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Ash formation and deposition in coal and biomass fired combustion systems: Progress and challenges in the field of ash particle sticking and rebound behavior

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\textbf{Abstract}

The purpose of this paper is to review the present knowledge on ash formation, ash particle transport and deposition during solid fuel combustion, with emphasis on particle sticking and rebound behavior. A substantial part of the fuel can be inorganic, forming inorganic vapors and ash particles. The impaction of solid, molten or partially molten particles on surfaces is dependent on the particle and surface characteristics. For instance, a particulate deposit might capture incoming particles or be removed due to erosion, while a molten layer will collect all impacting particles, no matter if they are sticky or not. The main properties affecting the particle stickiness are the viscosity and surface tension for silicate-rich ashes. On the contrary, the stickiness of salt-rich ashes – typical for herbaceous biomass and wood- or waste-based fuels – is often described using the liquid melt fraction. Furthermore, the particle kinetic energy and the angle of impaction are crucial parameters. If all kinetic energy is dissipated during the impact, the particle will remain on the surface. This review presents an overview of major ash forming elements found in biomass and coal, and discusses the heterogeneity of particles’ inorganic composition. Ash transport and deposition mechanisms as well as their mathematical description are given and discussed, together with composition- and temperature-dependent models for the estimation of ash particle and deposit properties. These properties are essential in order to describe the particle sticking and rebound behavior.

Ash particle sticking and rebound criteria can be divided into three main groups, based on either: (1) the particle melt fraction, (2) the particle viscosity, or (3) the energy dissipation of a particle, upon impaction. Sticking criteria are presented, their required parameters are discussed and typical particle and surface properties found in combustion systems, are summarized. Eight different sticking criteria are implemented in a computational fluid dynamics code and computations are compared against measurements from an entrained flow reactor. Uniform sized soda-lime glass particles are applied instead of inhomogeneous fly ash particles, since soda-lime glass is known to behave similar to coal fly ash. Best agreement for the deposition rates on a clean tube is achieved using a criterion based on the work of Srinivasachar et al.\textsuperscript{[1]}. In this model, the sticking and rebound threshold, is a function of the particle kinetic energy, the angle of impact, and the particle viscosity. Particularly, the particle viscosity is confirmed as a key parameter for silicate-rich ashes. It should be calculated using temperature- and composition-dependent correlations, being aware that there is a significant scattering in the results from such models and that the models are often only valid in narrow compositional ranges, and cannot be used outside these. A mechanistic model is used to explain results from glass particle experiments and their dependence on the particle kinetic energy. Therefore, the impaction process is subdivided in four steps, and the energy dissipation of each step is calculated. These theoretical considerations show that the contact angle of a molten droplet with the substrate is of minor importance, and that the majority of depositing particles are dominated by the work of deformation against viscosity, rather than surface tension effects.

This review underlines the importance of the particle viscosity, and its accurate prediction for silicate-rich ashes. The proposed criterion is able to predict the sticking of small, solid particles below 10 \(\mu\)m diameter, as it is often observed in literature. Also, it is crucial to consider the surface structure and stickiness, in order to predict deposition rates in solid fuel-fired systems. Biomass ashes and their stickiness are more difficult, due to a different ash particle chemistry, compared to coal ashes. Salt-rich particles and their stickiness are
controlled by the amount of liquid phase. Here, a link between the viscosity and amount of liquid phase is a promising approach, and should be addressed in future work. Furthermore, the viscosity of different ash particles — silicate-, salt- or Ca-rich — should preferentially be modeled from chemical and physical structure instead of an empirical fitting procedure between fuel chemistry and viscosity measurements.

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### Nomenclature

#### Abbreviations:
- **ADLVIC** Ash deposit Local Viscosity, Index of refraction and Composition
- **PAS** Aerodynamic Particle Sizer
- **AT** Arrhenius Type
- **BFB** Bubbling Fluidized Bed
- **BLPI** Berner type Low Pressure Impactor
- **BSE** Back-Scattered Electron
- **C** Criterion
- **CCSEM** Computer-Controlled Scanning Electron Microscopy
- **CFB** Circulating Fluidized Bed
- **CO** COndensation
- **COR** Coeficient Of Restitution
- **DEM** Discrete Element Method
- **DI** Diffusion
- **DMA** Differential Mobility Analyzer
- **DO** Discrete Ordinates
- **DSC** Differential Scanning Calorimetry
- **DTM** Discrete Transfer Method
- **EDX** Energy Dispersive X-Ray
- **EF** Eulerian Formulation
- **EFRI** Entrained Flow Reactor
- **EI** Eddy Impaction
- **ELPI** Electrostatic Low Pressure Impactor
- **ESP** ElectroStatic Percipitator
- **FB** Fluidized Bed
- **FG-DVC** Functional Groups - Depolymerization Vaporation and Cross-linking model
- **FLOREAN** FLOw and REAction - CFD code
- **FM** Inertial impaction
- **JKR** Johnson-Kendall-Roberts
- **KD** Kinetics/Diffusion limited char combustion model
- **KW 21** KraftWerke des 21. Jahrhunderts
- **LEADER** Low-temperature Engineering Algorithm of DEposition Risk
- **LHV** Lower Heating Value
- **LT** Lagrangian Tracking
- **MIT** Massachusetts Institute of Technology
- **MSW** Municipal Solid Waste
- **NBO** Non-Bridging Oxygen
- **PCGC** Pulverized Coal Gasification and Combustion
- **PF** Pulverized Fuel
- **PM** Particulate Matter
- **PSD** Particle Size Distribution
- **QEMSCAN** Quantitative Evaluation of Minerals by SCANning electron microscopy
- **RH** ReHeater
- **RMSE** Root Mean Square Error
- **RNG** Re-Normalization Group for turbulence modeling
- **SE** Semi-Empirical
- **SEM** Scanning Electron Microscope
- **SH** SuperHeater
- **SMPS** Scanning Mobility Particle Sizer
- **SR** Single Rate devolatilization model
- **SRF** Solid Recovered Fuel
- **SST** Shear Stress Transport
- **STA** Simultaneous Thermal Analysis
- **TEC** Thermodynamic Equilibrium Calculation
- **TGA** Thermo-Gravimetric Analyzer
- **TP** Thermophoresis
- **TR** Two competing Rates devolatilization model
- **UC** Unit Cell
- **UDF** User-Defined Function
- **WT** Weymann Type
- **XRD** X-Ray Diffraction

#### Latin Symbols:
- \( a, b [-] \) fitting parameter
- \( A \left[ m^2 \right] \) area
- \( A \left[ (m^2/kmol^{n-1})/s \right] \) pre-exponential factor
- \( A_0 \left[ J \right] \) Hamaker constant
- \( A_{\alpha}, A_{\beta}, H_{\alpha}, H_{\beta} [-] \) coefficients for the thermophoretic coefficient
- \( A, B, C, D [-] \) fitting parameter
- \( Bi [-] \) Biot number
- \( B/A [-] \) ratio of base to acid fuel ash components
- \( c_i [mol/m^3] \) concentration of species \( i \)
- \( c_p [J/(kg K)] \) heat capacity
- \( C_r, C_m, C_{int} [-] \) temperature jump, velocity slip, and interp. constant
- \( C_m [-] \) proportionally factor
- \( Ca [-] \) Capillary number
- \( d [m] \) diameter
- \( D [m] \) diameter of a tube/cylinder
- \( D_A, B \left[ m^2/s \right] \) diffusion coefficient of species \( A \) in species \( B \)
- \( D_{Kn} \left[ m^2/s \right] \) Knudsen diffusion coefficient
- \( D_{e} \left[ m^2/s \right] \) particle Brownian diffusion coefficient
- \( DT \left[ ^\circ C \right] \) deformation temperature (ash fusion test for biomass)
- \( e [A s] \) elementary charge
- \( e [-] \) coefficient of restitution
- \( e_n, e_t [-] \) normal (\( n \)) and tangential (\( t \)) restitution coefficient
- \( E [J/J] \) energy
- \( E [V/m] \) electric field strength
- \( E [MPa] \) Young's modulus
- \( E_A \left[ kJ/mol \right] \) activation energy
- \( E_{ex} [-] \) excess rebound energy
- \( f [-] \) coefficient of friction
- \( f_p [-] \) melt fraction
- \( f_{11}, f_{22}, f_{33} [-] \) functions for the thermophoretic coefficient
- \( F [N] \) Force
- \( FT \left[ ^\circ C \right] \) fluid temperature (ash fusion test)
- \( g [m/s^2] \) gravitational acceleration
- \( G [MPa] \) shear modulus
- \( h [W/(m^2 K)] \) heat transfer coefficient (often introduced as \( \alpha \))
- \( h [kJ/kg] \) specific enthalpy
- \( h [m] \) height
- \( H [-] \) function for the sticking probability
- \( H_f [kJ/kg] \) heat/enthalpy of fusion
- \( HT \left[ ^\circ C \right] \) hemispherical temperature (ash fusion test)
<table>
<thead>
<tr>
<th>Greek Symbols:</th>
<th>Subscripts:</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \alpha_\text{m} ) [-]</td>
<td>0, 1, 2 collision partner 1 and 2</td>
</tr>
<tr>
<td>( \alpha_{\text{shed}} ) [-]</td>
<td>initial</td>
</tr>
<tr>
<td>( \beta ) [-]</td>
<td>10, 50, 90 percentage under this value</td>
</tr>
<tr>
<td>( \chi ) [-]</td>
<td>adhesion</td>
</tr>
<tr>
<td>( \gamma ) [kg/s²]</td>
<td>work</td>
</tr>
<tr>
<td>( \varepsilon ) [-]</td>
<td>WEB number</td>
</tr>
<tr>
<td>( \varepsilon_i ) [-]</td>
<td>fitting parameter for sintering law</td>
</tr>
<tr>
<td>( \varepsilon_i ) [m²/s³]</td>
<td>coordinate in all three spatial directions</td>
</tr>
<tr>
<td>( \epsilon ) [-]</td>
<td>mole fraction of species i</td>
</tr>
<tr>
<td>( \epsilon_a, \epsilon_i ) [-]</td>
<td>elasticity length scale, distance, surface roughness</td>
</tr>
<tr>
<td>( \eta_{\text{front}}, \eta_{\text{back}} ) [-]</td>
<td>yield strength</td>
</tr>
<tr>
<td>( \eta ) [m]</td>
<td>energy and momentum accommodation coefficients for TP</td>
</tr>
<tr>
<td>( \eta_i ) [-]</td>
<td>order of shedding</td>
</tr>
<tr>
<td>( \eta_i ) [-]</td>
<td>contact area ratio</td>
</tr>
<tr>
<td>( \eta_i ) [-]</td>
<td>radiative exchange factor</td>
</tr>
<tr>
<td>( \eta_i ) [-]</td>
<td>surface tension (sometimes defined as ( \sigma ))</td>
</tr>
<tr>
<td>( \epsilon_i ) [-]</td>
<td>emissivity</td>
</tr>
<tr>
<td>( \xi ) [-]</td>
<td>strain</td>
</tr>
<tr>
<td>( \xi_i ) [-]</td>
<td>dissipation rate</td>
</tr>
<tr>
<td>( \xi_\text{c} ) [-]</td>
<td>electrical charge parameter</td>
</tr>
<tr>
<td>( \xi_\text{f} ) [-]</td>
<td>impaction efficiency cylinder front and rear face</td>
</tr>
<tr>
<td>( \lambda ) [m]</td>
<td>free mean path length of molecules</td>
</tr>
<tr>
<td>( \lambda_i ) [-]</td>
<td>mean number of mineral inclusion per particle</td>
</tr>
<tr>
<td>( \lambda_i ) [-]</td>
<td>parameter for the maximum contact pressure</td>
</tr>
<tr>
<td>( \lambda_{\text{c}} ) [-]</td>
<td>dynamic viscosity (sometimes defined as ( \eta ))</td>
</tr>
<tr>
<td>( \nu ) [-]</td>
<td>Poisson number</td>
</tr>
<tr>
<td>( \nu ) [-]</td>
<td>kinematic viscosity</td>
</tr>
<tr>
<td>( \xi_\text{c} ) [-]</td>
<td>spread diameter</td>
</tr>
<tr>
<td>( \rho ) [kg/m³]</td>
<td>density</td>
</tr>
<tr>
<td>( \sigma ) [W/(m² K)]</td>
<td>Stefan Boltzmann constant</td>
</tr>
<tr>
<td>( \sigma ) [-]</td>
<td>mechanical stress</td>
</tr>
<tr>
<td>( \sigma ) [MPa]</td>
<td>characteristic flow time for flow around cylinder</td>
</tr>
<tr>
<td>( \tau_\text{c} ) [s]</td>
<td>particle relaxation time</td>
</tr>
<tr>
<td>( \tau_\text{p} ) [s]</td>
<td>dimensionless particle relaxation time</td>
</tr>
<tr>
<td>( \tau_{\text{el}} ) [-]</td>
<td>wall shear stress</td>
</tr>
<tr>
<td>( \tau_{\text{el}} ) [kg/(s² m)]</td>
<td>viscous dissipation function</td>
</tr>
<tr>
<td>( \phi ) [kg/(s³ m)]</td>
<td>angle of impaction between particle and surface</td>
</tr>
<tr>
<td>( \varphi ) [rad]</td>
<td>correction factor for effective Stokes number</td>
</tr>
<tr>
<td>( \psi ) [-]</td>
<td>specific dissipation rate</td>
</tr>
<tr>
<td>( \omega ) [s⁻¹]</td>
<td>distance between particle surface and substrate</td>
</tr>
<tr>
<td>( \Delta ) [m]</td>
<td>angle indicating the position around cylinder</td>
</tr>
<tr>
<td>( \Theta ) [rad]</td>
<td>contact angle between substrate and droplet</td>
</tr>
<tr>
<td>( \Theta_\text{c} ) [rad]</td>
<td>thermal conductivity ratio</td>
</tr>
<tr>
<td>( \Delta ) [-]</td>
<td>thermophoretic coefficient or phase function of thermal radiation</td>
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<table>
<thead>
<tr>
<th>Subscripts:</th>
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<tbody>
<tr>
<td>0</td>
</tr>
<tr>
<td>1, 2</td>
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<tr>
<td>10, 50, 90</td>
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<td>ad</td>
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</tbody>
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<table>
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<tr>
<th>Initial Deformation Temperature (ash fusion test)</th>
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</thead>
<tbody>
<tr>
<td>( J_{\text{W}} ) [kg/(m²s)]</td>
</tr>
<tr>
<td>( J_{\text{p}} ) [kg/(m²s)]</td>
</tr>
<tr>
<td>( k ) [W/(m K)]</td>
</tr>
<tr>
<td>( k^{-1} ) [m]</td>
</tr>
<tr>
<td>( k_{\text{r}} ), ( k_{\text{shed}} ) [-]</td>
</tr>
<tr>
<td>( k_{\text{p}}, k_{\text{w}} ) [-]</td>
</tr>
<tr>
<td>( k_{\text{s}} ) [-]</td>
</tr>
<tr>
<td>( Kn ) [-]</td>
</tr>
<tr>
<td>( K_{\text{r}} ) [-]</td>
</tr>
<tr>
<td>( m ) [kg]</td>
</tr>
<tr>
<td>( m ) [kg/s]</td>
</tr>
<tr>
<td>( M_i ) [kg/kmol]</td>
</tr>
<tr>
<td>( n, m ) [-]</td>
</tr>
<tr>
<td>( n, m, k ) [-]</td>
</tr>
<tr>
<td>( p ) [Pa]</td>
</tr>
<tr>
<td>( p_i ) [Pa]</td>
</tr>
<tr>
<td>( p_i ) [-]</td>
</tr>
<tr>
<td>( p_{\text{stick}} ) [-]</td>
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<tr>
<td>( P ) [N s]</td>
</tr>
<tr>
<td>( P_e ) [-]</td>
</tr>
<tr>
<td>( Pr ) [-]</td>
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<tr>
<td>( q ) [A s]</td>
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<tr>
<td>( q ) [W/(m²K)]</td>
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<tr>
<td>( Q ) [W]</td>
</tr>
<tr>
<td>( Q_\text{t} ) [-]</td>
</tr>
<tr>
<td>( r_\text{p}, r_i ) [m]</td>
</tr>
<tr>
<td>( R ) [l/(mol K)]</td>
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<tr>
<td>( R_i ) [K/W]</td>
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<tr>
<td>( R ) [-]</td>
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<tr>
<td>( Re ) [-]</td>
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<td>( s ) [m]</td>
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<td>( s_\text{fl} ) [m]</td>
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<td>( s_\text{i} ) [-]</td>
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<tr>
<td>( Sc ) [-]</td>
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<td>( Sh ) [-]</td>
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<tr>
<td>( SST ) [°C]</td>
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<tr>
<td>( S_\text{r} ) [-]</td>
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<td>( S_\text{e} ) [-]</td>
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<td>( ST ) [°C]</td>
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<td>( t ) [s]</td>
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<td>( T ) [K], [°C]</td>
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<tr>
<td>( u, v, w ) [m/s]</td>
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<td>( u_{\text{f}} ) [-]</td>
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<td>( \bar{v}_\text{m} ) [m/s]</td>
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<tr>
<td>( V ) [m³]</td>
</tr>
<tr>
<td>( V_i ) [m³/kmol]</td>
</tr>
<tr>
<td>( V_{\text{dep}} ) [-]</td>
</tr>
<tr>
<td>( W ) [wt.%]</td>
</tr>
<tr>
<td>( \xi_\text{c} ) [-]</td>
</tr>
<tr>
<td>( \lambda ) [m]</td>
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<tr>
<td>( \mu ) [kg/(s m)]</td>
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<tr>
<td>( \rho ) [kg/m³]</td>
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<tr>
<td>( \sigma ) [W/(m² K)]</td>
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<td>( \sigma ) [MPa]</td>
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<td>( \tau_\text{c} ) [s]</td>
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<tr>
<td>( \tau_{\text{el}} ) [kg/(s² m)]</td>
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<tr>
<td>( \phi ) [kg/(s³ m)]</td>
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<tr>
<td>( \varphi ) [rad]</td>
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<tr>
<td>( \psi ) [-]</td>
</tr>
<tr>
<td>( \omega ) [s⁻¹]</td>
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<td>( \Theta_\text{c} ) [rad]</td>
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<td>( \Delta ) [-]</td>
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<td>( \Phi ) [-]</td>
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1. Introduction

Ash deposition on heat exchanging surfaces during solid fuel combustion, leads to a number of operational problems, and may cause frequent power plant shutdowns, reduced heat transfer rates or increased soot-blowing and cleaning activities [14–16]. The main route between a burning fuel particle in a furnace, and a troublesome deposit on a heat transfer surface, can be divided into a number of consecutive steps:

- Release of critical ash-forming elements (mainly K, Na, S, Cl, Zn, and Pb), during devolatilization, and subsequent char burnout,
- Formation of aerosol particles by nucleation and coagulation of flame-volatilized ash-forming elements,
- Formation and entrainment of coarse fly ash particles through mineral transformation (chemically and physically) during devolatilization and char burnout,
- Transport of ash species, i.e. gases, liquids (droplets) and solids (particles), from bulk gas to heat transfer surfaces,
- Sticking, adhesion or rebound of these ash species on heat transfer surfaces, and
- Build-up, sintering and consolidation, erosion and shedding of deposits.

Through several years, high-quality research has been conducted to characterize fuels [2–6], investigate fuel conversion and ash formation [7–11], as well as ashes and deposit formation in utility boilers fired with coal, biomass and waste fractions [12–20]. Huge amounts of experimental data have been gained, but the fact is that there are still in 2017, a number of big gaps in our current understanding of ash and deposit formation in utility boilers, and that we need to focus strongly on these points, in order to be able to describe, understand and quantify the process of deposit formation completely. Many high-quality data are available on the release of critical ash-forming elements, although most of the lab-scale measurements are performed under experimental conditions different from what happens in full-scale. The main difference being the particle size distribution of the fuels investigated, and the time-temperature history, mainly the heat-up rate and final temperature, experienced by the fuel particles. Further important differences between small-scale setups and furnace environments are particle concentrations affecting particle dynamics and particle formation by condensation, as well as the fact that drop tube studies are often conducted with high excess air and low gas velocities. Both, particle concentration and excess air, are crucial explaining partial vaporization, e.g. of alkali metals. Fly ash formation has been intensively studied for coal combustion, where the fly ash size distribution has a multi-modal size distribution [21–23]. Larger particles originate from mineral grains in coal and their size distribution depends upon the coal characteristics, pre-treatment (sizing) of the coal, and, the actual combustion conditions. Sub-micron particles on the contrary, originate mainly from homogeneous nucleation, and subsequent coagulation of flame-volatilized inorganic species. Other important processes going on include fragmentation of chars and mineral inclusions as well as coalescence of ash droplets on receding char surfaces. A number of basic mechanisms of ash species transport has been outlined and quantified in the literature during the last 20 years, but a very crucial aspect of ash deposition, the process when an ash particle impacts on a heat exchanging surface, is often not addressed or discussed in detail. There is a lack of a comprehensive review in the field of ash particle sticking and rebound behavior and a comparison of different sticking criteria in terms of accuracy and performance. In this field, many publications use inappropriate models underlining the necessity of a review. Therefore, this paper summarizes ash formation and deposition mechanisms, discusses the differences between biomass and coal, and presents a critical literature review on ash particle sticking and rebound criteria.

This paper is organized in the following manner. Section 2 provides the fundamentals of solid fuel combustion systems, inorganic constituents in solid fuels, ash formation, fly ash particles and their classification, deposit formation mechanisms as well as an overview on the effect of deposits on heat transfer. It is a summary of major
literature references, however, due to the enormous amount of studies in this wide field, it is not possible to include all findings. Section 3 gives mathematical models for the estimation of particle and deposit properties. These properties are required in order to describe the ash particle stickiness. The following two sections review experimental and theoretical studies on ash particle sticking and rebound behavior. Different sticking criteria found in literature are summarized and discussed critically for their applicability. Section 6 evaluates and compares different sticking criteria and explains main findings. Section 7 presents a comprehensive model describing all relevant processes during ash deposition in solid fuel-fired systems. Finally, an outlook and recommendations for future work is given and conclusions are drawn.

2. Fireside deposit formation

Solid fuel combustion has been subject to research for more than 100 years. But still today there are many unresolved problems and phenomena, which are not understood in detail. Many existing mathematical models describing solid fuel conversion are empirical in nature and fitted towards measurements. One of the main reasons is the heterogeneity and complex chemical structure of solid fuels and their changes during thermal conversion. Fuel conversion in combustion systems involves homogeneous and heterogeneous chemical reactions, changing particle structures entrained in a turbulent flow combined with radiative heat transfer. The complex interaction of these phenomena, is the main difficulty in understanding and modeling such systems.

2.1. Solid fuel combustion systems

Typical solid fuel combustion systems are illustrated and compared in Fig. 1. They comprise of three main types: grate combustion, fluidized bed (FB) combustion and pulverized fuel (PF) combustion systems. Characteristics of each boiler type are summarized underneath each schematic. The main difference among boiler types is boiler size, fuel quality, fuel processing before combustion, fuel-oxidizer ratio, gas flow conditions as well as temperatures.

Pulverized fuel boilers are the most commonly built systems for power generation from coal. Pulverized fuel, with a typical particle size smaller than 200 μm, is transported with preheated air or recirculated flue gas to the burner and into the furnace. Particles heat up, release combustible gases and react with oxygen, forming flue gas. The flue gas is transported with the remaining ash particles through the combustion chamber. Boiler walls and tubes inside the combustion system act as heat exchanging surfaces, where heat is transferred from the flue gas to the water-steam cycle. PF systems are designed in a way that combustion is completed before the flue gas reaches the first convective heat exchanger in the form of tube banks. This ensures lower temperatures of remaining fly ash particles, compared to burning particles, and thus a reduced threat of molten, sticky ash particles adhering to heat exchanging surfaces. There are studies indicating that char particles burn at temperatures up to 300 K higher than the surrounding flue gas [24]. A critical parameter, when designing the furnace and its height, is the ash softening and ash melting temperature. The furnace exit gas temperature should stay below the ash softening temperature. However, this criterion can also fail. There are studies reporting up to 50% of melt in the ash system at the ash softening temperature [25,26]. In this case, there can be excessive deposit formation, even though the furnace exit gas temperature is below the ash softening temperature. The main difficulty in boiler design is to achieve a high level of burnout, while staying below the ash softening temperature. This is challenging, since nowadays, fuel and load flexibility become more and more important. Within combustion systems, ash deposition is often defined as either slagging or fouling. Slagging occurs in the furnace area, where heat exchanging surfaces are exposed directly to flame radiation. A further definition states that particles or deposits are molten, and thus in the liquid state. Fouling is referred to deposits, which are not directly exposed to flame radiation. Deposits in this area are typically caused by solidified particles. Fouling layers are loosely bound or partly sintered, and therefore usually more easy to clean [15]. Fig. 1 shows areas threatened by slagging (filled with gray color) and fouling (no color). In modern tower boiler configurations, this area ends after the first superheater, when radiation of the flame is shaded by earlier tube banks. In the conventional two path boiler design, this area is in the cross-over path between the first and the second duct. The transition between slagging and fouling is smooth and the extent to which a certain fuel leads to slagging or fouling is highly dependent on the form and chemical composition of the inorganic material within the fuel as well as the process conditions inside the boiler.

