illustrated.

The optimization problem is written as

\[
\max_{\xi(r) \in [0,1]} \Phi_{\text{Total}}(\xi) = \sum_{i=1}^{3} \Phi_{\text{Max}_i}(\xi) - \Phi_{\text{Min}_i}(\xi),
\] (3)

s.t. \( \Phi_{\text{BG}}(\xi) \leq \gamma_1, \) (4)

\[ \gamma_2 < \Phi_{\text{Max}_2}(\xi)/\Phi_{\text{Max}_3}(\xi) < \gamma_3, \] (5)

where \( \Phi_{\text{Total}} \) is the objective function consisting of a linear combination of the terms \( \Phi_{\text{Max}_i}, \) \( i \in \{1, 2, 3\}, \) and \( \Phi_{\text{Min}_i}, \) all of which are integrals of the field intensity magnitude over \( \Omega_{\text{Max}_i}, \) \( i \in \{1, 2, 3\}, \) and \( \Omega_{\text{Min}_i}, \) while \( \Phi_{\text{BG}} \) denotes the integral of the field intensity magnitude over \( \Omega_{\text{BG}}; \) see Fig. 1(d). The constants \( \gamma_j > 0, j \in \{1, 2, 3\} \) control the constraints Eqs. (4) and (5), and \( \Phi_* \) is calculated as

\[
\Phi_*(\xi) = \tau_* \int_{\Omega_1} |I(\Psi(\xi))| \, dr / \int_{\Omega_2} \, dr.
\]

\[
* \in \{\text{Max}_j, \text{Min}, \text{BG}\}, \quad i \in \{1, 2, 3\}. \] (6)

Here \( I(\Psi(\xi)) \) denotes the field intensity and \( \tau_* \) a set of scaling constants. The choice of \( \Phi_{\text{Total}} \) leads to a maximization of the energy transmitted into \( \Omega_{\text{Max}_1} \) and \( \Omega_{\text{Max}_2} \) along with a simultaneous minimization of the energy transmitted into \( \Omega_{\text{Min}_3}. \) That is, in order to maximize \( \Phi_{\text{Total}}, \) any field emitted by \( \mathbf{P}_S \), propagating along the interface between \( \Omega_{\text{dR},1} \) and \( \Omega_{\text{dR},2}, \) must keep \( \Omega_{\text{dR},1} \) on its right-hand side and \( \Omega_{\text{dR},2} \) on its left-hand side at all times. This in turn promotes backscattering protected transport of energy along the interface. The constraint Eq. (4) ensures that a bulk band gap exists in both topological phases, as energy is prohibited from propagating into \( \Omega_{\text{BG}}. \) The constraint Eq. (5) may be used to control the ratio of the intensity transmitted to \( \Phi_{\text{Max}_1} \) and \( \Phi_{\text{Max}_3} \), respectively.

The design problem, Eqs. (1)–(6), is implemented and solved in COMSOL MULTIPHYSICS 5.3 using the globally convergent method of moving asymptotes [34] to solve Eqs. (3)–(5). The objective function gradients are calculated using adjoint sensitivity analysis [28]. A physically admissible final design, consisting solely of solid and air and free of numerical artifacts, is assured using the projection and filtering procedure outlined in Refs. [24,35,36].

For the TI considered in the following, Eqs. (1)–(6) are solved with \( \{\alpha = 0.01 \text{ m}, f_0 = 20 \text{ kHz}, c = 343 \text{ m/s}, \alpha = 6 \text{ dB/} \lambda \ \forall \ r \in \Omega_{A}, \alpha = 0 \text{ dB/} \lambda \ \forall \ r \in \Omega_{\text{dR},1} \cup \Omega_{\text{dR},2}, \gamma_2 = 0.3, \gamma_3 = 0.04, \gamma_2 = 0.3, \gamma_3 = 1.7, \tau_{\text{Max}_3} = 1, \tau_{\text{Max}_2} = 1, \tau_{\text{Max}_1} = 0.1, \tau_{\text{Min}} = 4, \tau_{\text{BG}} = 1.\} \) The initial \( \xi(r) \) layout, shown in Fig. 2(a), is chosen to constitute a crystal with a bulk band gap at \( f_0 \) [see the band structure in Fig. 3(a)]. The final material layout obtained from the optimization process is shown in Fig. 2(b), with white (black) representing solid (air).

The max-normalized pressure field at \( f_0 = 20 \text{ kHz} \) along with the initial and optimized material configurations in \( \Omega_{\text{dR},1} \cup \Omega_{\text{dR},2} \) are shown in Figs. 2(c) and 2(d), respectively. The bulk band gap of the initial material configuration is observed. For the optimized TI it is clear that the vast majority of the energy flowing into port \( P1 \) is transmitted to either port \( P2 \) or port \( P4. \) Simultaneously, a bulk band gap is observed for both phases of the TI. Figure 2(e) presents a frequency sweep of the transmission
to $P_2$, $P_3$, and $P_4$, normalized to the power flowing through $P_1$: $10 \log_{10}(|P_x|/|P_1|)$. It is seen that $99.5\%$ of the acoustic power is transmitted from $P_1$ to $P_2$ and $P_4$ at $f_0 = 20$ kHz. Further, the transmission does not drop below $-0.85$ dB from 18 to 20.4 kHz.