Fluidized bed combustion systems can be characterized as either bubbling fluidized bed (BFB) or circulating fluidized bed (CFB) combustion systems. The basic idea is to burn the fuel in a hot bed of small particles, e.g. quartz sand, which are fluidized using combustion air from below. The bed material is typically kept at relatively low temperatures (800–900 °C) in order to reduce pollutant formation, particle agglomeration (e.g. caused by low melting ash particles), ash deposition and corrosion. Furthermore, chemically inert material is used to inhibit reactions between fuel ash and bed materials. An exception are sulfur-rich fuels (e.g. pet-coke), where limestone is added to the bed material, in order to reduce SO₂ emissions. The combustion air is injected using jets from below and depending on gas velocity, particle size and density of the bed material, bed material is entrained in the flow (CFB) or it remains in a bubbling bed (BFB - stationary fluidized bed). CFB systems circulate the bed material and require a separation unit, typically a cyclone. These systems enable a higher energy density and improved heat transfer rates, however design and operation are more complex. Furthermore, bed material such as quartz is known to be erosive, leading to erosion on heat exchanging surfaces and/or to the removal of deposits. Fluidized bed combustion systems are characterized by good mixing characteristics between fuel, combustion air and the bed material and thus a high momentum and heat transfer leading to a uniform temperature distribution.

Fluidized bed systems are typically built in medium size, from 30 to 350 MWₑₑ, for troublesome fuel ashes or fuels with a low volatile content and thus low combustibility (e.g. pet-coke or sewage sludge with a high moisture content). Typical fuels are waste wood, pet-coke, solid recovered fuels (SRF) in the form of pellets or sewage sludge [27–29]. The fuels’ high ash content and low ash melting temperature can be handled through a moderate and uniform temperature enabled by the good mixing behavior inside the bed material. The biggest concerns for operators are bed reactions and agglomeration. Bed agglomeration can lead to a decrease in heat transfer and fluidization. In extreme events it may lead to the total defluidization of the bed, resulting in unscheduled plant shut down [30]. Bed agglomeration is often caused by chemical reactions of inorganic vapors or molten phases of salts and/or silicates. These mechanisms and ash species can lead to coating, adhesion and sintering between sand particles [30,31]. Slagging is rarely reported for FB combustion, due to low temperatures and erosion by bed material, compared to grate firing or PF systems.

Grate combustion is typically used for low-grade fuels with troubling ash behavior. Commonly used fuels are municipal solid wastes (MSW), straw or wood including waste wood, forest residues or demolition wood. The fuel is burned without pretreatment on a moving grate, where combustion air is supplied from beneath. Modern systems use a staged air supply, where the combustion zone on the grate uses low stoichiometries in order to suppress nitric oxides.
Fig. 1. Combustion systems for solid fuels showing locations threatened by slagging and fouling. Typical process conditions, fuels, steam temperatures and efficiency values are given.
A substantial part of the inorganic material is transported out of the systems as solid ash particles and agglomerates via the grate. However, small ash particles and inorganic vapors can be entrained by combustion gases. They are liberated from the grate and transported through the flue gas duct of the boiler. The first duct is typically cladded in order to prevent the boiler wall from deposition of molten ash particles and excessive corrosion. Steam temperatures are often limited to values below 500 °C, due to high chlorine contents in the raw fuel, and, thus, the threat of high temperature chlorine-induced corrosion. Studies on straw grate firing have shown that fly ash is enriched in salt species consisting mainly of K, S and Cl, compared to bottom ash, which is silicate like and rich in K, Ca and Si. This fly ash can lead to severe operational problems such as slagging in the furnace or fouling at lower temperatures further downstream, e.g. on secondary or tertiary superheaters.

When comparing combustion systems, the power plant size, final steam temperature and the net electrical efficiency increase typically in the order: grate firing, FB and PF as illustrated in Fig. 1. The choice of combustion system is mainly depending on the fuel, its availability and inorganic constituents. Fig. 2 shows steam temperatures for different firing systems as a function of thermal input. The steam temperature is directly connected to the plant electrical efficiency. The highest steam temperatures are currently obtained for supercritical coal-fired power plants, where the latest built generation reaches values slightly above 600 °C and 285 bar. In addition, Fig. 2 shows current steam temperatures of biomass-fired combustion systems. It can be seen that medium to large-scale systems with a thermal input of 10–200 MWth have relatively low steam temperatures – up to 540 °C – compared to the latest design values of ultra supercritical coal-fired power stations, which exceed 700 °C at 330 bar. Currently, the highest steam temperatures in biomass combustion are found in a tangentially-fired PF system operated by DONG Energy. In 2000, DONG commissioned unit 2 at Avedore Denmark, a 563 MWth, supercritical coal-fired boiler with 600 °C steam temperature and an electrical efficiency of 46%. The unit was converted to high-quality wood pellets in 2004. The operator had to reduce the steam temperature to 540 °C in order to reduce the risk of ash deposition and corrosion. In 2006, they introduced coal fly ash injection to avoid the corrosive environment and to increase steam temperatures to 560 °C, which led to an electrical efficiency of 43.8%. The process was successful, however, mechanisms are still not understood. Coal fly ash is assumed to absorb potassium, which otherwise forms corrosive KCl-rich inner deposits on superheater tubes. This conversion shows the main problem of today’s power generation from solid biomass: deposition and corrosion caused by inorganic species. Even with high-quality wood pellets, steam temperatures are limited. This is even more troubling when using straw and other chlorine-rich biomasses. They are typically burned in systems with much lower steam temperatures, as shown in Fig. 2. Lower temperatures are mainly caused by the threat of severe ash deposit formation and high-temperature chlorine-induced corrosion. An interesting approach was presented for grate-firing systems in Masnedø and Maribo Søskæbing, where the superheater design was changed to so-called collecting superheaters. The new design enabled an increase in final steam temperatures from 450 to 540 °C by allowing the collection of ash deposits. Successful tests revealed a protective oxide layer formation as a shield against chlorine-induced corrosion.

Combustion systems also differ in process conditions, such as particle size, flue gas temperatures, or flue gas velocities, as listed beneath Fig. 1. With higher flue gas temperatures, ash particles are softer/contain a higher fraction of melt and thus their tendency to stick upon impaction on a surface increases. A higher flue gas velocity increases the particle kinetic energy, and thus the probability to impact on walls, such as the boiler wall or tubes. A detailed discussion on process conditions will be given in Section 4. Solid fuel combustion in a furnace involves a number of complex steps releasing chemically-bound energy as heat. Typically, there are four steps describing the process of solid fuel combustion: (1) drying and release of moisture, (2) devolatilization, i.e. thermal decomposition and release of volatile matter, (3) ignition and combustion of volatile matter, and (4) char combustion. Char combustion is known as the slowest step and the parameter determining the furnace height in PF combustion systems. Char combustion has to be
completed before particles can enter the superheating region. Otherwise, particle temperatures are too high due to the exothermic oxidation and ash is molten, thereby increasing the sticking propensity and the risk of corrosion. During the process of combustion, inorganic constituents transform physically and chemically and form the remaining ash, which is dominated by solid ash particles. However, inorganics can also be found as gaseous species, as liquid droplets or as solids, depending on the fuel and flue gas temperature. The following sections focus on observations made in experiments and their implication for numerical models. They include an overview on fuel inorganics, as well as fundamentals of ash and deposit formation.

2.2. Fuel inorganic constituents

A substantial part of solid fuels can be inorganic in nature and is difficult to remove from the organic substance. This ash forming matter varies strongly among different fuel types, and for coal it can range from as low as 2 wt.% in a clean feedstock up to 40 wt.% for low-grade lignite. Unfortunately, there is large confusion and misunderstanding of definitions for inorganic constituents in the literature. A commonly used classification for inorganic material in solid fuels is presented by Ward [37]; where similar definitions go back to the pioneering work of Benson and Holm [38] applied for a low-grade coal. Work in the field of biomass can be found in the publication of Zevenhoven et al. [6], Werkelin et al. [4,135], Marschner [39] or Vassilev et al. [5]. It has to be mentioned that definitions differ in literature, but mainly four groups of inorganic constituents are used for coals and biomass:

- **Dissolved salts** and other inorganic substances in the fuel moisture. In coals they can originate from contact with sea water, and are contained in the pore water. In biomass, such as wood or straw, dissolved salts originate from the liquid phases inside the plants. Elements are typically found as cations of K⁺, Na⁺, Ca²⁺ and anions Cl⁻, HPO₄²⁻, H₂PO₄⁻, SO₄²⁻ or Si(OH)₄⁻.

- **Organically-bound ash-forming compounds**: Inorganic elements that are incorporated in organic compounds (e.g. in the macerals of coals). Typically these are cations including K⁺, Na⁺, Ca²⁺, Mg²⁺, Fe³⁺, Al³⁺. A further group consists of covalently bonded non-metals such as organic S, P or Cl.

- **Included minerals** found as discrete inorganic particles within the fuel matrix, either crystalline or non-crystalline, representing mineral components. Within coals, these included mineral grains are often finely dispersed and intimately mixed with the organic substance and therefore difficult to remove. Within woody biomass, typical minerals are composed of Ca, Si, Mg; where Ca is frequently found in the form of calcium oxalate CaC₂O₄, which forms crystals during the drying of wood-based fuels. In the case of herbaceous fuels such as straw, soluble Si in the form of silicic acid Si(OH)₄ is transported within the cell walls and enriches in insoluble SiO₂ leading to the strengthening of the plant tissue.

- **Excluded minerals**, are liberated from the organic structure. For coals this can occur during the coalification process or during milling in the power station. Typical excluded mineral grains are quartz, pyrite or clay minerals. In the case of biomass, impurities originate from the soil or contaminants attached to the plant. Typical representatives are clay minerals in the form of alumino-silicates (rich in K, Na, Ca and Fe), feldspars or quartz.

Fig. 3 shows the most common forms: organically-bound inorganics, included and excluded mineral grains (not illustrated are dissolved salts). Ward [37] describes the first two groups (dissolved salts and organically-bound inorganics) as non-mineral inorganics. The amount of these inorganic constituents strongly depends on the fuel rank. An estimate on the amount of these elements can be found in Fig. 4 based on various literature references. The lowest quantity is typically observed for bituminous coals. Typical elements are alkali metals (Na, K), alkaline earth metals (Ca and Mg), P, S and Cl. High-rank coal inorganics have around 5–10 wt.% of these non-mineral inorganics, low-rank coals such as lignites or brown coals typically 10–40 wt.% of the total amount of inorganics [15,38]. In the case of biomass, this strongly depends on the plant type, where herbaceous biomass such as straw has around 15–58 wt.% (estimated...
from data of e.g. [40–42]), and wood-based feedstocks range from 12 up to 56 wt.% (estimated from data of e.g. [43–45,52]). An interesting biomass that produces low quantities of inorganic vapors is rice husk. Rice husks are extremely rich in silicon, as shown in Table 1. Inorganics in rice husks are non-leachable as shown by chemical fractionation studies [53]. Based on these results it is estimated that the amount of vaporizable elements is very low, probably below 5 wt.%. However, it has to be mentioned that the amount is difficult to determine and strongly dependent on the fuel, the temperature during conversion, the heating rate, the residence time at a certain temperature, and the measurement device. These inorganic components (Al, Ca, Cl, Fe, K, Mg, Na, Si, S, Ti and trace elements) can be covalently and ionically bound to the organic matter. The elements are present in ion-exchangeable forms and as salts of carboxylic acids within the organic matter [56]. Dissolved salts in coals can for instance originate from contact with sea water. In addition, plants have soluble salts in their liquid phases [6]. Both groups, dissolved salts and organically-bound elements are known to vaporize during the combustion, leading to inorganic vapors in the gas phase. These vapors can re-condense to small particles, referred to as aerosols or sub-micron ash particles. A method that might be suitable in order to estimate the amount of vaporizable inorganics is chemical fractionation, often referred to as leaching. During this method, the fuel samples are dissolved in various solvents and the remaining residue and eluate are analyzed [38]. There are several methods and procedures described in literature [61]. Typical solvents are deionized water, ammonium acetate and hydrochloric acid. Elements that are leachable in the first two are assumed to be vaporizable. Chemical fractionation of coals was for instance done in projects Sodium [54] and Calcium [55] at the Energy & Environmental Research Center (EERC) in early 1990s; see also Benson and Holm [38]. Chemical fractionation results of commonly used biomass can be found in the work of Zevenhoven et al. [6].

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Discrete inorganic particles are often referred to as mineral matter in the fuel [56]. They are present as mineral grains within the organic matter or separated from it. Most minerals are in crystalline form of e.g. [40–42], and wood-based feedstocks range from 12 up to 56 wt.% (estimated from data of e.g. [43–45,52]). An interesting biomass that produces low quantities of inorganic vapors is rice husk. Rice husks are extremely rich in silicon, as shown in Table 1. Inorganics in rice husks are non-leachable as shown by chemical fractionation studies [53]. Based on these results it is estimated that the amount of vaporizable elements is very low, probably below 5 wt.%. However, it has to be mentioned that the amount is difficult to determine and strongly dependent on the fuel, the temperature during conversion, the heating rate, the residence time at a certain temperature, and the measurement device. These inorganic components (Al, Ca, Cl, Fe, K, Mg, Na, Si, S, Ti and trace elements) can be covalently and ionically bound to the organic matter. The elements are present in ion-exchangeable forms and as salts of carboxylic acids within the organic matter [56]. Dissolved salts in coals can for instance originate from contact with sea water. In addition, plants have soluble salts in their liquid phases [6]. Both groups, dissolved salts and organically-bound elements are known to vaporize during the combustion, leading to inorganic vapors in the gas phase. These vapors can re-condense to small particles, referred to as aerosols or sub-micron ash particles. A method that might be suitable in order to estimate the amount of vaporizable inorganics is chemical fractionation, often referred to as leaching. During this method, the fuel samples are dissolved in various solvents and the remaining residue and eluate are analyzed [38]. There are several methods and procedures described in literature [61]. Typical solvents are deionized water, ammonium acetate and hydrochloric acid. Elements that are leachable in the first two are assumed to be vaporizable. Chemical fractionation of coals was for instance done in projects Sodium [54] and Calcium [55] at the Energy & Environmental Research Center (EERC) in early 1990s; see also Benson and Holm [38]. Chemical fractionation results of commonly used biomass can be found in the work of Zevenhoven et al. [6].
form, however some can exist as amorphous phases. Both transform during the combustion and the remaining residue is referred to as ash. Strictly, ash is the remaining solid residue after complete conversion [15]. However, literature is not consistent and an incorrect use of the terms ash, inorganic constituents and mineral matter is common. The amount, chemical composition and size distribution of ash is highly-dependent on the fuel and the form of inorganic constituents as well as the combustion system (temperatures, atmospheres) and fuel preparation (e.g. grinding, washing). Laboratory ash has a considerably different temperature- and time-history compared to ash samples collected in power plants. Furthermore, the atmosphere (i.e. oxidizing or reducing) will influence ash characteristics. Unfortunately, there is inaccuracy in the literature, and preparation or sampling techniques are often not stated clearly. Particular care must be taken for obtaining representative samples. This is less important in laboratory-scale, but can be of great importance in a PF boiler, as the amount analyzed is extremely small compared to mass flow rates in a full-scale furnace [15]. Furthermore, information on the feedstock and its origin (e.g. coal mine and storage) is missing in most studies. By knowing the amount of remaining ash, empirical correlations can be used to estimate the mineral matter content in the raw fuel. There are empirical equations in literature, which relate the mass fraction of mineral matter \( w_m \) to the proximate ash yield \( w_A \) and the total sulfur content \( w_{S,\text{total}} \), such as the one suggested by Parr [58] given by:

\[
\text{Equations relating ash yield to mineral matter exhibit high uncertainties. These equations are often derived for high-temperature ashing and therefore, a significant amount of inorganic matter is already released to the gas phase. Generally speaking, inorganic matter transforms, decomposes and releases gaseous components during conversion. Typical components are } H_2O, CO_2, Cl_2, HCl, SO_2 \text{ and } H_2S \text{ depending on conditions and stoichiometry [59,60]. Therefore, in most correlations, the mineral matter content in the raw fuel is around } 10\% \text{ higher than the final ash content. The sulfur content, } w_{S,\text{total}}, \text{ contributes to some extent to the ash yield depending on its occurrence. Sulfur can be either present in the form of organic sulfur bound to the coal structure, as sulphotides originating from } \text{pyrite, sulphotides, e.g. } CaS_2O_4 \text{, or as elemental sulfur [35]. Detailed information and discussion of mineral transformations and decompositions are provided in the following sections. Vassilev and Tascón [56] come to another order. They argue that coal ash is the inorganic residue resulting from incineration of coal and that it is composed of original and new-formed inorganic phases generated from both inorganic and organic matter [56]. They state that the magnitude should be in the order of } ash > inorganic matter > mineral matter; where the mineral matter is a part of the inorganic matter and organically-bound inorganic compounds are not included in the inorganic matter according to their definition [56]. However, lower values of ash than mineral matter are commonly observed when ash is produced at high temperatures and inorganic constituents volatilize [56] and minerals decompose. Furthermore, it has to be mentioned that measuring the amount of inorganic matter and mineral matter is highly difficult and an accurate and reliable method is currently not available. Different forms of inorganic compounds, various mineral types and the heterogeneity of solid fuels are the main reasons for the inconsistency and confusion in literature.

A compilation of different fuel types and their ash characteristics is presented in Table 2. Six major groups - comprising of bituminous coal, lignite, herbaceous biomass such as straw or grasses, woody biomass, manures and sludges as well as waste-based fuels - are summarized in terms of typical heating value, ash content, ash fusion (fluid) temperature and major ash forming elements. By far the highest ash content is observed for waste-based fuels and manures such as sewage sludge with values up to 50 wt.% on a dry basis (d.b.). There are some reports of linitges with very high ash contents, however typical coals have lower values between 10 and 20 wt.% (d.b.). Bituminous coals are dominated by Si, Al and Fe, which mainly originate from mineral grains composed of aluminosilicates, quartz or pyrite depending on the coal seam. The bulk ash fusion temperatures are fairly high, usually at around 1200 up to 1500°C. However, there can be single particles with low melting eutectics with considerably lower melting temperatures in particular for iron bearing mineral grains. Lignites can vary widely and are often dominated by Ca, Mg, Fe, S and Si. Frequently found minerals are carbonates, gypsum, quartz and many others. Melting temperatures are typically slightly lower, compared with bituminous coals. Very low melting temperatures down to 950°C are observed for straw and grasses, mainly due to the high potassium content. Si, Al, K species - found within the plant - can form low melting ash particles. This together with high chloride contents leave straw to be a troublesome fuel. On the contrary, wood-based fuels are often reported to be less problematic. The have relativity high melting temperatures, mainly due to the abundance of calcium. The majority of ash forming elements is found within the bark - with ash contents of 5-8 wt.% (d.b.). Very difficult and heterogeneous fuels are manures and waste-based fuels, such as MSW or SRF, demolition wood and other residues. Manures are often rich in phosphorus and heavy metals, leading to problems concerning the ash utilization. A further summary of major ash forming species and their quantity within different solid fuels is presented in Table 1. Different groups comprise of bituminous coals, lignites and different biomass including Nordic wood, herbaceous biomass and agricultural residues. Woody biomass is differentiated into bulk wood, bark, twigs, needles and leaves. The table reveals that woody biomass is dominated by Ca and K making up for around 65 mol.% followed by Mg and S. Twigs, needles and leaves have an increased content of K and P compared with bark and stem wood. Furthermore, it is shown that bark, twigs, shoots, needles and leaves have a strongly increased content of inorganic matter, up to ten times higher, compared with stem wood. The amount of inorganics found in annual biomass is similar to bark in the range of 3–10 wt.% of the fuel. Inorganic species in
annual biomass, such as straw or grasses, are dominated by Si, K and a fairly high Cl content.

Fig. 5 shows a back-scattered electron (BSE) microscope image of unprocessed wood (a) and straw (b). In BSE images, the intensity of the signal and thus the intensity of gray in the image is strongly related to the mean atomic number of elements in the sample. Therefore, minerals with high atomic numbers appear brighter, compared to the organic structure or the embedding material with lower atomic numbers. Wood, shown in Fig. 5(a), is in general a very clean feedstock with a low amount of excluded mineral grains or contaminants such as soil, sand or clay minerals. Most of the inorganic species are found embedded within the organic, regular wood matrix. They are typically 1-10 \( \mu \text{m} \) large grains composed of crystalline calcium oxalate or carbonates. Particles can contain Ca, Mg or Na as either silicates, or sulfates up to 40 \( \mu \text{m} \) \cite{66}. The ash content of straw is increased compared to wood. A typical straw stem is shown in Fig. 5(b). The Energy research Centre of the Netherlands (ECN) estimated that around 75% of the Si is found in quartz particles, which are either embedded in the organic straw matrix up to 25 \( \mu \text{m} \) or form thin continuous linings at the outside of the straw stem \cite{66}. In addition, some clay minerals containing Mg and/or Ca were found during the scanning electron microscopy (SEM) and SEM/EDX (energy dispersive X-ray spectroscopy) analyses.

A very powerful characterization method for inorganic constituents and their variation within one sample is the so-called “computer-controlled scanning electron microscopy” (CCSEM) analysis. This method allows to analyze the raw fuel sample directly without any thermal pretreatment such as ashing in a muffle furnace. The fuel is mount in epoxy, cut and the cross-section is polished. Conventional SEM or CCSEM are often applied for the identification (type, form and size) and quantification of minerals in coals. Fig. 6 shows a BSE microscope image of bituminous coal particles. It can be seen that a substantial fraction of the mineral matter is excluded from the fuel matrix. Additionally, the amount and number of mineral inclusions vary widely among different coal particles. Therefore, scanning electron microscopy is a key method for developing a detailed fuel model for numerical codes.

The CCSEM technique was developed during the late 1970’s and early 80’s when computer supported electron microscopy became available. The first studies using computer-controlled SEM techniques focused on classifying the mineral size distribution and composition within pulverized coals \cite{67}. Steadman et al. \cite{269} and Zygarlicke et al. \cite{68} were among the first to differentiate between included and excluded minerals. During CCSEM, coal particles are mounted in an embedding material which is polished, carbon coated and placed in an electron microscope. In order to distinguish between included and excluded minerals, a distinct contrast between the embedding material and coal matrix is needed. Two possible methods can be found in the literature. The best contrast on the BSE pictures is derived using carnauba wax. Another method is to increase the average atomic number by dissolving ten percent iodoform in epoxy resin \cite{69}. This resin is then mixed with coal particles and hardener. Once the sample is polished and carbon-coated, the cross-section can be investigated using SEM. CCSEM can be applied for coal, char and ash particle characterization. Typical results provide information on the mineral composition, its size and type (excluded or included). Eleven elements are detected most commonly including Al, Ca, Cl, Fe, K, Mg, Na, P, Si, S and Ti. The sample is scanned automatically by computer and X-ray detectors are used to quantify elements of individual mineral grains. The composition of a mineral grain is then compared with a database of mineral compositions and subsequently classified. It has to be mentioned that a classification leads to a loss in information. For instance, a mineral grain with a composition close to quartz is classified as pure quartz (SiO\(_2\)). Typical minerals in the system include quartz,
kaolinite, pyrite, rutile, montmorillonite, apatite, gypsum, various silicates, and many others [3].

CCSEM analysis can provide very useful details and insight in the heterogeneity of a solid fuel, as shown in Fig. 7. Monroe [23] detected around 6000 mineral grains for a Kentucky No. 9 coal. It is shown that mineral grain composition varies widely within one fuel sample and therefore, each mineral grain has its own transformation and melting point. Where classic ash oxide analysis yields just one average point, CCSEM illustrates a number of points with varying composition. CCSEM is able to provide information on the variation in chemical composition, form and size of minerals. However, this method has to be applied with care. There are some limitations and disadvantages when using CCSEM techniques. Ignoring these limitations can lead to different results and wrong conclusions. For instance, particles in the sub-micrometer range cannot be detected without using very high magnifications, which is impracticable. A sufficiently high number of particles have to be analyzed in order to obtain statistically meaningful and quantitative results. Typical results are in the range of 2000–4000 particles. This is of special interest when a broad particle size distribution (PSD) has to be characterized. Furthermore, using different magnifications can lead to different results and more importantly, Sarofim and Helble [70] discuss that particle sizes in a cross-section are artificially shifted towards smaller diameters (due to the effect that the probability to intersect a sphere at its pole is low). Another problem is associated with the electron beam size. The size of the beam restricts the lower limit of mineral inclusions to about 1 μm, depending on the magnification. Often, small clusters of two or more different mineral grains close to each other and with different chemistry cannot be distinguished, and results show a misleading composition. Furthermore, they are classified as one instead of multiple grains. The penetration depth of the beam is also a parameter affecting the lower detection limit. Furthermore, atomically-dispersed elements, i.e. organically-bound inorganics, cannot be identified or quantified.

Although information on mineral-mineral (two different mineral grains in a cluster close to each other) or mineral-maceral association can be determined, commercially available CCSEM analyses do not provide such data. It is often difficult to differentiate between coal particles and resin; hence an automatic procedure is not applicable. There are only a few studies on the mineral-organic association using CCSEM [72–75]. An interesting approach is the QEMSCAN system, developed at CSIRO [76,77]. QEMSCAN describes a method that directly enables the measurement of mineral matter - organic matter association on a particle-by-particle basis. The difference compared to CCSEM analysis is that coal particles are included in the analysis and the whole cross-section is analyzed pixel by pixel. Mounting medium and coal particles are distinguished by the brightness of the BSE picture, and the X-ray spectrum. Around 4000 particles are required for statistically significant results [78].

Studies on the distribution of inorganic constituents in solid fuels are rare in literature. Typically, CCSEM analyses are carried out providing information on the amount and type of included and excluded minerals. However, CCSEM analyses are not covering organically-bound inorganics and do not give information on the association of the coal matrix with mineral grains. A study of Liu et al. [78] uses the QEMSCAN technique to determine the mineral-maceral association for 14 different Australian coals. The most abundant particle type found by Liu et al. [78] were particles without mineral grains. Only, about 10% of the particles' cross-sections contained mineral inclusions. They defined three particle classes, based on these findings. Class 1: coal particles with 95% or more area covered with organic substance, class 2: particles with included minerals containing 40–90% organic substance, and class 3: excluded mineral grains, containing less than 40% organic substance. According to this classification, the majority of the studied coal samples had an included mineral matter content in the area of 50–80%. There was just one sample with more excluded than included minerals [78]. In a later study, Liu and co-workers [79] investigated the mineral-

![Fig. 7. Mineral particle composition distribution for 38–45 μm fraction of a raw Kentucky #9 coal. Each symbol represents the composition of one individual mineral grain measured using CCSEM (figure taken from Monroe [23]).](image-url)
mineral association of excluded mineral grains. They studied three different coals and the corresponding ashes after combustion in a drop-tube furnace at 1400 °C, and came to the conclusion that illite, ankerite and siderite change their shape to spherical particles, while quartz, kaolinite and calcite do not show significant changes. They found mineral associations of quartz and kaolinite in excluded mineral grains, whereas combined particles of carbonates with silicates were rare [79].

Mineral matter is often reported to be enriched in smaller particle sizes. This trend has been observed in several studies [12,80–84] and can be explained by the fuel grinding process. Unsworth et al. [82] state that particles with high mineral matter content and thus high particle densities tend to be ground to a finer size and may liberate mineral grains. This is based on the effect of a classifier mill, which recycles heavier particles. Only if the particle inertia is low enough, the gas flow can entrain the particle. In particular higher-rank coals tend to demonstrate this behavior [15].

Data on the number of mineral grains per particle and their distribution among coal particle sizes are rare. Barta et al. [72,86] developed the so-called “urn” model using CCSEM data. They used a Poisson law in order to distribute mineral grains among individual coal particles. SEM investigations of a size-graded Texas lignite (63–75 μm) revealed a mean value of 15 mineral inclusions per coal particle. Particles were embedded in epoxy resin, cut and polished for measurements using a back-scattered electron detector. An inverse Abelian transformation is applied, in order to obtain volume-based size distributions. The Poisson distribution law is used to describe the number of mineral inclusions per coal particle. For n mineral inclusions in m coal particles the probability Pj of finding j mineral particles in a coal particle is calculated by the following equation [72]:

\[
P_j = \lambda^j \frac{e^{-\lambda}}{j!},
\]

where \( \lambda = n/m \), the mean number of mineral grains per coal particle and j is the number of mineral grains per coal particle, which can take an integer value of 0 to n [70,72]. Eq. (2) is less accurate for coals with a high content of included mineral matter. The number of mineral inclusions \( n \) per coal particle of a given size \( d_{50,c} \) can be estimated by [86]:

\[
n = \frac{d_{50,c}^3 \rho_c}{M_{3,m} \rho_m \cdot w_m},
\]

where \( \rho_c \) and \( \rho_m \) are the density of the coal substance and of the mineral inclusion, \( M_{3,m} \) is the third moment of the mineral size distribution, and \( w_m \) is the mass fraction of the mineral inclusion. Experimental work on the number of mineral inclusions per coal particle is rarely found in literature. A similar approach was followed by Monroe [23], who used SEM to measure the mineral size of Kentucky #9 coal, with a varying degree of cleaning. Monroe used a Monte Carlo method to distribute mineral matter among individual coal particles. Although there are some studies evaluating mineral size and distribution, general rules are not identified, and each fuel needs to be investigated separately. This is of particular concern for biomass with low mineral matter content. Often, power plant operators use more simplified and cheaper methods in order to determine the slagging and fouling potential of fuels. One of the first tests for new purchased fuels is the popular ash fusion test.

This laboratory test is applied to study the ash melting behavior under controlled conditions. Ash samples, typically produced in a muffle furnace, are pressed to a specimen, heated up under a controlled atmosphere and observed with an optical system. The silhouette recorded from the sample is judged to identify critical temperatures. There are several standards available in literature for ash sample preparation and ash fusion tests. According to Couch [15], the available standards differ quite significantly in terms of specimen preparation and characteristic temperatures. Specimen and silhouettes of characteristic temperatures are illustrated for the American standard in Fig. 8. These characteristic temperatures are referred to, as initial deformation temperature (IDT), softening (ST), hemispherical (HT) and fluid temperature (FT), respectively. Ash fusion temperatures are often used by boiler designers for selecting the maximum furnace exit temperature and for the estimation of slagging propensities using indices and the bulk ash chemistry. The ash fusion test for biomass uses different characteristic temperatures. Ash samples derived from biomass show a shrinking specimen and therefore the IDT is replaced by the so-called shrinkage starting temperature (SST). The second characteristic temperature is called deformation temperature (DT), whereas the rest is identical. Generally speaking, the applicability of the ash fusion test is questionable. Couch [15] states that laboratory ash is considerably different due to the slow formation process compared to conditions in a boiler. Laboratory ash absorbs \( \text{SO}_3 \) from sulphates and oxygen from ferric oxides which does not occur in a boiler. Furthermore, heterogeneity strongly influences ash melting temperatures. For example, quartz grains distributed within the specimen lead to a strong compound structure and ash fusion temperatures are often quite high, even though most of the other ash particles are already molten. Van Dyk et al. [88] reported that low viscosity ashes can have a high molten fraction without changing the geometry of the specimen. Another important parameter is the atmosphere under which the test is carried out. The atmosphere can be selected either as oxidizing or reducing. It is reported in literature that reducing conditions lead to lower ash fusion temperatures, typically around 50 K. A dominant role exhibit iron minerals and their transformation under reducing conditions [15]. Bryers [89] correlates the ash softening temperature under reducing conditions for eight eastern US coals to the sum of basic compounds in the ash. A parabolic curve can be found with the minimum temperature at approximately 50 wt.% of basic compounds. Therefore, the amount of basic compounds in the fuel can help to estimate the threat of slagging and fouling. However, detailed information on individual particles, which might melt at much lower temperatures (50–250 K), can only be obtained by SEM methods. Furthermore, detailed predictions on ash formation, in terms of ash particle size distribution and chemistry, can only be conducted if SEM data is available.

2.3. Ash formation

Ash formation in solid fuel combustion systems involves several mechanisms and processes, producing gases, liquids - in the form of melts - and solids. There are three main aspects: the first, and probably most important one, being the distribution of inorganic constituents in the fuel matrix, which has been discussed in the previous section. Secondly, inorganic constituents undergo physical transformation including melting, fusion, vaporization, fragmentation, etc. And thirdly, inorganic constituents decompose and transform to ash,
which is dependent on process parameters such as flue gas temperature and composition. This process is often referred to as chemical or mineral transformation. The following sections address each of the two latter aspects, and summarize the current state of the art.

### 2.3.1. Physical transformations of inorganic constituents

Inorganic constituents in solid fuels undergo physical transformation processes, which are strongly dependent on the conditions inside the boiler, and on the fuel itself [14]. Possible physical transformations of inorganic constituents are:

- coalescence of mineral inclusions within the particle or on the particle surface [9,12,70,86,91,96,104],
- shedding of mineral or ash particles from char surfaces [91–93,165],
- coal/char particle fragmentation and incomplete coalescence of minerals [93–96,104,114,115,118,122],
- fragmentation of excluded minerals due to mineral transformations [12,79,183,540],
- formation of inorganic cenosphere- or plerosphere [57,97],
- vaporization of mineral species, their re-condensation and agglomeration [12,73,91–93], and
- vaporization of salts and release of organically-bound inorganics [43–45], their chemical reaction with ash particles [48–51,261,262], and their condensation [98–103,212].

Fig. 9 illustrates the process of ash formation. It occurs along with devolatilization, char conversion and subsequent flue gas cooling. Depending on the fuel, a considerable amount of inorganic constituents may vaporize. Mainly, organically-associated inorganic compounds are released as inorganic vapors, during devolatilization and char conversion. These inorganic vapors are illustrated by open arrows, whereas solid particles are shown with filled arrows, in Fig. 9. Remaining inorganic constituents, mainly mineral matter, decompose, transform to ash, melt and coalesce (fuse together) depending on the mineral type and temperatures. The behavior of included minerals is complex. Most ash particles have a sufficiently high surface tension to form liquid droplets and thus, do not wet the char particle surface [57]. Included mineral grains are often reported to coalesce during char conversion. During coalescence, mineral inclusions come into contact with each other and fuse to one remaining ash particle. Coalescence of mineral inclusions has been investigated by several authors. Sarofim and Helble [70] suggest the full coalescence model as a good starting point for estimating the ash particle size distribution. In this model, every coal particle yields exactly one ash particle. The full coalescence model yields the largest possible particle size distribution (assuming no particle-particle collisions in the bulk flow). The opposite behavior and lower boundary for the ash PSD, is the so-called no coalescence model, where every mineral grain yields one ash particle. Eq. (4) can be used to estimate the ash particle diameter \(d_{p,a}\) for a given coal particle diameter \(d_{p,c}\) [70]:

\[
d_{p,a} = d_{p,c} \cdot \sqrt{\frac{w_a \cdot \rho_{p,c}}{n \cdot \rho_{p,a}}}
\]

where \(w_a\) is the ash mass fraction of the coal particle, \(n\) is the number of resulting ash particles from the coal particle with size \(d_{p,c}\), and \(\rho_{p,c}/\rho_{p,a}\) is the ratio of the densities of the coal and the ash particle. In this equation, the mineral matter content equals the ash content. Sarofim and Helble [70] refer to a publication of Wall et al. [71], noting that Eq. (4) is less accurate for coals with high shares of included mineral matter content (e.g. \(w_a > 20\) wt.%). For such coals, the volume occupied by the ash has to be considered. Wiemerski and Srinivasachar [104] successfully used a Monte Carlo method for the mineral distribution in combination with the full coalescence model for the prediction of ash size distribution. However, the same model failed for a highly cleaned coal, which showed excessive fragmentation behavior. Barta et al. [86] developed the random coalescence model in combination with a char combustion model, providing limits for the coalescence of mineral inclusion. The model is based on input from CSEM analyses. This model uses a simple char burnout formulation with two subsequent steps. In the beginning, char conversion is assumed to occur in the diffusion-limited regime with a shrinking particle diameter. Mineral inclusions are released step by step and assumed to adhere to the surface as molten particles. If ash particles get in contact due to a shrinking char structure, they start to coalesce. In the next step, the combustion is assumed to be in the kinetically-limited regime. Particles now burn from the inside and the diameter is unchanged. By this approach, coalescence is interrupted, and char particles break up once they reach a critical porosity. A further development was presented by Yan et al. [9] for high-rank coals using CSEM data. Included and excluded minerals were treated differently. Included minerals were distributed randomly among coal particles using Poisson distribution. The authors found that small particles do not fuse together. Best agreement is reported when using a partial coalescence model as shown in Fig. 10. An interesting ash formation model for CFD codes is presented in a
study of Zhou et al. [454]. The model accounts for ash layer collapse during char burnout and assumes coalescence. Such a model should be extended for char fragmentation and should be validated with measurements. In this case char fragmentation becomes important. Char fragmentation was first mentioned 80 years ago by Davis and Hottel [107] and is often given as an explanation for differences in predictions and observations of particle size distributions or fly ash formation. Fragmentation can occur during devolatilization, during char combustion, or for excluded mineral grains, in particular minerals, which undergo thermal decomposition. The majority of literature references reporting fragmentation observed char fragmentation. It is reported for different fuel ranks, however, mostly for swelling coals. Char fragmentation influences ash formation, as shown in Figs. 11 and 12, and therefore also the remaining particle size distribution as well as char conversion rates. The onset and extent of char fragmentation can be predicted using percolation models [109,116,477,478]. When the particle reaches a critical porosity, typically around 0.8, but values scatter in-between 0.2 up to 0.96 [113,125], it is assumed to fragment, where the number of fragments is dependent on the particle size, char structure and many other parameters [96]. Furthermore, the initial char structure is known to affect the ash formation. Wilemski and Srinivasachar proposed a fragmentation model for cenospherical particles, where particles break up into a certain number of fragments as shown by Fig. 11. Mineral grains in these fragments fuse together and form the remaining ash. A similar model considering different char particle shapes was presented by Wu and co-authors [105]. Fig. 12 shows the ash formation mechanism postulated for different char types and included minerals. Typically, three different char types are reported in literature [163,164]: type I chars are spherical to sub-spherical particles with thin walls (< 5 μm) and high porosity values, so-called cenospheres. Type II particles show a sub-spherical shape with medium porosity, almost no swelling and variable wall thicknesses. And type III chars, which are relatively dense, have an angular shape and a swelling coefficient smaller than unity. Wu et al. [105] used a size-graded and density-fractionated Australian bituminous coal and studied their conversion in a drop-tube furnace at 1300 °C, atmospheric pressure and air. The coal sample was in a narrow size range of 63–90 μm and excluded minerals were removed by sink/float separation with an upper specific gravity of 2.0 g/cm³ [105]. Combustion took place in the diffusion-limited regime. Depending on the char type, a different degree of coalescence is assumed. Char type III forms one remaining ash particle, whereas for char type I every mineral inclusion forms an individual ash particle. Thus, information on char structure is necessary according to the authors. They further argued that different char types have different observed reactivities. Char type I is assumed to fragment and burn four times faster than the dense and less porous char type III. This might also be due to different specific surface areas of varying char types. Char fragmentation of type I seems to determine ash formation during early stages of combustion, while the formation of coarse fly ash particles occurs by coalescence of included mineral matter during late stages of combustion [105]. Syred et al. [121] give an overview on mechanisms leading to particle fragmentation. Reasons can be:

- thermal stresses [126–130],
- pressure-induced fracture during devolatilization [94,133].
Table 3
Overview of reported particle fragmentation of solid fuels in chronological order and separated for coal and biomass (with acronyms for fragmentation mechanism: TS - thermal stress, PI - pressure induced fragmentation, AR - attrition and PM - percolative mechanism).

<table>
<thead>
<tr>
<th>References</th>
<th>Fuel rank</th>
<th>Particle size</th>
<th>Mechanisms</th>
<th>Number of fragments</th>
</tr>
</thead>
<tbody>
<tr>
<td>Helleb &amp; Sarofim 1989 [168]</td>
<td>sub-bit. coal</td>
<td>75–90 μm</td>
<td>PM</td>
<td>↑ when dp &gt; po</td>
</tr>
<tr>
<td></td>
<td>lignite</td>
<td>75–90 μm</td>
<td>PM</td>
<td>↑ when dp &gt; po</td>
</tr>
<tr>
<td>Baxter 1992 [110]</td>
<td>bit. coal</td>
<td>1–100 μm</td>
<td>PM</td>
<td>1–100 for large dp</td>
</tr>
<tr>
<td></td>
<td>lignite</td>
<td>1–100 μm</td>
<td>–</td>
<td>1–2</td>
</tr>
<tr>
<td>Dacombe et al. 1994 [112]</td>
<td>anthr.</td>
<td>1–5 mm</td>
<td>TS</td>
<td>50–100</td>
</tr>
<tr>
<td>Mitchell &amp; Akanetak 1996 [94]</td>
<td>synth. char</td>
<td>90–106 μm</td>
<td>PM</td>
<td>&gt; 100</td>
</tr>
<tr>
<td>Zhang et al. 1996 [111]</td>
<td>spherocarb</td>
<td>205 μm</td>
<td>PM</td>
<td>2</td>
</tr>
<tr>
<td>Dacombe et al. 1999 [128]</td>
<td>bit. coal</td>
<td>1–4 mm</td>
<td>TS</td>
<td>10–100</td>
</tr>
<tr>
<td>Liu et al. 2000 [169]</td>
<td>bit. coal</td>
<td>63–90 μm</td>
<td>PM</td>
<td>large for type I char</td>
</tr>
<tr>
<td>Feng &amp; Bhatia 2000 [113]</td>
<td>diff. chars</td>
<td>varying size bins</td>
<td>PM</td>
<td>&gt; 20</td>
</tr>
</tbody>
</table>
| Scala et al. 2006 [125],a | wood chips | 3.35–9 mm | AR, PM | 2.5–4.5
| | pine shells | 5–20 mm | AR, PM | 1.6
| | olive husk | 3.35–5 mm | AR, PM | 1.04
| Sreekanth et al. 2008 [134],a | tropical hard wood | 10–30 mm | pri. frag. | |
| Sudhakar et al. 2008 [124],a | tropical hard wood | 10–25 mm | pri. frag. | up to 12 |
| Costa and Costa 2015 [122,123]b | olive stones | 300 μm |
| | pine shells | 500 μm |
| | straw | – |
| Lin et al. 2015 [120],a | wood pellets | – | AR, PM | – |

*a fluidized bed combustion conditions.
*b in a drop tube furnace.
*c dₚ > 500
*d primary fragmentation multiplication factor.

- collision-induced attrition of small particles from the surface [131,132], and
- percolative mechanism in which oxidation (i.e. conversion) progressively erodes the solid network [108–111,131,168,169]

Fragmentation is often divided into primary and secondary fragmentation. Primary fragmentation refers to fragmentation induced by mechanical stresses (thermal or pressure), mostly during devolatilization, whereas secondary fragmentation is related to char conversion induced by coalescence of large pores at late stages of burnout (percolation) [112]. Experiments on fragmentation cover a broad range of fuels and carbons with different process parameters such as temperature, oxygen partial pressure and particle size. Table 3 summarizes experimental investigations on fragmentation, listing the fuel, particle size and the observed mechanism of fragmentation. Evaluation of this data indicates the predominant role of a percolative nature of char fragmentation.

Char fragmentation during coal combustion strongly depends on the particle size. Large particles are often reported to fragment due to thermal stresses as shown in Table 3 and the work Senneca et al. [114,133] or Dacombe et al. [112,128]. Small particles, typical for PF combustion, on the other hand fragment due to percolative mechanisms. The oxidation proceeds and erodes organic substance by releasing ash particles sitting on the char surface. A similar mechanism is expected to occur for biomass char. However, experimental data on biomass fragmentation is rare and only recently studies appeared. Fig. 13 shows spruce wood particles after pyrolysis. Cotton-like agglomerations of small ash particles and Ca-rich crystals are sitting on the char surface. It is assumed that these particles are liberated during burnout. However, direct experimental evidence is missing. Most of the studies on biomass presented in Table 3 were under fluidized bed combustion conditions with relatively large wood pellets or wood chips. In these cases, interaction between bed material and fuel particles occurs. The majority of these studies reported primary fragmentation during devolatilization together with attrition of ash particles from surfaces, probably caused by interactions between bed material and fuel. Percolative fragmentation during char conversion is also reported for biomass [120,125], probably due to the fact that biomass chars have higher porosity values compared with coal [119].

Fragmentation and its extent is difficult to determine in experiments, in particular for small particle sizes. Thermal stresses during heating or the oxidation of thin particle structures will lead to fragmentation. One can imagine that particle sampling and collision with tubes and boiler walls might also lead to fragmentation events, which is not discussed in literature. There are many uncertainties and sources of errors leading to a highly discussed field of research.

The conclusions drawn from Table 3 are:

- char fragmentation is mainly percolative in nature and more pronounced for large particles,
- char fragmentation depends on the char type, and thus the maceral composition in the case of coal,
- the number of fragments increases with particle size, but varies widely among literature,
- cenospherical particles (type I chars) are the main source of fragments,
- char fragmentation most likely increases burning rates and the amount of fine fly ash,
- macro-porosity determines the extent of fragmentation with critical porosity values reported mostly in between 0.7 and 0.95,
- fragmentation can occur during devolatilization, mainly for biomass and large particles, and is induced by thermal stresses and internal pressure due to volatile release.

Shedding is illustrated in Fig. 14. During shedding, ash particles sitting on the char particle surface experience forces, mainly shear forces. These forces can detach the ash particle from the char structure and liberate it to the flow. Forces can be caused by particle rotation or slip flow between the particle and gas. Particle rotation is reported during devolatilization, where volatile jets evolve from
pores and openings. Studies on shedding are rare. Often shedding is referred to as a fragmentation event, leading to small particles in the range of 0.5–5 μm [165–167]. Helble [165] studied shedding using two color pyrometry and found values as high as 1000 revolutions per second for a 100 μm particle at the onset of char combustion. Theoretical considerations including rotational and surface tension forces showed that this effect is of minor importance for small, molten mineral grains sitting on the char surface. Nevertheless shedding might be a source of small particles in large-scale boilers with highly turbulent flow fields, when mineral grains are not properly attached to the char surface; e.g. if they are solidified. This effect should be studied in large-scale test rigs with considerably higher gas velocities (3–15 m/s compared to 0.2–2 m/s in lab-scale test rigs). Often it is difficult to differentiate between shedding and fragmentation due to the erosion of organic substance, called percolative fragmentation [168,169].