The above discussion demonstrates that the top-down approach results in the desired macroscopic response. However, this could in principle be attained without having designed a TI. That a TI has indeed appeared spontaneously through the optimization process is revealed in the following analysis. Figure 3(b) shows the band structure diagram, calculated for the TI supercell shown in Fig. 3(c) using periodic boundary conditions on the top and bottom edges and Neumann conditions on the left and right edges. The bulk-band regions are colored gray and the two "crossing" symmetry inverted edge-state bands are colored red and blue corresponding to the positive or negative pseudospin-1/2 edge states, shown for $f_0 = 20$ kHz in Figs. 3(d) and 3(e), respectively. From Fig. 3(b) the bulk band gap is seen to stretch from $\approx 18$ to $\approx 20.4$ kHz, i.e., $\approx 12.5\%$. A narrow gap is seen in the two edge-state bands at the $k_{||} = 0$ point. A similar gap was reported in Ref. [18], where it was explained to originate from the imperfect cladding layer. Figure 3(f) shows the band structures for the two crystal phases constituting the TI, revealing degeneracies for bands 2 and 3 and bands 4 and 5 at the $\Gamma$ point for both phases.

To further investigate if a TI supporting geometrically robust backscattering protected transport of acoustic energy has been designed, studies on the effect of introducing defects in the TI are performed. Figure 4 presents four examples, with Fig. 4(a) showing a slab without defects, while Figs. 4(b)–4(d) show a bend, cavity, and disorder defect, respectively. The three defects all preserve the symmetry of the bulk materials and are shown in Fig. 1(a) (highlighted green). The slabs are excited by a point source positioned 0.3a from their left edge, at the interface of the two topological phases. The power, transmitted through the TI, is computed at the right-hand side of the slab and the results are reported in Fig. 4(e), max normalized with respect to the nondefect TI. Figure 4(e) reveals agreement of the transmitted power inside the bulk band gap across the four cases. The largest deviation between the nondefect and defect structures is 2.5 dB, and intervals showing less than 0.25 dB deviation are observed supporting that a TI offering backscattering protected propagation has been designed. The differences in transmission seen in Fig. 4(e) are orders of magnitude smaller than the differences observed across the majority of the band of operation for similar defects in a traditional phononic crystal waveguide, with a worst-case value of more than 25 dB reported in Ref. [18].

An important aspect to consider when designing systems for energy or information transport, such as waveguides, is the footprint of the system. In the present context, the footprint refers to how wide the material slab must be to confine a certain fraction of the transported energy. From Fig. 4(a), the pressure field in the TI appears to be confined (to a 30-dB level) inside approximately 3a from the TI interface edge. An investigation of the spatial confinement of the field is performed using the TI from Ref. [18] as a
showing the distance the reference design that more than 99% of the power is contained within a distance of 6 provided in Fig. 5(b). The map reveals that at most a power is confined versus frequency for both TIs is achieved by the resulting TI is demonstrated through protected, directional energy transport. That the effect is directly targets the desired effect of backscattering protection. In summary, this Letter reports on the design of a topological insulator using a top-down approach based on density-based topology optimization. The approach directly targets the desired effect of backscattering protected, directional energy transport. That the effect is achieved by the resulting TI is demonstrated through numerical studies. Experimental validation of the approach may be found in Ref. [33], where a metamaterial exhibiting negative refraction is considered.

The proposed design approach is trivially extendable to photonics, assuming TE or TM polarized light. Further, by introducing additional design constraints and goals it is straightforwardly extendable to, e.g., consider global defects in the TI or to target a maximization of the operational bandwidth in the design process. Hence, the approach has freedom to tailor TIs to operate under alternative conditions.

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\[
P_f(d) = \frac{\int_0^d \mathbf{n} \cdot \mathbf{I}(y) dy}{\int_{-\infty}^{\infty} \mathbf{n} \cdot \mathbf{I}(y) dy}, \quad d > 0.
\]

The results for \( f_0 = 20 \, \text{kHz} \), shown in Fig. 5(a), reveal that more than 99% of the power is confined within \( d \approx 3a \) for the TI design proposed in this Letter, while for the reference design \([18]\) \( d \approx 9a \) is required. A map showing the distance \( d \) within which 99% or more of the power is confined versus frequency for both TIs is provided in Fig. 5(b). The map reveals that at most a distance of 6a is required to contain 99% of the power for the proposed TI.