The behavior of excluded minerals depends on the mineral type. Quartz can be transported through the combustion system without any changes and maintain its sharp, angular structure [57]. Other excluded minerals such as clays can fragment during dehydration, melt and form cenospheres or plerospheres, i.e. cenospheres filled with small particles. The same can occur for carbonates. Pyrite is reported to fragment more easily due to its framboidal structure [57]. Both, coalescence and fragmentation have a significant effect on the ash size distribution. The remaining ash particles formed by coalescence and/or fragmentation are referred to as fly ash or coarse fly ash and are in the range of 1–50 μm for conventional PF combustion systems. During ash formation, particles are transported through the boiler with decreasing gas temperatures. Due to this temperature decrease, inorganic vapors start to condense. The condensation can be divided into homogeneous and heterogeneous condensation. The type of condensation is dependent on the supersaturation ratio $S_i$ of the condensing species $i$. The supersaturation is calculated by the ratio of the partial pressure of species $i$, $p_i$, and its saturation pressure $p_{sat,i}$ at a certain location and temperature ($S_i = p_i / p_{sat,i}$ – see Section 2.5.3). Homogeneous condensation and the nucleation of sub-micron particles takes place at supersaturation ratios of approximately $S_i > 5$ (numbers in literature range from 1 to 10 [170–174]), whereas heterogeneous condensation is possible at values above unity. Heterogeneous condensation can occur on other particles (char or ash) or on heat exchanging surfaces. This layer can be liquid and sticky or porous depending on the temperature. Both homogeneous and heterogeneous condensation lead to the formation of sub-micron particles, and sub-micron modes depending on where nucleation of vaporized metals occurs. At high concentrations of these fine particulates, coagulation effects due to particle-particle
interactions can become important leading to agglomeration. This is of great importance for biomass combustion with high shares of inorganic vapors; see the work of Friedlander [171], Jöller [176], Brunner [101] or Balan [175]. For a detailed experimental and theoretical investigation of fine particulate matter formation during pulverized coal combustion, it is also referred to the work of Wieland [174]. Typical ash particle size distributions for a high-volatile bituminous coal, El-Cerrejón, and barley straw are presented in Fig. 15. The volume distribution is illustrated as a function of particle diameter. The volume distribution equals the mass distribution, if every particle has the same density. However, the heterogeneity in fly ash samples has been observed in various studies, implying that volume and mass distribution are not identical. Thus, the measurement of a mass distribution requires the identification of individual particle chemistry and size, and is therefore highly complex. Alternatively, sieve analysis can be used for the coarse fly ash PSD. However, as shown by Beckmann et al. [397], results can be misleading when compared with other methods such as CSEM or laser diffraction. Furthermore, sieve analysis is difficult to apply for fly ashes with small particle size, e.g. obtained in PF systems. Both ash samples shown in Fig. 15 are derived from pulverized fuel combustion tests in an entrained flow reactor (for details see the work of Balan [175]). The ash particle size distribution shows two significant modes (local maxima). The first mode is in the area of $0.1 < d_p < 1 \mu m$; the so-called sub-micron ash. The second and dominant mode is typically found around 20 $\mu m$. The ash sample of straw was collected using an electrostatic low pressure impactor (ELPI) for particles smaller than 10 $\mu m$, and a cyclone for larger particles [175]. The coal ash sample was extracted with the cyclone only. Both cyclone ashes and their size distributions were determined using the laser diffraction method. Wieland [174] used the same coal and showed that the amount of sub-micron ash is below 15 wt.% compared to coarse fly ash. As expected, the straw ash has a considerably higher volume fraction in the first mode compared to the coal ash sample. This is mainly due to the high amount of vaporizable species, e.g. organically-associated cations in the straw, in particular potassium. However, uncertainties due to the sampling of the coal ash particles are present and may lead to an increase of the first mode. Sarofim and Helble [70] mention an additional smaller first mode in the range of $0.02 < d_p < 0.1 \mu m$, which is barely observed in Fig. 15. According to their investigation, this very small, first peak is due to condensation effects. However, they do not have an explanation for the second mode in the range of $0.1–1 \mu m$. This mode might be caused by percolative fragmentation of ash particles from the burning char particle. Another interesting aspect is the plateau at large particle sizes above 100 $\mu m$, which might be due to unburnt carbon. It seems that char conversion has a strong impact on fly ash formation and only a combined approach including the distribution of mineral matter in coal and a detailed char conversion model is able to predict the remaining ash particles and their properties. However, detailed information on the fuel and char structure are required for this approach. Furthermore, many studies found indications of char fragmentation for coal [94,95,108,110,112–114,117,168] and biomass [119,120,122–124].

2.3.2. Chemical transformations of inorganic constituents

Inorganic constituents in coal not only undergo physical changes, such as melting, fusion or fragmentation, but also chemical transformation and decomposition. During heat up, part of the inorganic constituents and mineral matter is released as a gaseous species. The mass loss from mineral matter is due to the release of water from clay minerals, carbon dioxide from carbonates, and sulfur from pyrite [57]. This, and the release of organically-bound inorganics are challenges in predicting the ash composition. Gas release is usually included in the proximate analysis leading to erroneous results, especially for coals with a high ash content [57]. Not only the temperature treatment influences the decomposition and chemical transformation. Gas atmosphere and its composition can have a strong impact, in particular reducing environments. These reducing zones lead to a changed chemical transformation of some minerals. Crucial parameters are the availability of oxygen and the particle temperature. Reducing zones are also found inside burning char particles. Within regime II or III there is a depletion of oxygen and thus reducing environments. Fig. 16 shows the transformations of the main minerals found in coals, as a function of temperature. Depending on the mineral type, a very different behavior can be observed. Clay minerals, e.g. kaolinite or illite, are often dominating in the mineral systems. The transformation of kaolinite is well understood. Kaolinite loses water at around 425–525 °C, forming metakaolinite, which then changes to mullite and amorphous quartz, at around 900 °C [15]. The typical melting point of this amorphous phase is around 1700 °C [178]. Illite is a mineral containing most of the iron, magnesium, potassium and/or

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**Fig. 15.** Typical ash particle size distribution from PF combustion of straw and bituminous coal. Taken from tests in an entrained flow reactor [175,188].
aluminosilicates. McLennan and others [8] report iron bearing eutectics with even lower melting temperatures in the presence of only for pyrite, but also for calcite. Included pyrite can form pyrite was studied in a drop tube furnace by Yan et al. [183] observ-
tics with melting points around 1220 °C, are reported [8]. Excluded Similar behavior was observed in reducing conditions, where eutect-
[15] mentions a low melting point for partially transformed pyrite. and therefore, kinetic investigations were carried out [182]. Couch and, the second being a direct oxidation. Both are known to be slow
involving the thermal decomposition and subsequent oxidation,
which subsequently oxidizes in the presence of oxygen, to form hematite or magnetite. Hematite and magnetite are again high melt-
formation of glass phases and of amorphous silicates. Benson et al. [57] discuses the vast variation of
composition. They further claim the dominance of amorphous
discussion of mineral transformations by Mitchell and Gluskoter [177], Unsworth and others [82], and Bryers [16]. Sodium of all clays [15]. It is often present in large quantities and with associations to other minerals, such as pyrite [178]. It also starts to decompose at around 400 °C, forming an amorphous aluminosilicate. The melting point strongly depends on the composition. Typical values are around 1400 °C, however, the melting point can be as low as 980 °C for certain eutectics in the K2O - Al2O3 - SiO2 system [16,179]. Included illite is often reported to coalesce and form low-temperature melts. Excluded illite does not show fragmentation or swelling behavior. Quartz has a very high melting point and is often reported to be inert. Quartz can be liberated during milling and be present as an excluded particle. It can be embed-
ded in clay minerals or exist as a pure mineral [178]. Excluded quartz particles do not melt at temperatures below 1600 °C leading to sharp, erosive ash particles. Quartz is reported to start to volatil-
ize at temperatures around 1650 °C, or above. The behavior of pyrite is rather difficult. Iron is often reported to be a key element in deposit formation [15] and many research has focused on its transformation [8,180,181]. Pure pyrite (Fe2S) starts to decompose around 300 °C, releasing sulfur and forming pyrrhotite (Fe1-xS), which subsequently oxidizes in the presence of oxygen, to form hematite or magnetite. Hematite and magnetite are again high melting minerals. There are two mechanisms reported in literature, one involving the thermal decomposition and subsequent oxidation, and, the second being a direct oxidation. Both are known to be slow and therefore, kinetic investigations were carried out [182]. Couch [15] mentions a low melting point for partially transformed pyrite. Similar behavior was observed in reducing conditions, where eutectics with melting points around 1220 °C, are reported [8]. Excluded pyrite was studied in a drop tube furnace by Yan et al. [183] observing fragmentation, where each pyrite grain (50 µm) yielded around four child particles. The authors successfully used the Poisson law, similar to Eq. (2), in order to predict fragmentation behavior not only for pyrite, but also for calcite. Included pyrite can form eutectics with even lower melting temperatures in the presence of aluminosilicates. McLennan and others [8] report iron bearing glass melts at temperatures as low as 1080 °C. Ten Brink et al. [181] studied pyrite transformation in a real 2.5 MWth flame. They observed a decomposition to molten FeS, which then oxidized to solid iron oxide (Fe2O3 and Fe3O4). The kinetics of the decomposition were estimated to proceed as fast as devolatilization, and the subsequent oxidation as fast as char conversion [181]. Carbonates are known to decompose, and release carbon dioxide. Calcite (CaCO3) for instance starts to loose CO2 at around 800 °C. Other carbonates such as siderite (FeCO3) or dolomite (MgCO3CaCO3), start at roughly 500 °C and 750 °C, respectively [15,16]. Sulfates, for example gypsum, decompose earlier, and form stable anhydrite by the release of water.

Chemical transformations and their complexity are discussed in various references [16,82,178,184]. Process conditions, such as temperature and oxygen content, can change the path of chemical transformations, and lead to a variety of possible routes. Details of the chemistry and mineral decomposition are poorly understood, in particular for particles containing a mixture of mineral inclusions. When considering the melting temperatures shown in Fig. 16, most values are above typical temperatures in combustion systems. However, ash deposition occurs already at much lower values, which is probably due to interactions of mineral inclusions. Associated minerals are referred to as combinations of different mineral types in one particle. These associated minerals and their compounds behave differently, leading to eutectics and lowered melting points. In addition, minerals are often contaminated with other elements. Therefore, modeling the fate of pure minerals is not able to capture real processes. An overview of mineral transformations can be found, for instance, in the work of Unsworth and others [82], Bryers [16], Božić [184] or Magda [178]. The bar chart illustrated in Fig. 17, gives the mineral composition of the Upper Freeport bituminous coal, before and after combustion [57]. It shows the transformation of major minerals, in particular the oxidation of pyrite to iron oxide, the formation of glass phases and of amorphous silicates. Benson et al. [57] discusses the vast variation of fly ash particles in size and chemical composition. They further claim the dominance of amorphous phases consisting mainly of silicate glass, summing up to 90 or more

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**Fig. 16.** Mineral transformation of coal minerals as a function of temperature (modified from Mitchell and Gluskoter [177], Unsworth and others [82], and Bryers [16]).
Aerosols generated during solid fuel combustion and their characteristics received much attention during the 70’s and 80’s in the case of coal, and during the late 90’s in the case of biomass, when the number of units firing lower-grade fuels, such as straw or waste-

wood, increased. Aerosols can be distinguished into organic and inorganic particles. Organic particles such as soot, polycyclic aromatic hydrocarbons etc., can be caused by incomplete combustion, typically for small-scale biomass boilers. Inorganic aerosols originate from inorganic vapors and their condensation. A typical number and mass distribution for wood combustion in a stove can be seen in Fig. 18(a) and (b), respectively. Different operation conditions show that aerosol concentration can be affected by process conditions such as temperatures, oxygen concentration and distribution. However, for large units such as PF boilers the variation and potential is considerably smaller. Carroll et al. [47] showed for small-scale applications that air staging can reduce particulate matter (PM$_{10}$) emissions by 16 up to 26% in the case of wood combustion. A much higher potential was reported when co-firing peat with straw [46]. Up to 70% of aerosols were reduced caused by reactions of gaseous alkali vapors with aluminosilicates found in peat - see also Section 2.5.4. Damle et al. [139] collected data on aerosols formed during coal combustion. Fig. 19 compares measured particle concentrations within coal-fired boilers. The first mode typically occurs around $d_p = 100$ nm with particle concentrations in the range of $10^7$–$10^8$ per cm$^3$. It is difficult to compare different studies, since aerosol measurement devices differ, devices are highly complex, and locations inside a boiler, boiler type as well as process conditions highly affect results. Nevertheless, a qualitative estimate on typical particle sizes and their distribution can be drawn from such a comparison. Fig. 20 shows a similar collection of data on the particle number distribution in biomass fired systems. Particle numbers are slightly higher compared with coal measurements and shifted towards larger particle sizes with modes around $d_p = 100$–300 nm. This could be caused by an increased share of vaporizable inorganics as shown in Fig 4. An increased amount of inorganic vapor leads to a higher particle number, where a high particle concentration enhances particle coagulation and agglomeration. During this process, particles stick together, the particle number decreases, whereas the mass remains constant. The quantity, form and concentration of aerosols depends on the fuel, fuel preparation, firing system, but also on process conditions, such as stoichiometry and temperature [199]. Stoichiometry most likely affects organic aerosols produced during incomplete or under-stoichiometric combustion. This is often confirmed in small-scale wood fired grates [144]. Gas temperature strongly affects the vaporization of inorganic elements in the fuel, the supersaturation of inorganic vapors in the gas phase and thus, the condensation and formation of aerosols. These phenomena will be discussed within Section 2.5.3.
Table 4 compares different publications dealing with aerosol measurements in all three firing systems. Typical devices that are applied are impactor cascades such as the Berner type low pressure impactor (BLPI), similar to an ELPI, the differential mobility analyzer (DMA), the scanning mobility particle sizer (SMPS) or the aerodynamic particle sizer (APS), where the latter two are typically applied in automotive industry. A detailed description and comparison of these devices can be found in literature, e.g. [101,151,158,175,194]. An interesting high-temperature impactor was presented by Brunner et al. [160], which enables studying aerosol formation at higher temperatures. All these devices are highly complex and influenced by various parameters, such as dilution gas in order to prevent agglomeration in the device, the ability of particles to carry electrical charge, particle shape and density, gas temperature and thus gas viscosity and gas density, as well as many more. Therefore, it is not surprising that measurement results scatter significantly. A comparison of different studies should be only qualitatively. When evaluating Table 4, one can see that most studies apply impactors in order to sample aerosols. The highest concentrations of aerosols are found for waste-wood and straw. This can be explained by the relatively high ash content and the fact, that these fuels are rich in alkali metals shown in Table 1. Aerosol concentrations for particles smaller than \( d_p = 1 \) \( \mu \text{m} \), also referred to as PM1, show values up to 1500 mg/m\(^3\) as measured by Christensen et al. [149] in a straw-fired grate. Mikkonen [161] showed that around 66\% of fly ash can be found in aerosols with \( d_p < 3 \) \( \mu \text{m} \). For coals, typically smaller numbers are reported, however, many different values can be found in literature. The chemistry of aerosols strongly depends on the parent fuel. Straw leads to aerosols rich in salts mainly composed of KCl and K\(_2\)SO\(_4\). Aerosols from wood combustion are typically rich in K, Ca, Cl and Mg. On the contrary, bituminous coals lead to S-, Ca- and Si-rich aerosols. As discussed previously, the mode is typically around 100–200 nm, and is dominated by agglomerates. The combustion system can influence aerosol formation, however, there is no clear picture derived from Table 4.

Future studies should deal with the prediction of aerosol formation such as the work of Jokiniemi et al. [162]. There is a need for guidelines on how to present, calculate and evaluate aerosol measurements and emissions. Many studies do not provide all information that is needed in order to evaluate and interpret their measurement results. Further fundamental work has to be conducted and should be coupled with comprehensive CFD models enabling the prediction of ash deposition and hence, improve sootblowing or plant design. It is believed that aerosol behavior is of great importance for slagging and fouling, in particular for biomass-fired boilers.
Table 4
Selected studies dealing with aerosol measurements in different combustion systems. Major findings summarized in terms of aerosol concentration, particle size and chemistry.

<table>
<thead>
<tr>
<th>References</th>
<th>System and size</th>
<th>Fuel</th>
<th>Measurement technique</th>
<th>Concentration in mg/m³</th>
<th>Mode in nm</th>
<th>Chemistry</th>
<th>Findings</th>
</tr>
</thead>
<tbody>
<tr>
<td>[140]</td>
<td>Different PF boiler</td>
<td>Coal</td>
<td>Impactor, optical LPI</td>
<td>n.a. 1460³</td>
<td>100-200</td>
<td>50 and 2 μm</td>
<td>Ca, S, Si</td>
</tr>
<tr>
<td>[155]</td>
<td>Grate Slagelse</td>
<td>Bit. coal</td>
<td>BLPI</td>
<td>60-200</td>
<td>67</td>
<td>K, Ca, Mg</td>
<td>Measurement downstream of baghouse filter on diff. days</td>
</tr>
<tr>
<td>[141]</td>
<td>275 MW, UPM Kym</td>
<td>Black liquor</td>
<td>BLPI</td>
<td>11000⁹</td>
<td>200-300</td>
<td>Na, S, K, Cl</td>
<td>Primary particle size determined</td>
</tr>
<tr>
<td>[156]</td>
<td>35 MV, co-genera-</td>
<td>Willow</td>
<td>DMA, ELPI</td>
<td>53</td>
<td>90</td>
<td>K, S, Cl</td>
<td>Measurements at different locations and temperatures</td>
</tr>
<tr>
<td>[151]</td>
<td>6 MW, moving grate</td>
<td>Forest residue</td>
<td>BLPI, SMPS</td>
<td>17</td>
<td>79-145</td>
<td>120-140</td>
<td>K, Cl, S</td>
</tr>
<tr>
<td>[147]</td>
<td>10 kW, updraft pellet</td>
<td>Wood pellets</td>
<td>APS, SMPS</td>
<td>31-74</td>
<td>200-5000</td>
<td>60-70</td>
<td>K, Cl, C, S</td>
</tr>
<tr>
<td>[157]</td>
<td>404 MV, PF boiler</td>
<td>Bark pellets</td>
<td>Impactor, SMPS</td>
<td>48</td>
<td>100-110</td>
<td>110</td>
<td>K, Cl, S</td>
</tr>
<tr>
<td>[160]</td>
<td>20 MV, grate</td>
<td>MSW</td>
<td>Own LPI</td>
<td>384-1754</td>
<td>250-700</td>
<td>Cl, Na, K, Zn</td>
<td>High temperature LPI</td>
</tr>
<tr>
<td>[175]</td>
<td>15 kW, PF entrained</td>
<td>Straw (barley)</td>
<td>ELPI</td>
<td>5 wt.%</td>
<td>130</td>
<td>K, Cl, S</td>
<td>Additives are tested and evaluated</td>
</tr>
<tr>
<td>[174]</td>
<td>15 kW, PF entrained</td>
<td>Wood dust (spruce)</td>
<td>ELPI</td>
<td>1 wt.%</td>
<td>100</td>
<td>K, Ca, Cl, Mg, Si</td>
<td>Aerosol model development and validation</td>
</tr>
</tbody>
</table>

BLPI: Berner-type low pressure impactor, ELPI: electrostatic low pressure impactor, DMA: differential mobility analyzer, SMPS: scanning mobility particle sizer, APS: aerodynamic particle sizer. sub-micron modes are considered.

- Given values based on number distribution.
- Sorted by decreasing quantity.
- Concentration at mode diameter and at 13% O₂ in the dry gas.
- Mass in size class of the mode according to dm/dlog(dₚ).
- ELPI: PM₁₀ in mg/m³, SMPS: PVₐₘₐₚ in mm³/m³, APS: Number > 1 μm in 1/cm³
- Range from different days, diameter range given as geometric mean value.
- Concentration in PM₁₀ before filter/ESP (electrostatic precipitator)
- dₚ < 1 μm, measured at 160°C downstream convective section
- Estimated from given data.
- dₚ < 3 μm, measured at the furnace exit at 3 vol.% O₂
- Based on measured number distribution
- dₚ < 1 μm and primary particle diameter in the size of 20 nm
- mg/MJ

2.4 Classification of fly ash particles

Ash particles and their behavior in combustion systems are particularly challenging, since they can occur as liquid droplets with Newtonian fluid flow behavior, as solid elastic particles, or somewhere in between with a partially molten particle containing crystals. Ash particles can be classified based on their physical properties such as size, shape and geometry, as well as based on their chemical composition and chemical structure.

Ash particle structures reported in combustion systems are [97,186–188]:

- molten, perfectly spherical particles (typically from fusion of low melting ash/mineral particles),
- cenospherical particles with variable wall thickness (hollow spheres),
- plerospherical particles (hollow spheres filled with small often sub-micron ash particles).
angular sharp particles (often reported for unmolten quartz),
• loose, irregular shaped and highly porous solids (mainly reported for biomass, or unburnt char), and
• agglomerations of small particles (often produced from included mineral grains partially undergoing coalescence or by condensation and coagulation).

A graphical illustration of typical ash particles produced from coal combustion is shown in Fig. 21. Spherical particles, as illustrated in the top right corner, indicate that they have been molten in the flame region. Raask [200] first explained the formation of cenospheres (see middle right image). Coal particles with a high number of included mineral grains form an ash layer around a reactive char core. Fusion of this silicate envelope leaves burning carbon residue inside, continuously releasing gases. If the remaining carbon contains mineral grains, cenospheres, as shown in the center of Fig. 21, are assumed to form. Agglomerates may form similarly, however melting/fusion temperatures of ash or partially-transformed mineral grains, does not occur. Sharp, unmolten particles are often found to be composed of quartz or feldspars [15,97].

Typical ash particles produced by biomass combustion are summarized in Fig. 22. At a first glimpse, one can see much more irregular particles. Perfect spheres are rarely observed. Instead agglomerates (lower right corner) and irregular-shaped ash particles or crystals are reported. Wood combustion leads to calcium-rich particles with high fusion temperatures, as shown in the top left corner [101]. Straw (lower three images) forms similar particles, however, fusion is more often observed. Typically, small aerosol collide with large ash particles, which can change the stickiness and thus the deposition process. Characteristic salt-rich aerosol are shown in the top-middle image. They can be angular, and have relatively low melting temperatures.

Ash particle structures mainly depend on the raw fuel - size, form and distribution of inorganics - and on the combustion system - plant size, fuel size, grinding, temperatures, stoichiometry and combustion intensity. The first point is often addressed in scientific studies. However, the impact of combustion system on fly ash particle structures has never been studied systematically. It is known that ashes from lab-scale flow reactors and full-scale boilers can differ significantly. Different heating rates and flow velocities can change particle structural development, char fragmentation, and thus, ash formation [105]. However, there are studies, such as the work of Xu et al. [192], reporting relatively good agreement between PSD of ashes from lab- and full-scale. As expected, their data reveals that full-scale systems have much higher particle concentrations [192]. In general, higher temperatures increase the probability of fusion/coalescence of included mineral grains and enhance burnout. A coal having high numbers of included mineral grains will form coarser fly ash particles with spherical shape when burnt in a PF boiler, compared with low-temperature laboratory ashes, where every mineral grain will form one remaining ash particle, as long as char burnout is identical and sintering does not occur. Char particles within ashes are typically large (50 μm and larger) compared with fly ash particles [193,196]. A comparison of ashes from different combustion systems such as grate, FB and PF using the same parent fuel is challenging. As shown in Fig. 1, grinding, and thus particle size differs significantly, which then affects mineral liberation and residual ash PSD. Furthermore, residence time and temperature profiles differ significantly affecting the whole fly ash formation process. Ashes from grate combustion are typically differentiated into fly ash and bottom ash. In general, bottom ash are known to be significantly larger. For instance, bottom ash particles in MSW combustion systems are in the size range of 0.5–4 mm [197]. Fly ashes collected in grate systems on the other hand are often reported to be rich in sub-micron ash particles with peaks at around 0.2 up to 0.5 μm,
depending on the fuel and vaporization of inorganics [149,198]. Valmari et al. [189] studied fly ashes from willow combustion in a CFB boiler and found a bi-modal size distribution with peaks at 0.2–0.5 and 5–10 μm, respectively. Some large, irregular and unmolten particles with 100 μm were found indicating incomplete coalescence due to low temperatures [189]. In general, different combustion systems lead to changed fly ashes mainly caused by varying temperature profiles, residence times and parent fuels.

A classification based on chemistry is challenging. Within the same fuel sample, a wide range of chemical compositions and structural variations among fly ash particles, are observed. Coal ashes can produce glassy ash particles, particles containing crystals and intermediates. Therefore, a classification based on chemistry is not recommended. Instead CSEM data can be a powerful tool, for determining the chemical composition and its variation. Care should be taken, when categorizing ash particles to mineral or ash classes. Instead a list of the raw elemental composition for each ash/mineral particle, might be more useful.

In general, ash particles differ significantly in size, shape, structure and chemistry. This is even more pronounced in case of waste-based fuels or biomass. Both, the shape and chemistry are known to affect the sticking probability. Therefore, it is recommended to use synthetic materials mimicking ash particles, in order to study sticking and rebound behavior under well-defined and controlled conditions. For instance, coal ashes can be simulated using soda-lime glass particles [1,201], or biomass ashes with synthetic salt particles [202,203].

2.5. Ash deposition mechanisms

Ash deposition strongly depends on the presence of ash particles or inorganic vapors at heat exchanging surfaces. Deposition of particles involves particle transport to the wall, particle impaction, and particle retention, often called particle sticking. Commonly it is differentiated between particle impaction, sticking, and capture efficiency, which are defined as [204,205]:

\[ \text{Impaction} \% = \frac{\text{Mass of particulate impacting surface}}{\text{Total mass of particulate injected}} \]
\[ \text{Sticking} \% = \frac{\text{Mass of particulate sticking surface}}{\text{Mass of particulate impacting surface}} \]
\[ \text{Capture} \% = \frac{\text{Mass of particulate sticking to surface}}{\text{Total mass of particulate injected}} \]

\[ = \text{Impaction} \% \cdot \text{Sticking} \% \]

In this definition, the total mass of particulate injected should be calculated for the projected area in front of the obstacle, which is typically a cylinder with diameter \(D\) [206]. The difference between particle impaction and deposition rate are particles rebounding from heat exchangers. The capture efficiency can be calculated as the product of impaction and sticking efficiency. Physical phenomena affecting the transport of particles and vapors in the flue gas are summarized by Couch [15], who refers to an early study by Samms and Watt [207]. These phenomena are particle drag due to the flow,
molecular and Brownian diffusion, thermal and eddy diffusion, as well as gravity and electrostatic effects. Basically, each gradient in a flow field can lead to particle movement, where small particles are typically more prone to these gradients. This can be a gradient of shear forces, the so-called Saffman lift force [208], a gradient in species (referred to as diffusiophoresis) [209] or in turbulence (called turbophoresis), where particles are transported in the direction of lower turbulent kinetic energy [210]. The main transport mechanisms leading to ash deposition on a surface are [211,212]:

- **inertial impaction** including eddy impaction,
- **thermophoresis** and diffusional aerosol transport due to gradients in the flow,
- **diffusion** of inorganic vapors followed by heterogeneous condensation and/or heterogeneous chemical reactions with deposits.

The first two bullet points are related to particle deposition, where inertial impaction is often reported as the dominant mechanism of deposit formation, in terms of weight gain, and if a sticky initial layer is already existing. Heterogeneous condensation on the wall and chemical reactions of inorganic vapors with the deposit keep the surface concentrations of these gaseous species to zero. The behavior of inorganic vapors is difficult to study. They can form submicron particles during cooling within the boundary layer, which are then transported by thermophoresis and other diffusional effects to the surface. A graphical illustration of particle deposition mechanisms on a tube is shown in Fig. 23 [213]. Inertial impaction, and eddy impaction in a porous layer are dominating on the upstream cylinder face. Eddy impaction together with thermophoresis are dominating for small particles on both, the cylinder front and rear. They are often reported to be the dominant mechanisms on the cylinder rear. Thermophoresis, condensation and chemical reactions are often mentioned, however, their role is unclear. Experiments on particle deposition are mainly carried out in a vertical turbulent duct flow. Fig. 24 shows the rate of particle deposition on the wall of a circular duct, as a function of non-dimensional variables. The dimensionless deposition velocity $V_{\text{dep}}$ is plotted as a function of the dimensionless particle relaxation time $\tau_p$. The dimensionless deposition velocity is commonly defined as [214]:

$$V_{\text{dep}} = \frac{f_{\text{p}}}{\rho_{\text{p}} u_*}.$$  

![Fig. 23. Ash deposition mechanisms on a superheater tube (adapted with permission from Laursen et al. [213]. Copyright 1998 American Chemical Society.).](image)

![Fig. 24. Particle deposition from fully developed vertical turbulent duct flow (modified from Young and Leeming [214] and Guha [216]).](image)
where $J_{p\text{w}}$ is the mass flux of particles to the wall per unit area (in kg/(m$^2$s)), $\rho_{p\text{w}}$ is the mean particle concentration or density (in mass of particles per unit volume kg/m$^3$), and $u_\infty$ is the friction velocity at the wall. The friction velocity can be calculated by $u_\infty^2 = \tau_w/\rho_g$, where $\tau_w$ is the wall shear stress and $\rho_g$ the gas density. The wall shear stress $\tau_w = \mu_g(*)/\partial u_\infty/\partial y_{\text{wall}}$ is expressed by the gradient of the velocity parallel to the wall $u_\infty$, the distance to the wall $y_{\text{wall}}$, and the dynamic gas viscosity $\mu_g$. The horizontal axis shows the dimensionless particle relaxation time, which can be viewed as the time scale of the particle's reaction to changes in the gas phase velocity. The relaxation time is the time that a particle, initially traveling with free-stream velocity, needs in order to reach equilibrium velocity. The particle relaxation time $\tau_p$ needs in order to reach equilibrium velocity is caused by Brownian motion of particles. The difference between the particle Schmidt number, $Sc = \nu_g/D_p$, and the frequently cited publication of Liu and Agarwal [221], the deposition curve is decreasing with increasing particle size is observed. However, only recently, advances are reported [216]. Particle deposition in a power plant is dependent on the wall type, e.g. tube or boiler wall, and shows some differences compared to turbulent dust flow experiments. In the following subsections each of the listed mechanisms is described, recent advances are discussed, and differences to vertical dust flow experiments are discussed.

2.5.1. Inertial impaction

Inertial impaction is often referred to as the dominant mechanism, leading to accelerated deposit build-up, and producing the biggest weight gain in a deposit. It describes the effect that larger fly ash particles ($d_p > 10 \mu m$) cannot follow the streamlines around an obstacle, and thereby impact due to their inertia. This behavior is commonly expressed by the Stokes number, which is defined as the ratio of the particle relaxation time $\tau_p$ given by Eq. (6), to a characteristic flow time scale $\tau_{\text{flow}}$:

$$St = \frac{\tau_p}{\tau_{\text{flow}}} = \frac{\rho_g \cdot D_p^2 \cdot u_\infty}{9 \cdot \mu_g \cdot D}$$

where the characteristic flow time scale is calculated for a tube by $\tau_{\text{flow}} = D/2 \cdot u_\infty$, with $D$ being the outer tube diameter, and $u_\infty$ being the free-stream velocity. The flow time scale is the time that the free-stream flow needs to pass the cylinder radius. Fig. 25 illustrates the process of inertial impaction. The flow around a cylinder, with its recirculation zone in the wake of the tube, is shown by blue streamlines. Particles (black) approaching the cylinder cannot follow the curvature of the streamlines due to their large mass, which forces them to keep the current direction of the trajectory. Thus, inertial forces exceed aerodynamic forces. Larger particles with high inertia, and Stokes numbers of $St > 1$, barely respond to changes in the fluid flow, as illustrated by the top particle trajectory in Fig. 25. The particle impaction rate is highest for the front stagnation point of the cylinder at $\Theta = 0$ and decreases along the circumference. The maximum impaction angle $\Theta_{\text{max}}$ depends on the flow characteristics around the cylinder, and the separation point of the flow. Particle impaction on the cylinder rear side is also reported in literature, and is caused by the recirculation zone, which again is a function of the free-stream velocity $u_\infty$. Often, the so-called impaction efficiency $\eta$ is used to describe the impaction probability of a particle approaching a cylinder in the cross-flow. The impaction efficiency for the
from this linear function. Therefore, Israel and Rosner [215] introduced a correction factor for the Reynolds number. The particle Reynolds number for typical ash particles is

\[ \text{Steff} = \frac{\text{Steff}}{\text{Rep}} \]

where the correction factor is a function of the particle Reynolds number. The correction factor decreases from unity with an increasing particle Reynolds number. The particle Reynolds number for typical ash particles is \( \text{Rep} < 1 \), which leads to a negligible influence of the correction factor \( \psi \).

\[ \psi(\text{Rep}) = \frac{3 \cdot \left( \frac{\text{Re}_p^{1/3} \cdot \sqrt{0.158} - \tan^{-1} \left( \frac{\text{Re}_p^{1/3} \cdot \sqrt{0.158}}{\text{Re}_p \cdot 0.158^2} \right)}{\text{Re}_p \cdot 0.158^2} \right)} \]

where \( \text{Re}_p \) is the particle Reynolds number. Wessel and Righi [224] use the free-stream particle Reynolds number in order to calculate the effective Stokes number, using the following definition:

\[ \text{Rep} = \frac{\rho_p \cdot d_p \cdot u_\infty}{\mu_g} \]

Finally, the impaction efficiency can be estimated, using the following correlations:

\[ \eta = \beta_1 \cdot \ln(8 \cdot \text{Steff} \cdot 1/8) + \beta_2 \cdot \text{Steff} \cdot 1/8 \]

and

\[ \eta = \left[ 1 + \beta_1 \cdot \left( \text{Steff} - 1/8 \right)^{-1} + \beta_2 \cdot \left( \text{Steff} - 1/8 \right)^{-2} + \beta_3 \cdot \left( \text{Steff} - 1/8 \right)^{-3} \right]^{-1} \]

The valid range of Eqs. 13(a) and Eqs. 13(b), as well as the coefficients \( \beta_1, \beta_2 \) and \( \beta_3 \) are given in Table 5. The impaction efficiency as a function of the effective Stokes number is illustrated in Fig. 26(a). Values shown are calculated using Eqs. (10) to (13). The flue gas velocity is fixed to a value of \( u_\infty = 10 \, \text{m/s} \), and the gas density as well as the dynamic viscosity, are computed for a gas temperature of \( T_g = 1000 \, ^\circ\text{C} \), with data from the VDI heat atlas [225]. The correlations given by Isreal and Rosner [215] and Wessel and Righi [224] show similar behavior. Small particles with effective Stokes numbers below \( \text{Steff} < 0.125 \) do not impact according to the correlations. With increasing size, particles start to hit the surface and the impaction efficiency is monotonically increasing, with an increasing Stokes number. Particle impaction probability increases from around 8% for a 12.5 \( \mu \text{m} \) particle to around 35%, when doubling the diameter. A parametric study is conducted in Fig. 26(b). The impaction probability increases with increasing particle size and density. Two examples are shown for an aluminosilicate particle, with a density around \( \rho_p \approx 2.5 \, \text{g/cm}^3 \), and an iron-rich particle, e.g. hematite, with a density around \( \rho_p \approx 5.5 \, \text{g/cm}^3 \). It can be seen that particle density is along with the particle diameter a critical parameter. Thus, both parameters are crucial and an ash formation model needs to be able to predict both, in particular the particle size, since the Stokes number is a quadratic function of the particle diameter. The correlations given

---

**Table 5**

<table>
<thead>
<tr>
<th>References</th>
<th>Equation</th>
<th>Valid for</th>
<th>( \beta_1 )</th>
<th>( \beta_2 )</th>
<th>( \beta_3 )</th>
</tr>
</thead>
<tbody>
<tr>
<td>Wessel and Righi [224]</td>
<td>13a</td>
<td>0.125 &lt; \text{Steff} &lt; 0.5</td>
<td>0.01978749</td>
<td>0.51386545</td>
<td>-0.0482858</td>
</tr>
<tr>
<td>Wessel and Righi [224]</td>
<td>13b</td>
<td>0.5 &lt; \text{Steff} &lt; \infty</td>
<td>1.54424</td>
<td>-0.538013</td>
<td>0.2020116</td>
</tr>
<tr>
<td>Israel and Rosner [215]</td>
<td>13b</td>
<td>0.14 &lt; \text{Steff} &lt; \infty</td>
<td>1.25</td>
<td>-0.014</td>
<td>0.00508</td>
</tr>
</tbody>
</table>

---

**Fig. 26.** Impaction efficiency calculated with Eqs. 13(a) and 13(b): (a) as a function of the effective Stokes number and (b) as a function of particle diameter \( d_p \) and density \( \rho_p \). Calculated for a flue gas velocity of \( u_\infty = 10 \, \text{m/s} \) and a gas temperature of \( T_g = 1000 \, ^\circ\text{C} \).
are derived for in-viscous (potential) flow calculations and boundary layer effects are disregarded. It has been shown by Haugen and Kragset [226] that the cylinder Reynolds number \( Re_{cy} \) influences the capture efficiency curve, since it changes the boundary layer thickness for a viscous flow. An increased cylinder Reynolds number (calculated by \( Re_{cy} = \rho_d \cdot D \cdot u_\infty / \mu_g \)) shifts the impaction curve of Fig. 26(a) slightly to the left.

Particle impaction rates for small Stokes numbers cannot be predicted by potential flow calculations since boundary layer effects dominate this impaction process. Particles with \( St < 0.1 \), follow the streamlines around the cylinder almost perfectly. The impaction of these particles is solely due to their dimension. The particle center does not reach the surface, only the finite size of the particles leads to a contact between the cylinder surface and the particle surface. The small window in Fig. 25 illustrates this mechanisms. This effect is referred to as “interception” or “boundary layer interception”. Typically, this effect can be calculated by viscous flow calculations using CFD (see e.g. Haugen and Kragset [226]). The role of this effect on slugging and fouling, however, might be small, due to the small mass of these particles, and low impaction probabilities.

Compared with the vertical duct flow experiment, a cylinder exhibits an external flow with laminar boundary layers, and a transition flow with turbulent structures approaching the cylinder. To sum up, inertial impaction is often referred to as the dominant mechanism leading to extensive deposition, when particles adhere to the surface. It is most pronounced for larger particles, as shown in Figs. 26(a) and (b).

2.5.2. Thermophoresis

Thermophoresis describes a force on particles in a flow with a non-uniform temperature field. This force is acting in the opposite direction of the temperature gradient, i.e. from the hot gas towards the cold gas. The force becomes relevant for smaller particles, however, it is still not completely understood [227]. Thermophoresis is often mentioned to be important, but rarely addressed in a scientific way for slugging and fouling in a PF system. Another difficulty is the potential of particle nucleation within the boundary layer, which makes it very difficult to actually quantify thermophoresis. The main reason is due to the complexity of this effect. It is difficult to isolate the thermophoretic force in a deposition experiment, and it is even more complex to measure small thermophoretic forces, which are in the range of \( 10^{-9} \) to \( 10^{-13} \) N. The effect was first described by Tyndall [228] in the late 19th century, who observed the formation of a dust-free zone near a heated surface (see also the review of Young [227]). Small dust particles immersed in the flow could not reach the surface due to the thermophoretic force acting from the hot to the cold gas. There are several studies, such as Cawood [229], Walker et al. [230] or Cameron and Georg-Wood [231], indicating the dominant role of thermophoresis for the deposition of particles in the diameter range of \( 0.1 < d_p < 10 \) \( \mu m \). Gökoğlu and Rosner [232] showed that the impaction rate increases by a factor of 1000 for a 1 \( \mu m \) particle, when the wall temperature is set to a value of 20% below the free-stream temperature. Fig. 27 illustrates the force on particles in the boundary layer of a superheater tube. Thermophoresis (TP) can be explained by varying bombardment of gas molecules on a particle surface. Gas molecules are carrying a higher kinetic energy on the hot side of a particle compared to the cold side. The higher kinetic energy of collisions between molecules and the hot particle surface leads to a net force on the particle in the direction of the cold flow. The mean gas molecule velocity \( V_m \), can be derived from the Maxwell–Boltzmann equation:

\[
V_m = \sqrt{\frac{8 \cdot k_B \cdot T_g}{\pi \cdot m_m}} = \sqrt{\frac{8 \cdot R \cdot T_g}{\pi \cdot M}}
\]

where \( k_B \) is the Boltzmann constant, \( T_g \) the gas temperature, and \( m_m \) the molecule mass. It can also be calculated using the molar gas constant \( R \) and the molar mass \( M \) of the gas. A dimensionless expression of the thermophoretic force \( F_{th} \) is given in a study by Healy and Young [233]:

\[
F_{th} = \frac{\rho_g}{\mu_g} = \Phi \cdot \frac{\rho_d \cdot V_T_g}{2 \cdot \mu_g},
\]

where \( V_T_g \) is the temperature gradient in the gas phase at the position of the particle, if there is no particle present, and \( \Phi = f(Kn, \Lambda) \) is the thermophoretic coefficient. This coefficient is a function of the Knudsen number \( Kn \) and the ratio of the particle and gas thermal conductivity \( \Lambda = k_p / k_g \) (note that definitions differ in literature). The gas thermal conductivity is the translatory part of the thermal conductivity expressed by \( k_g = 15 / 4 \cdot \mu_g \cdot R_g \), where \( R_g \) is the specific gas constant. The gas properties in Eq. (15) are also calculated for the center of the particle, if there would be no particle. The Knudsen number \( Kn \), is defined as the ratio of the mean free path length \( \lambda \) of the fluid to the particle radius, according to the following equation:

\[
Kn = \frac{2 \cdot \lambda}{d_p}.
\]

The Knudsen number is used to judge, whether the flow characteristics can be described by continuum mechanics (for \( Kn < 1 \)), or, by methods of statistical mechanics (for \( Kn > 1 \)). For small particles (\( d_p < 5 \) \( \mu m \)) in a PF boiler, the Knudsen number can exceed values of \( Kn > 1 \) depending on the gas temperature. In this case, the classical Stokes drag has to be corrected (see e.g. [226]). The mean path length \( \lambda \), can be calculated by:

\[
\lambda = \sqrt{\frac{\pi \cdot T_g \cdot R_g}{2 \cdot \frac{\mu_g}{p}}}
\]
where \( p \) is the pressure in Pa, and the gas viscosity \( \mu_g \), being a function of the gas temperature \( T_g \). With an increasing gas temperature, the mean free path length increases leading to an increased Knudsen number. At ambient temperature, air has a mean free path length of \( \lambda = 65 \text{ nm} \). This value increases for a furnace temperature of \( T_f = 1200^\circ\text{C} \) to \( \lambda = 450 \text{ nm} \). At that temperature a particle with \( d_p = 0.9 \text{ µm} \) reaches the critical Knudsen number of \( Kn = 1 \), requiring extra laws for particle drag. Many studies have focused on the formulation of a generally valid expression for \( A_m \) and \( C_m \). Pointing out the dependency of the thermohorpeic force on the thermal conductivity ratio in the slip-flow region, and proposed the following equation for low Knudsen numbers \( Kn \ll 1 \):

\[
\Phi = \frac{-12 \cdot \pi \cdot K_e}{2 + \Lambda},
\]

(18)

where \( K_e \) is the thermal creep coefficient. Maxwell, who first postulated the theory of gaseous thermal creep, derived \( K_e = 0.75 \) from simple kinetic theory calculations [227,235]. Recent work suggests values in the range of \( 1.02 < K_e < 1.18 \) [227]. The negative sign in Eq. (18) indicates the direction of \( TP \), which accelerates particles in the opposite direction of the temperature gradient. Waldmann [236] suggested a correlation for the region of free molecular flow at \( Kn \gg 1 \):

\[
\Phi = \frac{-2 \cdot \pi}{Kn},
\]

(19)

\( \Phi \) is solely a function of the Knudsen number, and is not influenced by particle properties. A widely used theory is based on the work of Talbot et al. [237], who modified formulations originally proposed by Brock [238]:

\[
\Phi = \frac{-12 \cdot \pi \cdot K_e \cdot (1 + \alpha_c \cdot \Lambda \cdot Kn)}{(1 + C_m \cdot Kn) \cdot (2 + \Lambda + 2 \cdot \alpha_c \cdot \Lambda \cdot Kn)},
\]

(20)

with

\[
C_m = \left( 2 - \frac{\alpha_m}{\alpha_e} \right) \cdot A_m, \quad \text{and} \quad C_e = \left( 2 - \frac{\alpha_m}{\alpha_e} \right) \cdot A_e.
\]

(21)

The velocity slip and temperature jump coefficients \( C_m \) and \( C_e \) depend on the momentum and energy accommodation coefficients \( \alpha_m \) and \( \alpha_e \), as shown in Eq. (21), where \( \alpha_m \) and \( \alpha_e \) are constants [233]. Brock [238] suggested values of \( A_m = 1.0 \) and \( A_e = 15/8 = 1.875 \). Talbot et al. [237] used values of \( A_m = 1.14 \), \( A_e = 2.18 \), and \( K_e = 1.17 \), which are similar to the ones proposed by Beresnev and Chernyak [239]: \( A_m = 1.137 \) and \( A_e = 2.178 \). The accommodation coefficients \( \alpha_m \) and \( \alpha_e \) describe the interaction of incident gas molecules with the particle surface, and are often set to \( \alpha_m = \alpha_e = 1 \) [233,239]. Another mathematical description of \( \Phi \) was introduced by Beresnev and Chernyak [239], and is given by:

\[
\Phi = \frac{-2 \cdot \pi \cdot \left[ f_{11} + \Lambda \cdot f_{12} \right]}{\left[ f_{11} + (1 + 2.5 \cdot \Lambda \cdot Kn) \cdot f_{14} \right]},
\]

(22)

where the functions \( f_{ij} \) are only dependent on \( Kn \) and defined in look-up tables (see [239]). A further correlation was proposed by Yamamoto and Ishihara [240]:

\[
\Phi = \frac{-6 \cdot \pi^{3/2} \cdot A_{\text{th}} \cdot H_0 - A_0 \cdot (H \cdot W + 2.5 \cdot \Lambda \cdot Kn)}{H_0 \cdot W + 2.5 \cdot \Lambda \cdot Kn},
\]

(23)

Eq. (23) again uses look-up tables for the coefficients \( A_{\text{th}}, A_0, H_W, \) and \( H_0 \) [240]. Since look-up tables are impracticable and their application is elaborate, simpler correlations, such as the one proposed by Talbot et al. [237], are often preferred for modeling purposes. A recent correlation of \( \Phi \) has been proposed by Young [227], reassessing available measurements, without the need of look-up tables:

\[
\Phi = \frac{-12 \cdot \pi \cdot K_e \cdot (1 + \Lambda \cdot C_e \cdot Kn)}{[1 + 3 \cdot Kn \cdot e^{+4w/\Delta K_n}] \cdot (1 + 3 \cdot C_m \cdot Kn) \cdot (2 + \Lambda + 2 \cdot C_e \cdot Kn)},
\]

(24)

Young suggests a value of \( C_m = 0.5 \), for the interpolation constant. The correlation provides similar results as the one suggested by Beresnev and Chernyak [239], and is considered to be more accurate. Strictly it is only valid for \( Kn < 0.2 \), however, Young [227] suggests an application for the whole \( Kn \)-range. A comparison of different correlations for \( \Phi \) is shown in Fig. 28. At \( Kn = 0 \) all model curves are consistent with Eq. (18), suggested by Epstein [234]. The same behavior can be observed for large Knudsen numbers \( (Kn \to \infty) \), where they approach Eq. (19), suggested by Waldmann [236]. In the region \( 0.001 < Kn < 1 \), models show large differences. In particular, the frequently cited equation proposed by Talbot et al. [237] differs considerably to equations suggested by Beresnev and Chernyak [239], and the model by Young [227]. The latter two show considerably lower values at the same \( \Lambda \), indicating a decrease in thermohorpeic force. At very high thermal conductivity ratios \( (\Lambda = 1000) \) the so-called “reversed thermophoresis” is predicted. This force from cold to hot was first postulated by Dwyer [241], who did theoretical calculations in the Boltzmann equations [227]. It is often also referred to as “thermal stress slip flow” or “second mechanism of thermophoresis”. However, experimental evidence is still due [227]. This phenomenon can be seen in Fig. 28 when \( -\Phi/2\pi \) yields negative values. At a low value of \( \Lambda = 1 \), the thermophoretic coefficient shows its highest values. The values decrease with decreasing particle size, but relative to the particle mass, thermophoresis becomes more important at lower values of \( dp \). Typical thermal conductivity ratios for a PF boiler are in the range of \( 3 < \Lambda < 100 \), where both, the gas \( k_g \) and the particle thermal conductivity \( k_p \), are dependent on temperature and chemical composition. Rezaei et al. [246] gives values for the thermal conductivity of coal ashes in the range of \( k_g = 0.3 - 4 \text{ Wm}^{-1} \text{K}^{-1} \). They further assume higher values for iron-rich ashes. The gas thermal conductivity is typically in the range of \( k_g = 0.04 - 0.1 \text{ Wm}^{-1} \text{K}^{-1} \), where values are taken from the VDI heat atlas, and calculated for typical flue gas compositions [225].

The measurement of thermophoresis is a challenging task due to the small magnitude of this force. Early observations, such as the one reported by Tyndall [228], are strongly influenced by convection of the surrounding fluid. Later experiments focused on single particle studies, in a so-called Millikan cell. This enables the exact measurement of the particle diameter. Chaged liquid droplets are held in an electric field between two electrodes, with the field strength \( E \); see also [247–249]. By differential heating of the electrodes, one can establish the following equilibrium \( e^+ \cdot E = m_g \cdot g + F_{\text{th}} \), in which \( e^+ \) is the elementary charge, \( m_g \) is the mass of the particle, and \( g \) is the acceleration due to gravity. This equation can be used to calculate the thermohorpeic force by knowing the particle mass, which requires an exact determination of the particle size. This enables a direct measurement of the thermohorpeic force on droplets or particles in a controlled environment. By changing the carrier gas and its pressure or the particle composition, the value \( \Lambda \) can be studied at different \( Kn \) numbers.

Studies on the role of thermophoresis in combustion systems are rare. An interesting experimental and modeling study with direct relevance and link to slagging and fouling, was presented by Zhan et al. [242]. They used a vertical surface in a 100 kW down-flow laboratory coal combustor in order to study the inner deposit layer formation and the role of thermophoresis within laminar flow. The authors introduced a thermophoresis number \( Tp \) being the ratio of the time a particle travels along a cold surface with thermophoresis
and the time a particle would require without thermophoresis by considering only drag. If \( T_p < 1 \) particles are captured on the surface. By using this relationship, the authors could show reasonable agreement with measurements. Ash deposition rates increased linearly as the temperature difference between gas and surface increased. Future work will include thermophoresis in CFD codes and validate experiments.

A study [243] predicting the capture efficiency on a cylinder in the cross-flow with and without thermophoresis showed that the capture efficiency for particles with small Stoke numbers increased by three to four orders of magnitude depending on the thermophoresis model and the particle size. Two different models, i.e. Talbot et al. [237] and Young [227], were compared, where the latter one showed a decreased impaction efficiency. Furthermore, it was explained why small aluminosilicates particles experience a higher thermophoretic force compared with iron-rich particles. This is due to an increased thermal conductivity ratio \( \Lambda \) for iron-rich particles [243]. Lutro [245] conducted a similar study at lower cylinder Reynolds numbers and found similar results for a non-isothermal case.

Beckmann et al. [397] evaluated the influence of thermophoresis on the overall deposition rate using an isothermal plug flow reactor and a comprehensive and detailed CFD model. The CFD model included the effect of thermophoresis by using the model of Talbot et al. [237]. Predicted ash arrival rate on a cooled probe increased depending on the port in the test rig between 7 and 50%. The authors underline the important effect of temperature and the need for an accurate sticking criterion. A similar study was presented recently by Yang et al. [304], who used 2D CFD simulations in order to predict the deposit growth including thermophoresis using again the Talbot model. During early stages, thermophoresis increased the impaction efficiency from 0.02 to around 0.03. This effect diminished with increasing probe surface temperature and time. The authors found that ash deposition is dictated by inertial impaction and the stickiness of particles [304].

A different conclusion concerning thermophoresis was presented by Sinquefield [244]. He studied the role of different deposition mechanisms using the Multifuel Combustor at Sandia National Laboratories. Conditions from black liquor recovery boilers were mimicked using sub-micron and micrometer-sized particles together with a dynamic monitoring system for deposit growth rates. Results showed a linear deposit growth accompanied by a highly non-linear temperature increase, ruling out thermophoresis since temperature difference became smaller once the layer thickness increased. Sinquefield [244] showed that the rate remained constant even though the temperature difference dropped significantly, concluding that thermophoresis is not the rate-controlling mechanism. However, as the initial probe temperature was varied, deposition rate changed, indicating some sort of thermal effect. The author instead postulates an inertially-dependent mechanisms based on deposit morphology. Morphology of sub-micron deposits is dendritic with over 90% voidage. Particles are found to have a high sticking efficiency and do not roll or settle subsequent to impaction in the porous structure [244].

Thermophoresis is a temperature-driven effect, whose relevance during slagging and fouling is not clear yet. At early stages of deposit build-up, it may play an important role, however, detailed validation studies using CFD in order to explain experimental observations are rare in literature. Additionally, the effect of deposit structure is often neglected, mainly due to its complexity. Furthermore, uncertainty due to different correlations is high.

### 2.5.3. Condensation

The condensation of inorganic vapors occurs during cooling, when the flue gas is supersaturated and gas temperature falls beneath the vapor dew point. A fluid is saturated when the vapor pressure of the condensing species equals the saturation pressure of the same species. Condensation on a surface (fly ash particle or heat exchanger) is referred to as heterogeneous condensation. A direct particle formation in the gas-phase is called homogeneous condensation; see also the work of Wieland [174]. In the case of a clean tube, condensation leads to the formation of a thin, sticky film, which might change the pick-up of other solids [15]. Further condensation effects can occur on fly ash particles or on existing deposits. The amount and chemical composition of inorganic vapors strongly depends on flue gas temperatures, and the fuel itself. In the superheater region with gas temperature around 800–1200 °C, these inorganic vapors are primarily compounds of alkali metals [15,102,212].
alkali chlorides (KCl, NaCl),
alkali sulfates (K₂SO₄, Na₂SO₄),
alkali carbonates (K₂CO₃, Na₂CO₃),
alkali hydroxides (KOH, NaOH), and
heavy metals and their compounds (Zn, Pb, ZnCl₂, etc.).

The vapors listed above are predominantly formed by chemical reactions in the gas phase [212], and depend on the vaporization and release of inorganics in the fuel as discussed by Fig. 4, which gives estimates on elements, which can be vaporized and their quantity. Fig. 29(a) shows the inorganic element vaporization fraction per unit burnout time for a Montana lignite. This study was conducted by Mims et al. [250], and shows that only a small amount of inorganic vapors forms at combustion temperatures of 1300–1500 °C. The fraction vaporized \( x \) divided by the burnout time \( t_b \) is shown as a function of temperature [70]. At \( T = 2000 \, \text{K} \), the value \( x/t_b \) yields 5 for Na, implying that around 10% of the sodium in the lignite will vaporize during a burnout time of \( t_b = 2 \, \text{s} \). The amount might be even lower for higher-rank coals [57]. On the other hand, condensation is important for fuels with high alkali metal contents, such as biomass. Dayton et al. [251] used a high-temperature reactor coupled with a mass spectrometer, in order to study the release of alkali and chlorine species during switchgrass combustion. Their findings suggest that potassium release mainly occurs during char conversion, with a slight overlap with devolatilization. Chlorine is released as HCl during devolatilization. Adding steam reduced the amount of KCl, and increased the release of KOH [251]. Heterogeneous condensation requires the presence of inorganic vapors at the heat exchanging surface. For typical clean superheater tubes, the flow around the cylinder is in the range of Reynolds number of 500–5000. At these numbers, the boundary layer is laminar, and vapor transport is driven by Fick’s first law of diffusion:

\[
\dot{J}_A = -D_{AB} \nabla c_A,
\]

where \( \dot{J}_A \) is the diffusive flux in mol/(m² s), \( D_{AB} \) is the molecular diffusion coefficient of species “A” in species “B”, and \( \nabla c_A \) is the concentration gradient in all spatial directions (e.g. \( \alpha A/\alpha x \)). A correlation for the diffusion coefficient of gaseous salts in nitrogen can be found in the work of Wilke and Lee [252] or [212]. Tomeczek and Waclawiak [253] use mass transfer laws, and give the following equation in order to calculate the mass flux of species “A” to the wall:

\[
\dot{m}_A = \rho_A \cdot \beta_A \frac{D_A - p_{sat,A}}{p},
\]

where \( \beta_A \) is the mass transfer coefficient, \( \rho_A \) the partial pressure, \( p_{sat,A} \) is the saturation pressure (or vapor pressure) of species “A”, and \( p \) the total pressure. The mass transfer coefficient \( \beta \), often also defined as \( k \), can be calculated by the following expression:

\[
\beta_A = Sh \cdot D_{AB} \frac{D}{D}
\]

where \( Sh \) is the Sherwood number being a function of the Reynolds number \( Re \) and Schmidt number \( Sc \). The parameter \( D \) is the diameter of a heat exchanger tube. An empirical correlation for the Sherwood number of a tube in a cross-flow, is given by:

\[
Sh = c \cdot Re^{m} \cdot Sc^{n} \cdot (Sc/Sc_{w})^{0.2}.
\]

\( Sh = c \cdot Re^{m} \cdot Sc^{n} \cdot (Sc/Sc_{w})^{0.2} \cdot \) (28)

where the coefficients \( c, m \) and \( n \) are dependent on the flow characteristics, and thus on the Reynolds number. Analogous equation for a spherical ash particle can be found in the literature (see Baehr and Stephan [254]). The last term in Eq. (28) is a correction for differences in the Schmidt number of the free-stream Sc and of the wall Scw, where the Schmidt number is defined as the ratio of momentum- to mass-transport: \( Sc = v_g / D_{AB} = \mu_g / (\mu_g D_{AB}) \) [212]. An important quantity is the saturation pressure \( p_{sat,A} \), e.g. needed in Eq. (26). It is a function of gas temperature and concentration of species “A”. Typically, it is calculated using the Antoine equation:

\[
\log_{10} p_{sat,A} = A - \frac{B}{C + T}.\]

\( \log_{10} p_{sat,A} = A - \frac{B}{C + T} \) (29)

where \( A, B, \) and \( C \) are fitting coefficients, and \( T \) is the temperature in °C (e.g. given in [212, 255]). Another option for the calculation of the saturation pressure is by using thermodynamic equilibrium calculations. A useful number for the estimation of condensation is the supersaturation ratio \( S_A \) of the gas phase with species “A”. It
can be predicted by the following expression:

$$S_A = \frac{p_x}{\rho_{sat}(T)} \cdot (30)$$

At high supersaturation ratios $S_A \gg 1$, homogenous condensation is likely to occur, whereas at $S_A = 1$ the system is in equilibrium, as it is shown in Fig. 29(b). Homogeneous condensation (particle nucleation) starts at a gas temperature of $T_g = 1000 \degree C$ and $S_A > 5$ for alkali species [171,172,174]. Thus, ash deposition due to heterogeneous condensation is expected to play a key role in the range of $1 < S_A < 5$ [212]. Fig. 29(b) shows, that depending on the vapor concentration, $K_2SO_4$ starts to condense at relatively high temperatures of 950–1200 \degree C. Thus, it will most likely occur on fly ash particles in the superheater region or within boundary layers of heat exchangers. Alkali chlorides (KCl) supersaturate at lower temperatures and hence, they are expected to condense directly on the tube. Experimental studies on inorganic vapor deposition on surfaces are reviewed in the work of Haselsteiner [256]. There are only few studies present dealing with heterogeneous condensation such as the one by Nielsen et al. [257], Ajabshirian et al. [258], Lindberg et al. [203] or Yang et al. [304]. An important characteristic is the metal vapor dew point. Below this point, condensation effects, e.g. of inorganic vapors in the boundary layer of a tube, lead to sub-micron particles enhancing deposit built-up. Is an inorganic vapor above its dew point, chemical reactions can take place, either with other gases or with solids, e.g. ash particles or deposits. These reactions can then change the melting temperature or lead to a sticky surface, enhancing again ash deposition rates.

2.5.4. Chemical reactions

Heterogeneous chemical reactions can occur between gas phase species and deposited mass or ash particles. Often alkali metal vapors are dominating inorganic reactions, e.g. on particles or boiler walls. Couch [15] states that chemical reactions can determine whether a particles sticks and deposit starts to grow. The most important chemical reactions reported in literature are [15,259):

- formation of low temperature eutectics from the interaction of Fe, Na, Ca, Al, and Si,
- sulfation,
- alkali absorption,
- carbonation, and
- oxidation or reduction.

Strictly, the first point is not a chemical reaction, however, it is strongly influenced by reaction and diffusion processes. Sulfation typically occurs for compounds of Na and K, Ca, Mg or Zn with reactions being:

$$2MCl + SO_3 + H_2O \rightarrow M_2SO_4 + 2HCl \quad (31)$$

$$2MCl + SO_3 + 1/2O_2 \rightarrow M_2SO_4 + Cl_2 \quad (32)$$

In Eqs. (31) and (32) "M" stands for instance for alkali metals Na or K. Both reactions can also proceed with SO$_2$ instead of SO$_3$. However, sulfation is reported to be orders of magnitude faster with SO$_3$ [260]. Both reactions can either occur as a gas phase reaction, or as gas-solid reaction [257]. Furthermore, Eqs. (31) and (32) release chlorine species, which can then attack the metal surface and lead to corrosion, dependent on the metal temperature [175]. The chemical absorption of alkali species in the deposit is mainly attributed to aluminosilicates (such as kaolinite), and their ability to absorb alkali sulphates, or, alkali chlorides [48,49,261,262]:

$$Al_2O_3 \cdot 2SiO_2 + M_2SO_4 + 2H_2O \rightarrow M_2O \cdot Al_2O_3 \cdot 2SiO_2 + SO_3 + 2H_2O \quad (33)$$

$$Al_2O_3 \cdot 2SiO_2 + 2MCl + 2H_2O \rightarrow M_2O \cdot Al_2O_3 \cdot 2SiO_2 + 2HCl + H_2O \quad (34)$$

This absorption process leads to a formation of low-melting silicates. The transformations can include sintering and strongly affect physical properties of the deposit, depending on the temperature [15]. The reaction rate is slow for the absorption process, compared with sulfation. However, the absorption of alkali metal vapors above their dew point and at high temperatures, where condensation cannot occur, is known to be faster, in particular when aluminosilicates are molten. Lindner and Wall [263] claimed that sodium silicate formation is significantly higher in the case when NaOH reacts instead of NaCl. The reaction path is accordingly:

$$2MCl + 2H_2O \rightarrow 2MOH + 2HCl \quad (35)$$

$$Al_2O_3 \cdot 2SiO_2 + 2MOH \rightarrow M_2O \cdot Al_2O_3 \cdot 2SiO_2 + H_2O \quad (36)$$

Hydroxides are mainly stable at high temperatures and in systems with low concentrations of sulfur, e.g. when firing biomass. At lower temperatures, chlorides become stable, and even further down the temperature axis carbonates may show up. It is easier to capture hydroxides since their chemistry fits better into the aluminosilicate-3D structure, compared with relatively large chloride molecules. Sulfur has the effect to rise the dew point by forming sulfates that condense [49]. It is concluded that sulfur lowers the temperature for reaction between alkali vapors and aluminosilicates, and consequently, the amount of alkali metals scavenged [48]. Fagerström et al. [46] showed that the number of aerosols in the range of 0.05–1 \um is reduced by more than 70% when co-firing peat with straw. In particular the amount of alkali chlorides decreases leading to less corrosive deposits. High temperatures in the flame can have two effects. On the one hand, vaporization rates increase leading to a higher concentration of inorganic vapors. On the other hand, the absorption of alkali metals in aluminosilicates is much faster at higher temperatures, and thus, it can lead to a decrease in aerosol concentration. Another aspect of chemical reactions is the deposition of unburnt carbon. Typically, this value is below 2 wt.\% in fouled deposits, and no unburnt carbon is found in slagging deposits [15]. Unburnt carbon can lead to further reactions and reducing conditions, accompanied with heat and gas release inside deposits. All chemical reactions are a function of temperature, which can vary strongly within deposits as shown later on in Fig. 32.

2.5.5. Further transport mechanisms

There are further transport mechanisms reported in the literature with mostly unknown relevance for slagging and fouling. These mechanisms lead to forces on fly ash particles, change the impaction efficiency, and can therefore influence the deposition process. An often mentioned but rarely addressed transport mechanism is the so-called “eddy impaction”. Turbulent eddies in the vicinity of heat exchanging surfaces can accelerate small particles, which are then able to leave the eddy due to their inertia and penetrate the boundary layer. This effect might be important for the wake of a superheater tube (lee side of the cylinder), however, it is only relevant for smaller particles. A further force on particles is induced by “Brownian motion” of molecules affecting the movement of, again, only small particles. Saffman [208] proposed a force induced by shear stresses. It is often referred to as the Saffman lift force and should be included in regions with high shear stresses such as in the vicinity of walls. This force can enhance the deposition velocity of particles, and for deposition calculation a modified expression should be used including effects of the proximity of a wall [216]. The sign of the Saffman lift force depends on the direction of the slip velocity perpendicular to the wall.

Electrophoresis is a force on dispersed particles in an electric field. The force is given by $F_{ed} = q \cdot E$, where $q$ stands for the total charge of a particle. In addition, in the presence of a charged wall, particles can experience an electrostatic force [216], Guha [216]
impact of different electrical charges, heterogeneous condensation, and form dendritic structures. The operation, surfaces collect small particles due to thermophoresis or thermally due to sintering. This is a crucial parameter since a clean and smooth superheater tube up to three orders of magnitude leading to deposits of significant impact. A similar effect compared to the surface roughness can be observed. A slight temperature increase of $\Delta T = 50 \text{ K}$ leads to a 25 times higher deposition velocity due to thermophoresis (see Section 2.5.2).

2.5.6. Mechanisms removing deposits

Besides mechanisms leading to deposit formation, deposit removal is a phenomenon which is often observed. The main mechanisms leading to removal, according to a review of Zbogar et al. [265], are:

- shedding of deposits due to thermal shock, mechanical stresses or gravity,
- erosion caused by sharp, angular, unmolten particles, or melting and drip off.

Shedding of deposits can be caused by various mechanisms such as gravity, thermally- or mechanically-induced tensions. Thermal tension can be the result of combustion fluctuations, load changes or soot blowing. Mechanically-induced tensions are typically due to soot blowing or mechanical fluctuations, such as vibrations [265,266]. Soot blowers and water cannons use pressurized steam or water and spray it on heat exchanging surfaces in order to cause stresses in the deposit and clean the boiler wall. Fig. 31 shows the effect of soot blowing on steam generation. However, the efficiency of soot blowing strongly depends on the deposit structure, its chemistry, age and location in the boiler. A classification of deposits and the influence of removal mechanisms on deposit types is given in Table 6. Erosion is the process when sharp unmolten particles collide with non-sticky areas on a deposit surface [265]. Typically, in coal-fired boilers, these are quartz particles with relatively high melting points. Erosion, as a gradual removal of material, can be divided into deformation and cutting actions. Deformation is relevant for brittle materials and caused by the normal velocity component of incoming particles, whereas cutting actions are related to the tangential velocity component, and most relevant for ductile surfaces.

Rasalk [12] differentiates between erosion of abrasive, hard, and angular quartz particles, which cause erosion by cutting, and glass particles leading to surface deformation and brittle failure. Main parameters influencing erosion are particle hardness, shape, diameter, impact velocity, and angle of impaction. Table 6 shows that erosion is dominant for the removal of dry, powdery deposits, whereas molten slags are not affected by erosion effects. Gravity shedding is caused by gravitational forces due to the deposit weight, which lead to a break down and/or fracture in the structure [265]. The gravitational force can exceed forces in the bonding of the deposit, or the interface of deposit and steel surface. Large deposits are reported to fall into the ash hopper, causing damage to the tubes. This effect is most relevant for powdery or lightly sintered deposits. Gravity is also causing the removal of molten slags. A thermal shock leads to fracture due to different thermal expansion coefficients of the deposit and the tube material. A sudden shrinkage caused by cooling (e.g. by soot blowing) leads to thermal stresses and failure inside the deposit [265]. This mechanism is more pronounced for sintered deposits, with higher thermal conductivities and lowered porosity values. Removal mechanisms are manifold and dependent on many characteristics, such as deposit strength and structure, cleaning devices inside the boiler, chemical composition and particle characteristics. It is therefore not surprising that modeling of deposit removal is challenging and rare in literature.

![Fig. 30. Impact of surface roughness, particle electrical charge, and gas phase temperature gradient on dimensionless deposition velocity (data from Guha [216]).](image-url)
2.6. Deposit growth and effects on heat transfer

Deposit formation is strongly dependent on process conditions inside the boiler and fly ash characteristics, i.e. chemical composition and size distribution, as discussed in the previous section. Main process parameters influencing the extent of slagging (superheater region with molten or partially molten ash particles) and fouling (low temperature region such as economizer with lower flue gas velocities and solid ash particles) are the flue gas temperature, velocity, and composition (reducing or oxidizing environment). Slagged or fouled heat exchanging surfaces lower the heat transfer rate to the boiler and composition (reducing or oxidizing environment). Slagged or fouled heat exchanging surfaces lower the heat transfer rate to the water-steam cycle and thus reduce the boiler efficiency and significantly affect the operability. Van Beek et al. [267,268] reported a powdery deposit in the economizer region (fouling layer). In this region, ash particle are solidified due to lowered temperatures; flue gas temperatures are typically between 400 and 600 °C, and steel tube temperatures around 300 °C. During early stages of deposit formation (clean tube), only sub-micron particles can deposit, since their velocity is low enough. Large particles will rebound and possible erode loosely-bound particles [268]. This is confirmed by study of Steadman et al. [269], who observed a thin 10-100 μm thick layer, composed of sub-micron particles. At later stages, once the surface roughens and may sinter together, larger particles in the size range of 1-10 μm are reported to deposit and stick [268,270].

The main reason for deteriorated heat transfer is the low thermal conductivity of ash deposits. A deposit layer has a relatively low thermal conductivity (0.2 < k_{deposit} < 3 Wm^{-1}K^{-1}), compared to steel tubes (15 < k_{steel} < 57 Wm^{-1}K^{-1}), leading to a deteriorated heat transfer from the flue gas to the water-steam cycle. The thermal conductivity of steel depends on its composition. Austenitic steels (such as X8CrNiMoN1613) show values around 15 Wm^{-1}K^{-1}, whereas ferritic steels (such as 10CrMo9) have higher values of 35 Wm^{-1}K^{-1} at ambient temperature [271]. Wynnyckyj et al. [272] developed an integrated monitoring system in order to determine boiler performance and a cleaning strategy for heating surfaces by sootblowers. They applied a combination of thermocouples, heat flux meters and pyrometers. A furnace in Saskatchewan, Canada was used to install “dirty” and “clean” heat flux meters directly on the boiler wall. The clean heat flux meters were protected from slagging by purging air, whereas dirty ones were exposed to ash accumulation. Results for heat transfer over time are shown in Fig. 31. This figure clearly reveals a reduced heat transfer when an ash layer builds up. It shows that selective soot-blowing can increase heat transfer rates. This kind of monitoring system is often used to optimize soot-blowing in order to increase steam production, save steam from being used in soot-blowers, and hence, increase overall boiler efficiency.

The temperature profile of a fouled/slagged superheater tube is illustrated in Fig. 32. The curve shows a qualitative profile, and not computed or measured values. The steam temperature inside the superheater tube for typical PF systems is in the range of 400–650 °C depending on the boiler type and the materials used. The heat transfer coefficient at the inner tube wall (number “1” in Fig. 32) is relatively high in the range of 500 < h_{i,s} < 5000 Wm^{-2}K^{-1} for steam. Even higher values are typical for liquid water with 1000 < h_{i,w} < 10000 Wm^{-2}K^{-1} or a water-steam mixture with 15000 < h_{i,w,s} < 600000 Wm^{-2}K^{-1} [35]. The outer heat transfer coefficient (number “4” in Fig. 32) depends on whether radiation is present or not, and is typically in the range of 30 < h_{o} < 100 Wm^{-2}K^{-1}. Heat transfer in the radiant section is controlled by the heat flux and flame temperature, whereas the convective heat exchange is dominated by the temperature difference between the flue gas and the water-steam-cycle. In the case of radiative heat exchangers, this implies a lowered heat transfer coefficient through deposits. The temperature profile is shifted downstream and furnace exit temperature increases. A mathematical description of the heat flux $\dot{Q}$ from the flue gas to the water-steam cycle is given in Eq. (37):

$$\dot{Q} = \frac{T_\infty - T_{w,s}}{k_{\text{eff}}},$$

(37)
where $T_{\infty} = T_{IC}$ and $T_{\text{water}}$ stand for the flue gas and water/steam temperature, and $R_{\text{tot}}$ is the total thermal resistance. The calculation of the thermal resistance for a tube, is given by:

$$R_{\text{tot}} = \sum_{j} \left( \frac{\tau_{j}}{k_{j}} \ln \left( \frac{\tau_{j}}{\tau_{j-1}} \right) + \frac{1}{h_{j}^\text{c} + h_{j}^\text{r}} \right)$$ \hspace{1cm} (38)

where $A$ is the surface area of the heat exchanger, $h_{j}^\text{c}$ is the heat transfer coefficient at the tube inner surface due to convection, $\tau_{1}$ and $\tau_{n}$ stand for the inner and outer tube radius, $r_{j}$ and $r_{n}$ for the inner and outer deposit layer thickness of the material $j$, $k_{j}$ is the thermal conductivity of the material $j$, and $h_{j}^\text{c}$ and $h_{j}^\text{r}$ are the heat transfer coefficient at the outer surface due to convection (index “c”) and radiation (index “r”). The sum of the thermal resistance due to conduction $\sum_{j} \tau_{j} / k_{j} \ln (\tau_{j} / \tau_{j-1})$ typically includes the heat transfer through the inner and outer steel oxide layer, the conduction through the steel itself and the deposit including an initial layer. The initial layer is often composed of condensed inorganic elements and/or fine particles. It can have a dry and powdery nature, and therefore, a high porosity. If it is composed of condensed inorganic vapors, it is often sticky. Couch [15] describes different mechanisms being responsible for the initial layer formation:

- surface attraction between fine ash and the tube,
- local eddies in finger-like/dendritic structures,
- inherent tube roughness due to oxide layer formation,
- liquid phases on the tube surface,
- thermophoresis, and
- diffusion and condensation of inorganic vapors.

The initial layer is followed by a porous layer formed by large fly ash particles. The conduction through this porous material exhibits the highest resistance and thus limits heat transfer. This can be observed by the slope in region “3” in Fig. 32. However, high uncertainties exist for the effective thermal heat conductivity in the inner layers [273]. Deposit porosity, chemistry and temperature strongly influence thermal conductivity (see Section 3.9). During deposit growth, larger particles are able to stick leading to irregular surfaces structures. As the layer grows and consolidates, the surface temperature increases towards that of local gases [15,274]. The temperature gradient inside a deposit at its outer surface can reach values in the region of 30–100 °C/mm, depending on its thermal conductivity and the local heat flux [275]. Furthermore, during operation, the temperature gradient can exceed 200 °C/min [276]. Hence, knowing the surface temperature when predicting the particle sticking behavior can be challenging. Wibberley [275] lists four requirements for deposit formation [15]:

- inorganic vapors and/or fly ash particles are able to penetrate the boundary layer of the tube or wall and get in contact,
- material adheres to the surface,
- sufficient cohesion which prevents material from detaching as a result of local turbulence, temperature changes, vibration or gravity, and
- thermal and chemical compatibility of the steel surface and the depositing material.

Fig. 33(a) illustrates the process of heat transfer from the hot flue gas to the boiler wall and the water-steam cycle. Heat is transferred by radiation and convection to the deposit surface and conducted through the deposit and the steel tube. The deposit radiation properties change during growth and thus heat transfer rates change [273]. Using a heat balance, one can obtain Eq. (39). Heat conduction is equal to the energy transferred to the deposit surface due to

\[ R_{\text{cond}} = \frac{Q_{\text{cond}}}{T_{\text{in}} - T_{\text{out}}} \]

Therefore, the total thermal resistance for a tube, is given by:

$$R_{\text{tot}} = \sum_{j} \left( \frac{\tau_{j}}{k_{j}} \ln \left( \frac{\tau_{j}}{\tau_{j-1}} \right) + \frac{1}{h_{j}^\text{c} + h_{j}^\text{r}} \right)$$ \hspace{1cm} (38)

where $A$ is the surface area of the heat exchanger, $h_{j}^\text{c}$ is the heat transfer coefficient at the tube inner surface due to convection, $\tau_{1}$ and $\tau_{n}$ stand for the inner and outer tube radius, $r_{j}$ and $r_{n}$ for the inner and outer deposit layer thickness of the material $j$, $k_{j}$ is the thermal conductivity of the material $j$, and $h_{j}^\text{c}$ and $h_{j}^\text{r}$ are the heat transfer coefficient at the outer surface due to convection (index “c”) and radiation (index “r”). The sum of the thermal resistance due to conduction $\sum_{j} \tau_{j} / k_{j} \ln (\tau_{j} / \tau_{j-1})$ typically includes the heat transfer through the inner and outer steel oxide layer, the conduction through the steel itself and the deposit including an initial layer. The initial layer is often composed of condensed inorganic elements and/or fine particles. It can have a dry and powdery nature, and therefore, a high porosity. If it is composed of condensed inorganic vapors, it is often sticky. Couch [15] describes different mechanisms being responsible for the initial layer formation:

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convection and radiation by accounting for reflected and emitted heat.

\[
Q_{\text{cond}} = Q_{\text{convection}} + Q_{\text{radiation}} - Q_{\text{reflected}} - Q_{\text{emitted}}
\]

Zbogar et al. [273] rewrite Eq. (39) with a flame emissivity equal to unity (valid for a large boiler) and assuming that heat conduction through the tube wall and the steam unity (valid for a large boiler) and assuming that heat conduction through the tube wall and the steam film is negligible. The following expression can be obtained for a cylindrical geometry:

\[
Q_{\text{cond}} = \frac{T_{\text{dep},\text{o}} - T_{\text{steel},\text{i}}}{\ln \frac{r_{\text{dep},\text{o}}}{r_{\text{steel},\text{i}}}} = h_{\text{conv}} \cdot (T_{\infty} - T_{\text{dep},\text{o}}) + \alpha_{\text{dep}} \cdot \sigma \cdot T_{\infty}^4 - \varepsilon_{\text{dep}} \cdot \sigma \cdot T_{\text{dep},\text{o}}^4
\]

where \( T_{\text{dep},\text{o}} \) and \( T_{\text{steel},\text{i}} \) are the deposit outer surface and steel tube inner surface temperatures, \( k_{\text{dep}} \) is the deposit thermal conductivity, \( \alpha_{\text{dep}} \) the absorption coefficient of the deposit layer, \( \sigma \) the Boltzmann constant, and \( \varepsilon_{\text{dep}} \) the deposit emissivity. Calculated thermal resistances for a plane boiler wall normalized to \( A = 1 \text{m}^2 \) are illustrated in Fig. 33(b). The highest thermal resistance is due to heat transfer from the flue gas to the deposit (number 4) and through the ash layer (number 3). Heat conduction through the initial layer shows a relatively low value, due to the small layer thickness, and is comparable to the resistance caused by the steel tube. The thermal resistance due to convection on the water side strongly depends on the flow characteristics in the tubes and is low compared to the resistance of the deposit and the flue gas.

Deposit formation depends on the flow characteristics, ash particle chemistry, size and temperatures as well as the plant design. Typical tube arrangements that can be found in boilers are shown in Fig. 34. Commonly, the first superheater is designed as a platen array of tubes with wide traversal pitch \( s_y \), ranging up to more than one meter \((s_y/D = 5-35)\), and a small longitudinal pitch \( s_z \) \((s_z/D = 1.2)\), where \( D \) stands again for the outer tube diameter [15,253]. This wide spacing in traversal direction is necessary in order to prevent blockage caused by ash deposition. As flue gas temperatures cool down, and thus, the threat of particle sticking decreases, the spacing can be reduced leading to an increase in heat transfer surface per unit volume. Typical values for the convective section are \( s_y/D = 1.5 \) for the traversal and \( s_z/D = 2 \) for the longitudinal pitch, respectively.

Predictions of deposit formation and growth over time are illustrated in Fig. 35(a) and (b). Wagoner and Yan [278] predicted changing deposit shape for different tube diameters, flue gas velocities, particle diameters and densities, by considering inertial impaction. The model predicts an increase in deposit layer thickness, when tube diameter decreases, and, flue gas velocity, particle diameter or density increases. The model reveals a high sensitivity towards particle diameter and velocity, and thus the particle kinetic energy. However, the deposit formation is highly over predicted. The layer formed within six hours at a tube temperature of 593 °C indicating a missing sticking criterion. Tomeczek and Wachtliak [253] conducted two-dimensional CFD simulations for different tube longitudinal pitches and particle sizes. The free-stream flue gas velocity is set to \( u_{\infty} = 8.36 \text{ m/s} \). Their study shows the influence of particle size in particular on the cylinder rear. In general, the deposit formation on the cylinder front is considerably higher compared with the cylinder rear, which agrees with observations from power stations.

The formation of ash deposits on superheater tubes and water walls is illustrated in Fig. 36. The surface temperature of a clean superheater tube, e.g. at the commissioning of a power plant, is around 0.5–10 K higher than the water-steam temperature and thus significantly lower than flue gas temperatures. Ash particles impacting on the cold surface solidify and rebound. The initial layer is formed by heterogeneous condensation [15] or the migration of small particles to the surface. Inorganic vapors cool down in the boundary layer, start to saturate, and condense either directly on the surface or to sub-micron particles which are then captured. The inner layer is rich in K/Na, S and Cl, while the outer layer is often more slag like, porous and rich in Ca, Si, Al, Fe and other elements depending strongly on what fuel is fired. The outer layer is often reported to be loosely bound and can be more easily removed by soot-blowing compared with the inner layer. This inner layer is typically white, composed of alkali- or earth alkali-compounds and tightly bound, as shown in Fig. 37(a) and (b). Fig. 37(b) shows a SEM image of a superheater deposit taken from a straw-fired grate, where the innermost layer was composed of a dense layer of K2SO4, followed by porous layer of KCl. The outer layer was similar to fly ash and sintered together. It is believed that the innermost layer is formed by deposition of KCl with subsequent sulphation [280].

---

**Fig. 34.** Tube arrangement in solid fuel fired boilers (adopted and extended from Couch [15]).
However, if KCl deposits as a condensed aerosol or as a vapor is not completely understood. The exact role of aerosols during initial layer formation is unknown. Aerosols might act as glue and probably accelerate consolidation and chemical reactions. They fill up gaps and voids, and thus, increase contact area between particles. Jensen et al. [289] studied deposition rates in straw-fired grate boilers using a deposition probe simulating superheater coils. Results are shown in Fig. 38. An increase in aerosol concentration resulted in higher deposition rates. These findings were confirmed for two different boilers. Furthermore, their study revealed that the potassium content in the raw fuel correlates well with deposition rates. Again a linear increase in deposition rate with increasing K-content in the fuel was found. Sinquefield [244] collected deposits using sub-micron particles simulating ash deposition in black liquor boilers. He found a dendritic structure composed of long chains and strings of particles growing radially outwards. The author reported sintering of particles in these chains, however there was little contact between different chains [244]. Kaufmann et al. [281] also showed the importance of aerosols during deposit formation, when firing herbaceous biomass. The authors found sub-micron particles in the deposit and explained their deposition due to thermophoresis. An overview on typical deposition rates for different fuels and firing
Tagged systems can be found in Table 7. It can be seen that most experimental studies report values around 20°C0/100 g/(m²·h). The deposition rate mainly depends on the flue gas temperature, as well as the fuel quality. Bashir et al. [284] showed that deposition rate was influenced by flue gas temperature and straw-share, while changes in probe surface temperature had no significant influence. This suggests that large particles are controlled by the gas temperature and are not affected by boundary layer effects. On the contrary, aerosol temperatures is not crucial assuming that these particles cool down in the boundary layer. Aerosol sticking seems to be independent of their temperature. However, confirmation for this behavior is needed. Weber et al. [287] reported a similar finding, where the deposition rate and thus the sticking efficiency strongly increased with increasing fly ash particle temperatures. Highest sticking efficiencies were found for a bituminous coal ash followed by sawdust and mixed wood, where lowest values are reported for low melting ashes from grain and fermentation residues. There was no relation between sticking efficiency and ash softening temperatures or calculated viscosity values found. A possible explanation could be an increased collection efficiency of a porous deposit - in the case of bituminous coal - compared with a molten layer - grain and fermentation residues - as shown in Fig. 71(a) and discussed later on. Every incoming particle is captured in a porous layer, whereas when a molten layer exists, particles travel around this smooth surface. Kupka et al. [285] found increasing deposition rates with increasing co-firing shares of sewage sludge, when fired with a bituminous coal. This was caused by the low melting ashes of sewage sludge. A high deposition rate was reported when firing RDF [286]. A relatively high carbon content in the deposit might be caused by the condensation of tars. Much lower deposition rates are reported for the initial layer formation in a bituminous coal-fired boiler [188], probably due to low quantities of aerosols and alkali vapors. Furthermore, this table indicates that CFD studies are likely to over estimate deposition rates. The time required to form an initial layer is relatively long and can take several weeks. Condensation is particularly important for lignites and biomass with high shares of organically-bound inorganics. As the layer grows, the surface temperature increases and the formation of a liquid interface starts collecting ash particles. In the next step, larger ash particles start to adhere and form a powdery deposit. Again, the thicker the layer gets, the smaller is the temperature difference between the flue gas and the deposit surface. The deposit changes the flow around the tube and therefore the impaction process. Particle impaction on the water wall is shown in the lower part of Fig. 36. It is dependent on the configuration of the tubes, i.e. whether the tubing is vertical or in a meandering pattern. There are also publications reporting a deposit growth starting at the bridge in between tubes, due to increased surface temperatures at those locations [288]. Once the deposit layer grows, it can form a molten slag layer threatening boiler operation, as shown in the bottom right corner.

Fig. 39 shows a compilation of photographs taken from various power plants [288]. Typical areas affected by ash deposition are presented. Fig. 39 shows:

a) a partially slagged water-wall and the nose of a two-pass boiler. This section, introducing a change in the flow direction (boiler nose), is particularly in danger of ash deposition. Particles cannot follow the direction of the flow and impact on the surface.

b) a critical condition in a boiler. The cross-over path is partially blocked and only a small section is left for the flue gas to enter into the second pass. The flow accelerates, potentially leading to enhanced corrosion, erosion or deposition. Deposits in this

Fig. 37. Deposit structure and chemistry over time: (a) structure of a fouled deposit from low-rank coals (see also [263,279]), and (b) deposit collected in a straw fired boiler (image taken from Hansen et al. [280]).
region are not affected by the radiation of the flame, leading to porous, sintered structures.

c) a slagged superheater, with the danger of detachment and falling deposits. Deposits in the region of radiant superheater are fused and molten depending on layer thickness and temperatures. Normally, these are removed by sootblowers.

d) and e) show pictures through a boiler opening. Opposite walls are partly slagged. Removed deposits and large fly ash particles are collected in the ash hopper. The major issue at the furnace bottom is not the deposition itself, but associated with large fused deposits falling from higher up. There are reports of falling deposits damaging tube material at the furnace bottom leading to a power plant shut down. Furthermore, large deposits can block the ash hopper.

e) so-called burner eyebrows can form in the burner mouth. Recirculation zones from swirl burners can lead to particle accumulation around the burner mouth leading to changed aerodynamics.

### 3. Ash particle and deposit properties

Deposit and ash particle properties are crucial for estimating the sticking probability, predicting deposit formation or estimating the influence of deposits on boiler efficiency. Most important characteristics are the particle/deposit viscosity, chemical composition, porosity, surface tension, density or thermal conductivity. Therefore, the following subsections summarize deposit and ash particle characteristics and provide empirical correlations for their mathematical description and estimation.

#### 3.1. Material strength

The material strength can be important for the rebound behavior of solid spheres on a heat exchanging surface [290]. Furthermore, it is known to be crucial for deposit shedding [265]. The material strength is usually governed by the yield stress $Y$, a quantity above which a material deforms irreversibly. Below this value, the material deforms elastically upon load, and once the load is removed, it retains its original shape. A typical material test yielding the stress-strain curve is the tensile test. The stress-strain curve for steel and a brittle material are illustrated in Fig. 40. The stress expressed as load per area ($N/mm^2$) is determined by measuring the force applied to a specimen. The strain is quantified by the change in length divided by the original specimen length. At a certain point, the strain-stress curve deviates from a proportional line, the so-called elastic limit. For ductile materials, e.g. structural steel, this point is determined...
easily by creeping. However, for brittle material this point is more difficult to find, typically a value of 0.1 or 0.2% strain is used. This value is often referred to as \( R_p,0.2 \) and used instead of \( Y \). The material’s elasticity (stiffness) is described by Hooke’s law, relating stress to strain. Within the proportional region, the slope of the stress-strain curve reveals the materials elasticity, referred to as Young’s modulus \( E \) and given by Eq. (41). Typically, brittle materials such as ceramics have a considerably higher Young’s modulus compared with steel. Analogously, the shear modulus \( G \) of a solid, elastic material can be determined. The shear modulus describes the deformation, which takes place when a force is applied parallel to one face of an object while the opposite face is fixed by another equal force. A further important quantity describing the response of a material is the Poisson’s ratio \( v \). It relates lateral strain to longitudinal strain.

For most materials, Poisson’s ratio will fall in the range 0–0.5 [265]. For a perfect isotropic material, Poisson’s ratio is 0.25, with most glasses and ceramics being between 0.20 and 0.25 [265,291]. For linear-elastic, homogeneous and isotropic material the following relation is valid:

\[
E = 2(1 + v) \cdot G = \frac{\sigma}{\varepsilon} = \frac{\text{stress}}{\text{strain}}
\]  
(41)

The material properties \( Y, v \) and \( E \) are well documented for steel and other materials at room temperature. A compilation of typical values is given in Table 8. Even though values have been quantified for ash particles [296], glass or minerals such as quartz or mullite, the variation among reported values can be high and temperature dependence is often unknown. Fig. 41 shows Young’s modulus as a function of temperature for different materials. Most of the measurements are conducted for temperatures below 1000 °C and with increasing temperature, a decrease in Young’s modulus is observed, except for vitreous SiO2 [294]. However, it is mentioned that a decrease is expected at higher temperatures. The lower curve shows values for soda-lime glass measured by Marx and Sivertsen [292]. Data is extrapolated towards the melting temperature determined either with an ash melting microscope or predicted using thermodynamic equilibrium calculations. Uncertainty in this region is high. The Poisson’s ratio is often reported to slightly increase with temperature, but again literature is not consistent and materials behave differently. Furthermore, particle structures vary significantly and material properties for structures such as agglomerates are difficult to determine. Therefore, it is doubtful that temperature-dependent data for various ash particle compositions and structures can be found. Ai and Kuhlmann [297] used the following temperature-dependent relation

\[
E(T) = a \cdot \exp(-b \cdot T),
\]  
(42)
where a and b are fitting parameters. They used deposition experiments for coal fly ash particles of different size, in order to fit coefficients a and b for the prediction of Young’s modulus. However, it is questionable if results are applicable for other experiments, and the influence of chemistry is missing. Here more effort for temperature- and composition-dependent correlations is needed, similar to work of Roberts and Garboczi [298], who presented a model for elastic constants as a function of porosity.

### 3.2. Melt fraction

The melt fraction is often used to describe the stickiness of ash particles, or the flow behavior of slags, in entrained flow gasifiers. The melt fraction $f_p$ of ash particles is the total mass of liquid phases or components within an ash particle or, more general, in a system, relative to the overall mass. It is usually defined by weight, and can take values from zero to unity, according to the following equation:

$$f_p = \frac{m_{p,\text{liquid}}}{m_{p,\text{liquid}} + m_{p,\text{solid}}},$$

where $m_{p,\text{liquid}}$ and $m_{p,\text{solid}}$ are the liquid and solid particle mass, respectively. A method measuring the melt fraction is the differential scanning calorimetry (DSC). This data is derived from simultaneous thermal analysis (STA), where the temperature and mass change of a sample to an inert reference sample is continuously recorded during constant heating. The signal is shown in a DSC-temperature plot of an ash sample. The irregular shape or peaks of the signal identifies endothermic melting events, reactions or phase transitions, while sample mass remains constant. Changes in sample mass usually indicate thermal decomposition and release of gases or chemical reactions with the surrounding gas. By assuming, that the melt fraction is proportional to the area of the DSC signal over temperature, the following equation can be used to interpret the melt fraction:

$$f_p(T) = \frac{A(T)}{A_{\text{tot}}},$$

where $A$ is the area underneath the measured curve to a certain temperature (shown in Fig. 42) and $A_{\text{tot}}$ the total area. The above equation leads to a continuous melting curve as shown in the melt fraction-temperature plot in the bottom illustration of Fig. 42. Limitations of this method are as follows: (1) simultaneous evaporation processes or reactions can only be distinguished from melting processes with additional methods; (2) individual fusion enthalpies can differ significantly and are not taken into account; (3) the method can only be applied to bulk ash and not to single particles. The latter is crucial, since the chemical composition of individual ash particles can vary significantly from the bulk ash. The melt fraction can also be determined by thermo-mechanical analysis (TMA), where the shrinkage of a sample is measured during heating (see e.g. [400–402,405]). This method was developed as an alternative to ash fusion tests at the University of Newcastle. It yields sensitive shrinkage measurements correlating with the formation of liquid phases. The method is applied for various purposes including characterization and extent of slagging [401], determination of slag viscosity [404], or deposit structure [403].

![DSC signal](image1.png)

**Fig. 41.** Young’s modulus as a function of temperature. Data collected from various references including [292–295].

![DSC signal](image2.png)

**Fig. 42.** Calculation of a melting curve from STA data (adopted from Hansen et al. [87]).
or influences from other reactions. To understand the single mechanisms thermodynamic equilibrium calculations (TEC) are often used to predict stable phases in dependence of different parameters, e.g. composition, temperature, or atmosphere. The thermodynamic equilibrium is based on the minimization of the Gibbs enthalpy, which is implemented in various commercial software codes, such as FactSage thermochemical software and databases [306] or ChemApp [307]. The results are plotted in so-called phase diagrams. An example is shown in Fig. 44, for the binary system KCl-K2SO4. The solid black lines denote phase transitions. The blue dashed line shows exemplarily a system of constant composition of KCl and K2SO4 which is heated from 500 to 900 °C. After exceeding the temperature at point 3, the first liquid phase occurs, but K2SO4 is still in the solid phase. Exceeding 850 °C at point 2, the solid phase K2SO4 gets liquefied. Both components (KCl and K2SO4) are entirely in the liquid phase at point 1. When evaluating results it is important to consider that the thermodynamic equilibrium represent an ideal stable state after infinite time. Reaction rates or catalytic effects cannot be included.

A comparison of STA measurements and results from the phase diagram is shown in Fig. 43. Results are presented for the vertical blue line in Fig. 44 using a system composed of 15 mol.% KCl and 85 mol.% K2SO4. Hansen et al. [87] conducted STA measurements for different binary salt mixtures, as well as for straw and coal ashes. Salt mixtures show a good repeatability; the melting onset is determined within 10 °C and the melt fractions at a given temperature within 10% when compared with phase diagrams. Ash samples showed lower melting temperatures, between 50 and 100 °C when compared with the ash fusion test results [87]. The authors suggest to use CCEM results to identify individual melting events recorded in the STA curve. A more complex ternary phase diagram for K2O-CaO-SiO2, can be seen in Fig. 45. This figure can explain the troubling behavior of straw ash compared with wood ash. Straw ash particles are typically composed of K-silicates, having an eutectic melting temperature as low as 750 °C, at a mixture of 70 wt.% SiO2 and 30 wt.% K2O. On the contrary, Ca-rich particles have melting temperatures above 1500 °C (not shown for pure CaO) and thus a low stickiness and adhesiveness. In real combustion systems, particles are compounds of even more than three species and equilibrium is not reached due to small time scales complicating the application of phase diagrams. Nevertheless, they can be a useful indicator explaining certain ash behavior. Another application was presented by Jak [310]. The author used thermodynamic equilibrium calculations in order to predict the ash melting behavior. Results are calculated for Al-Ca-Fe-O-Si systems, and compared with ash fusion test results. Results show good agreement underlining the capability of theoretical predictions. Masiá et al. [311] studied biomass and waste ashes using leaching methods, STA and thermodynamic equilibrium calculations. STA measurements did not prove to be suitable for their ashes. In contrast, equilibrium calculations showed good results and are recommend by the authors for the determination of the melt fraction. Wieland et al. [312] found that the predictions from STA are shifted towards higher temperatures, compared to results from thermodynamic equilibrium calculations. Differences are explained by heat transfer limitations and reaction kinetics. Babat et al. [186] explained iron-rich deposits collected in a full-scale power station using thermodynamic equilibrium calculations. The authors could show that pyrite forms low melting eutectics in reducing conditions, where melting starts at temperatures as low as 950 °C. In general, TEC or STA methods provide useful information on the melting behavior of ashes, however they have to be applied with care. For predictions using TEC, databases have to be selected, which are not fully available for the vast set of ash chemistry systems, in particular for biomass or waste ashes. Furthermore, these predictions assume infinite time and kinetics of chemical transformations cannot be
considered. Kinetics are known to be important for instance for relatively slow pyrite transformation.

3.3. Viscosity

The dynamic viscosity \( \mu \) (sometimes \( \eta \) is used instead) of ashes or slags is frequently applied in modeling studies. Sticking criteria are often based on particle viscosity, and flow behavior of slags in entrained flow gasifiers is mainly described by its viscosity. Typical slag flow is occurring when the dynamic viscosity is in the range of \( \mu_{\text{slag}} = 15\text{–}25\text{ Pa}\cdot\text{s} \), at temperatures of around 1400–1500°C, depending on the fuel and ash composition [313]. At these temperatures, slag can be described as a Newtonian fluid, where viscous stresses are linearly proportional to strain rates. However, once the slag cools down, crystals can form in the melt, and the slag can no longer be treated in such a way. This transition point is often defined as the critical viscosity temperature \( T_{\text{cv}} \), and is shown in Fig. 46. The temperature viscosity curve changes abruptly at \( T_{\text{cv}} \) [323]. This temperature is time dependent and strongly affected by the crystal formation rate and thus, there might be no single value. Instead, the temperature of critical viscosity can change over time. Nevertheless, attempts were made for an estimation. In order to find viscosity values, empirical relations were developed, relating slag composition and temperature to measured viscosity values [314]. Nicholls and Reid [315] were the first to observe that at a given viscosity the gradient of the viscosity-temperature curve is similar for all coal ash slags within the Newtonian region. This behavior is expressed by the following equation [314]:

\[
\frac{d\mu}{dT} \neq f(\mu) \neq f(T)
\]

Eq. (45) implies, that if viscosity curves can be moved horizontally in a \( \mu - T \) plot, they will all overlap. This temperature shift is the principle of many empirical models. These models describe the viscosity in the form of an Arrhenius-type (AT) equation, by:

\[
\log \mu = \frac{A}{T - T_0} + B
\]

or \( \log \mu = A + \frac{B}{T} \) (46)

where \( A \) and \( B \) are constants, and, \( T_0 \) is a temperature correction parameter. This relationship is often used to describe viscosity at high temperatures in the range of \( 10^2\text{–}10^3\text{ Pa}\cdot\text{s} \) [316]. Another commonly used type of equation for the prediction of slag viscosity is the Weymann-type (WT) equation [317] given by:

\[
\mu = a \cdot T \cdot e^{1000 \cdot b/T},
\]

where \( a \) and \( b \) are composition-dependent fitting parameters. Eqs. (46) and (47) are commonly used and fitted to a set of slag compositions and temperature-viscosity measurements. Browning et al. [314] give a brief overview on advances in describing slag viscosity by empirical equations. Another good review is provided by Vargas et al. [323]. Table 9 shows a selection of viscosity models, available in literature. There are more models available, in particular in the glass industry or vulcanology. Mathematical descriptions of the models can be found in the Appendix A. Early models, such as the one by Watt and Fereday [319] or the S\(^2\)-correlation, were developed for British coals with a limited range of application (only valid for a certain range of Si and Fe content, as shown in Table 9). A widely used model considering different elements and their role in the melt was proposed by Urbain [321]. They used the analogy of slag and glass melts. They fitted viscosity measurements of different SiO\(_2\)-Al\(_2\)O\(_3\)-CaO-MgO systems to the Weymann-type equation [314,321]. Kalmanovitch and Frank [322] re-evaluated the data of Urbain [321], and modified their equations for improved accuracy. They included all major ash forming elements into the proposed equations, calculating the coefficients \( a \) and \( b \). But still, the range of applicability was limited to high temperatures, with viscosity values \( \mu < 10^3\text{ Pa}\cdot\text{s} \). Senior and Srinivasachar [316] examined many different glass compositions at lower temperatures, and found a change in the slope at approximately \( 10^3\text{ Pa}\cdot\text{s} \). Fig. 46 compares different slag viscosity measurements for two coal ashes with high silica content [Reid and Cohen [324] - glassy coal ash slags with SiO\(_2\) \( \approx 57\text{ wt.\%} \), and Ob et al. [325] - Suco coal ash with SiO\(_2\) \( \approx 60\text{ wt.\%} \), and three other coal ashes with medium SiO\(_2\) content (Pittsb. #8, Shenfu, Boadian, with SiO\(_2\) \( < 50\text{ wt.\%} \)). The glassy slags do not show a change in slope at given temperatures. It is assumed that the change will occur at lower temperatures, as mentioned by Senior and Srinivasachar when \( \mu = 10^4\text{ Pa}\cdot\text{s} \). The three other coal ashes with low silica content show a steep increase in the \( d\mu/dT \)-slope at around \( 10\text{–}20\text{ Pa}\cdot\text{s} \), which is considerably lower than those of glassy slags. The slope parameter \( B \) in Eq. (46) increases from around \( B = 1.1 \) to \( B = 6.4 \). All coals show a similar slope in the low- and high-temperature regime, underlining the validity of Eq. (45). Often, the change in slope is referred to as the critical temperature \( T_{\text{cv}} \). Different approaches have been used to predict the critical temperature. Sage and McIlroy

![Fig. 46. Comparison of measured slag viscosities from various literature references [324,325,333]. Two types of coal slags are compared, Si-rich (glass type) and slags with medium Si-content. A change in the slope can be observed for the latter class at lower temperatures.](image-url)

**Table 9** Comparison of different viscosity models for molten silicates and their range of validity (data summarized from various references).

<table>
<thead>
<tr>
<th>Model</th>
<th>Species considered</th>
<th>Notes, comments and range of validity</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reid and Cohen [318]</td>
<td>Si, Fe, Ca, Mg</td>
<td>alkali metals not considered</td>
</tr>
<tr>
<td>S(^2)-correlation [313]</td>
<td>AT Si, Fe, Ca, Mg</td>
<td>Si &lt; 55% and Fe &lt; 5% (^a)</td>
</tr>
<tr>
<td>Watt and Fereday [319]</td>
<td>AT Si, Al, Fe, Ca</td>
<td>Si &gt; 80% and Fe &gt; 15% (^a)</td>
</tr>
<tr>
<td>Bottinga and Weill [320]</td>
<td>a large number of compounds (^d)</td>
<td>varying constants for different ( T ) and SiO(_2)-contents</td>
</tr>
<tr>
<td>Urbain [321]</td>
<td>Si, Al, Ca</td>
<td>high temp. ( &lt; 10^8\text{ Pa}\cdot\text{s} ) extension of Urbain et al. for more elements</td>
</tr>
<tr>
<td>Kalmanovitch and Frank [322]</td>
<td>AT all major oxides (^d)</td>
<td>glass ash particles at ( 10^8\text{–}10^9\text{ Pa}\cdot\text{s} )</td>
</tr>
<tr>
<td>Senior and Srinivasachar (^b) [316]</td>
<td>AT all major oxides (^d)</td>
<td>wide range of SiO(_2), Al(_2)O(_3), FeO</td>
</tr>
<tr>
<td>Browning et al. [314]</td>
<td>AT all major elements (^b), (^d)</td>
<td></td>
</tr>
</tbody>
</table>

\(^a\) greater accuracy in this range.

\(^b\) has a low-temperature region for crystal formation.

\(^c\) of Si, Al, Fe, Ca, Mg, Na, K, Ti, Mn, Sr, Ba, Li and Al-compounds.

\(^d\) of Si, Al, Fe, Ca, Mg, Na, K, Ti.
related the hemispherical temperature from the fusion test to the critical viscosity. Song et al. [327] showed that the critical temperature correlates well with the liquidus temperatures, predicted using FactSage, for a large number of synthetic slags. The concept of low- and high-temperature regions is used by Senior and Srinivasachar [316] in their empirical model. The model concept is based on the network structure of silicate melts. These melts can be described as polymers consisting of a basic building block, the SiO\textsubscript{2} ion. Silicon and oxygen have a strong covalent bonding forming a glassy silica network, which can accommodate different cations. Senior and Srinivasachar [316] define three different categories, interacting within the network:

- glass formers (Si\textsuperscript{4+}, Ti\textsuperscript{4+}, P\textsuperscript{5+}),
- modifiers (Ca\textsuperscript{2+}, Mg\textsuperscript{2+}, Fe\textsuperscript{2+}, K\textsuperscript{+}, Na\textsuperscript{+}), and
- amphoteric (Al\textsuperscript{3+}, Fe\textsuperscript{3+}, B\textsuperscript{3+}).

The elements Ti\textsuperscript{4+} and P\textsuperscript{5+} can also act as glass formers, similar to Si\textsuperscript{4+}. Modifier ions lead to a lowered viscosity by disrupting the glass structure. The last group can act as a glass former in combination with a modifier ion by balancing their charge and thus forming a stable metal oxygen anion group fitting into the silicate network [316]. However, when modifier ions are missing in the mixture, amphoteric cations can act as modifiers themselves. This behavior of the elements is often used in the glass industry or for example by Senior and Srinivasachar in order to develop a model for the viscosity of coal ash particles. Their goal is to provide a model being able to predict the ash particle viscosity, based on ash composition for a wide range of temperatures. This region includes the beginning of particle sticking at around $\mu = 10^4$–$10^5$ Pa·s [316]. Therefore, they used a high- and low-temperature regime in which the $du/dT$-slope changes. In contrast, the majority of viscosity models only focuses on the region of high temperatures, in which the slag acts as a Newtonian fluid. However, at lower temperatures, crystals may form in the melt, leading to a sharp increase in viscosity as shown by Fig. 46 [106]. A compilation of ash particle viscosities for different fuel ashes and chemical compositions can be seen in Fig. 47(a). The measured viscosity ranges over a wide span from $10^{-3}$ for liquid salts to $10^5$ Pa·s for coal slags and glasses. The lowest values are observed for salts even at temperatures as low as 800°C. High viscosity values can be found at low temperatures, e.g. for glassy slags, but also at high temperatures as soon as crystals form in the melt. In general the viscosity of ash particles from straw combustion exhibit lowest values followed by woody ash and coals. However, variations in chemistry among different ash particles within one sample can lead to a different order.

Browning et al. [314] recently published an interesting approach, in which they investigated 1715 data points of 117 slag compositions, and developed an empirical equation similar to Eq. (45). The temperature shift is calculated composition-dependent and is given in Appendix A. The authors suggest that potassium acts as a network former, unlike Urbain [321], who counted K\textsuperscript{+} to the network modifiers. The reason why potassium increases the viscosity is its effect on the amphoteric aluminum oxide in the slag. They further state that the model is not valid for alumina-free samples containing K\textsubscript{2}O [314]. A comparison of models and measured viscosities is shown in Fig. 47. The best agreement for the high-temperature regime is achieved with the correlation suggested by Browning et al. [314]. Viscosity models not shown in Fig. 47 showed larger deviations. None of the models is able to predict the changing slope at lower temperatures. It is concluded that viscosity can be predicted relatively well in the region of high temperatures for typical coal slags. However, predicting ash particle viscosity at lower temperatures and with a highly variable composition is still challenging. The model of Senior and Srinivasachar [316] is validated for glassy slags containing modifiers. However, if particles have no modifiers or high Fe or Ca contents in the absence of Si, the correlation might yield unsatisfying results. Nevertheless, this model is the only available one in literature being capable of predicting the viscosity at lower temperatures of 800–1300°C, which are typical for ash particle deposition in a boiler.

In general, there is a need for better viscosity models in particular for Ca-rich or salt-rich ashes - typical for biofuels. Vargas et al. [323] compared viscosity models and their predictive capabilities with a number of viscosity measurements mainly for silicates. Best performance was attributed to the model of Bottinga and Weill [320]. Another model showing good agreement with measurements, is the model of Browning et al. [314]. However, both are only valid for silicates in a certain range of composition and in the Newtonian region at high temperatures. Therefore, more fundamental work should be directed towards models for biomass ashes and for lower temperatures.

A method considering the formation of crystals in the melt, and their influence on the viscosity, was presented by a number of studies. Vargas et al. [323] present an overview on models relating the solid fraction of crystals in the melt to the viscosity of the mixture.
The models differ in their complexity - all models consider the amount of crystals and some can consider the crystal shape. Vargas et al. [323] describes two classes, models for dilute suspensions with mostly spherical crystals such as the work of Einstein [334], Vand [335], Sherman [336], Roscoe [337], and models for dense slurries, e.g. Quemada [338]. A validation of these models is beyond the scope of this work, however, data of Oh et al. [325] is used to compare model predictions. Therefore, the viscosity of the melt is predicted using the composition of the Pittsburgh #8 ash and a fit of the model of Browning et al. [314]. The measurements and predictions are shown in Fig. 48(a) as points and dashed line, respectively. Relatively good agreement is observed at high temperatures. With decreasing temperature, a sharp increase of the measured viscosity is observed at around 1270 °C due to crystal formation. The fraction of crystals (solids) in the melt is determined using thermodynamic equilibrium calculations (FactSage and the FToxide database [306]). The blue curve shows the fraction of solids as a function of temperature. First crystals are predicted at around 1650 °C. A significant increase in the solid fraction is observed at around 1350 °C. The third curve (continuous line) in Fig. 48(a) shows the predicted viscosity of the solid-liquid mixture following a model suggested by Vand [335]:

$$\mu_{\text{mix}} = \mu_{\text{liq}} \cdot \left[1 + c \cdot \left(1 - f_p\right) + d \cdot \left(1 - f_p\right)^2\right],$$  \hspace{1cm} (48)

where \(\mu_{\text{liq}}\) is the viscosity of the liquid phase and \(f_p\) is the fraction of molten material within a particle or a slag sample. The solid fraction is accordingly obtained by \(1 - f_p\). The coefficients \(c\) and \(d\) are assumed to equal \(c = 2.5\) and \(d = 9.15\) [325,339]. A further model yielding good results is presented by Roscoe [337]. Equations are based on the work of Einstein [334]:

$$\mu_{\text{mix}} = \mu_{\text{liq}} \cdot \left[1 - c \cdot \left(1 - f_p\right)\right]^{-5/2},$$  \hspace{1cm} (49)

where the coefficient \(c\) is set to \(c = 1.35\). In general, all these models require the fraction of crystals in the melt and therefore additional effort.

### 3.4. Rheology

The fluid flow behavior, often referred to as rheological behavior, of coal ashes and/or slags is complex and controversial. Fluids are classified as time-independent fluids or time-dependent fluids. Both are illustrated in Fig. 49. The most common time-independent fluid is a Newtonian fluid describing most gases and liquids. Viscosity is expressed as the ratio of shear stress to shear rate. Pseudoplastic fluid, often called shear-thinning material, shows a decrease in viscosity with increasing rate of deformation. The fluid is termed plastic, if this effect is very strong. Typical examples are polymeric
solutions or melts [323]. The opposite behavior is rarely observed. It is termed dilatant or shear-thickening. Bingham plastics are fluids which require a finite deformation to initiate flow, e.g., tooth paste. Time-dependent fluids exhibit a changing shear stress with duration of shear [323]. Thixotropic fluids have a decreasing viscosity with time of shear, thus a time-dependent shear-thinning. This decrease in viscosity is often caused by structural changes or breakdown in the fluid. The behavior is shown in Fig. 49(b), where the shear rate is steadily increased at a constant rate to a maximum value and then decreased to zero. During the decrease a lower shear stress is observed yielding a typical hysteresis curve. Paints, ink or mayonnaise behave this way. Again, the opposite behavior, so-called rheoplectic fluid, is rarely observed. A special form of time-dependent fluids are viscoelastic materials. They behave as both, viscous fluids and elastic solids. The elasticity is typically a result of bond stretching along crystallographic planes, whereas the viscosity is due to diffusion of atoms or molecules inside an amorphous material [340]. Viscoelastic materials have a characteristic time constant called relaxation time. If deformation takes places during longer periods than this relaxation time, the material behaves as a viscous fluid. Within shorter periods, the material is deformed and recovers to its original shape after deformation [341]. Losurdo et al. [342] used viscous models to describe ash behavior. This is an interesting approach, however experimental confirmation for this behavior is still due.

The actual behavior of ash particles or slags is rarely studied. Typically, viscosity curves are measured and described with empirical equations. Song et al. [343] investigated the equation of crystalline phases during cooling. Vargas et al. [323] observe yielding a typical hysteresis curve. Paints, ink or mayonnaise give composition-dependent values for \(\gamma_p\) where values for \(\gamma_p\) can be taken from Table 10. Mills and Rhine [345] give composition-dependent values for \(\gamma_p\) presenting probably the best available data set for coal ash slags. Typical values for ashes range from around \(\gamma_p \approx 0.05\text{ N/m}\) for low viscosity ashes such as salt particles up to values around \(\gamma_p \approx 0.6\text{ N/m}\) for aluminosilicates (Al-Si).

### 3.6. Contact angle with the substrate

The contact angle \(\Theta_c\) of a liquid droplet with a substrate is illustrated in Fig. 50. The contact angle and the so-called wetting, i.e., the area that is covered with the liquid, strongly depend on the liquid and its surface tension, as well as on the substrate's surface energy and morphology. Small contact angles \(\Theta \leq 90^\circ\) correspond to a high wettability, low surface tension of the droplet, a good adhesiveness and high solid surface free energy [346,347]. The contact angle can be described mathematically using Young’s equation [348]:

\[
\gamma_{SV} = \gamma_{SL} + \gamma_{LV} \cdot \cos(\Theta),
\]

where \(\gamma_{SV}\), \(\gamma_{SL}\) and \(\gamma_{LV}\) are the solid-vapor, solid-liquid and liquid-vapor surface tension. All three interfacial tensions act as forces on the droplet, and the contact angle forms under mechanical equilibrium for an ideal surface [347]. In reality, this equilibrium is often not observed, instead the contact line is always moving, leading to a dynamic contact angle [347]. Often the liquid–vapor and solid–vapor surface tension is approximated with the droplet’s and substrate’s surface tension and free energy, respectively. Another method relates the contact angle to the surface tension of a droplet \(\gamma_p\) and the work of adhesion following the Young–Dupré equation:

\[
\gamma_p \cdot (1 + \cos(\Theta)) = W_{ad}/A,
\]

where \(W_{ad}\) is the work of adhesion and \(A\) the contact area between the droplet and the substrate. Since surface tension and viscosity values of molten ash particles are fairly high compared with e.g., water droplets, the contact angle of ash droplets on steel tubes or ceramics show typically high values. The contact angle measurement is a challenging task, in particular for ash particles since they require high temperatures in order to become liquid. One technique is the so-called Moza-Austin sticking test [349]. A pellet of mineral or ash is formed, and held in the center of a ring burner flame, until it melts and falls onto a pretreated steel specimen (typically oxidized), maintained at a certain temperature relevant for heat exchangers. The contact angle of the solidified droplet was determined optically, and the adhesion force determined by shearing the droplet off the surface [349]. By using this method, realistic values for supercooled surfaces are obtained, which differ from equilibrium contact angles. Heat exchangers are typically much colder compared with ash melting temperatures. Therefore, heat transfer and cooling affect the contact angle of ash particles with the surface. Ni et al. [333] used a Boltzmann-type equation, and fitted measurements of Abbott and Austin [350], in the form of:

\[
\Theta_c = A + |B - A|/(1 + \exp[(T - C)/D]),
\]

#### 3.5. Surface tension

The surface tension \(\gamma\) (in N/m) is typically used in particle deformation calculations, such as droplet impaction on a surface in internal combustion engines. In some publications it is defined as the variable \(\sigma\). Generally, the higher the surface tension is, the stronger are the forces to reduce the surface area of a droplet. Surface tension can be estimated using the composition-dependent relation [273],

\[
\gamma = \sum_{i=1}^{N} (x_i \cdot \gamma_i),
\]

where \(\gamma_i\) and \(x_i\) are the surface tension and molar fraction of species “i”. A linear temperature dependency is proposed in literature [344]:

\[
\gamma_i = \gamma_{i,1300°C} + \frac{0.0044}{1000} \cdot \Delta T,
\]

where values for \(\gamma_{i,1300°C}\) can be taken from Table 10. Mills and Rhine [345] give composition-dependent values for \(\gamma_p\) presenting probably the best available data set for coal ash slags. Typical

<table>
<thead>
<tr>
<th>Ash Oxide</th>
<th>(V_i) in m³/kmol</th>
<th>(\gamma_{1300°C}) in N/m²</th>
</tr>
</thead>
<tbody>
<tr>
<td>Al₂O₃</td>
<td>28.31 + 32 (x_{Al,0i}) - 31.45 (x_{Al,0i}) [345]</td>
<td>0.58 [357]</td>
</tr>
<tr>
<td>CaO</td>
<td>16.5 [351]</td>
<td>0.51 [357]</td>
</tr>
<tr>
<td>Fe₂O₃</td>
<td>38.4 [345]</td>
<td>-</td>
</tr>
<tr>
<td>K₂O</td>
<td>46.0 [353]</td>
<td>0.01 [357]</td>
</tr>
<tr>
<td>MgO</td>
<td>11.6 [353]</td>
<td>0.52 [357]</td>
</tr>
<tr>
<td>Na₂O</td>
<td>28.9 [351]</td>
<td>0.295 [357]</td>
</tr>
<tr>
<td>P₂O₅</td>
<td>65.7 [345]</td>
<td>-</td>
</tr>
<tr>
<td>SiO₂</td>
<td>19.55 + 7.966 (x_{SiO}) [345]</td>
<td>0.29 [357]</td>
</tr>
<tr>
<td>SO₃</td>
<td>4.04 [353]</td>
<td>-</td>
</tr>
<tr>
<td>TiO₂</td>
<td>24.0 [345]</td>
<td>0.25 [357]</td>
</tr>
</tbody>
</table>
where constants were determined to $A = 100$, $B = 150$, $C = 445$ and $D = 35$ to reproduce measurements from Abbott et al. [351] shown in Fig. 51 and $T$ is the substrate temperature. Abbott et al. [351] measured the contact angle and adhesive force of synthetic ash mixtures, on a preoxidized carbon steel, maintained at temperatures up to 700 °C. It can be seen that the contact angle decreases with increasing substrate temperature. The droplet cools slower upon contact and thus plastic deformation is increased due to lower viscosity values. The adhesive force increases rapidly with increasing substrate temperature, showing a higher connectivity, which can explain accelerated deposit formation at higher steel temperatures. Similar tests were conducted using pyrite, pyrite-quartz, pyrite-kaolinite and pyrite-illite mixtures [350]. Considerably lower contact angles down to 50° with high adhesive forces were observed in the case of pyrite-illite mixtures. Probably caused by a low melting eutectic.

Another method for determining the contact angle is the capillary bridge method developed by Restagno et al. [352]. This method puts a spherical solid surface in contact with a liquid, as illustrated in Fig. 52. The contact angle can be approximated by the following relation:

$$A = 2 \cdot \pi \cdot d_p / 2 \cdot (k^{-1} \cdot \sqrt{2(1 + \cos(\Theta_c)} - h), \quad (55)$$

where $A$ represents the wetted area, $h$ is the distance between the particle and the surface from the liquid bath, and $k^{-1}$ is the capillary length, which is known for common liquids [347]. The area $A$ strongly depends on the distance $h$. This method has some similarities compared with solid ash particles impacting a molten, slagged surface. The area $A$, which is a function of geometry and liquid properties can be used to estimate adhesive forces preventing the particle from rebound. However, further research in this area is needed.

### 3.7. Density

The density of a deposit or a slag layer depends on porosity and chemical composition, where the following equation relates the true/solid density $\rho_{dep,\text{true}}$ to the apparent density $\rho_{dep,\text{app}}$:

$$\rho_{dep,\text{app}} = \rho_{dep,\text{true}} \cdot (1 - \rho_{\text{dep}}). \quad (56)$$

A simple estimation of the true density can be achieved by using the empirical correlation $\rho_{dep,\text{true}} = 2.54 + 0.00978 \cdot w_{Fe_2O_3}$ in g/cm$^3$, where $w_{Fe_2O_3}$ is the mass fraction of Fe$_2$O$_3$. A more sophisticated approach was developed for slags and uses the method of partial molar densities [345,353],

$$\rho_{dep,\text{true}} = \sum_{i=1}^{N} x_i \cdot M_i / V_i. \quad (57)$$

where $V_i$ is the partial molar volume, $x_i$ is the molar fraction and $M_i$ is the molar mass of species “$i$”. Values for the partial molar volumes can be taken from Table 10. Temperature-dependent density changes are small and often neglected.

### 3.8. Sintering and fusion

Measurements on the sintering behavior of ash deposits are rare. Models are mainly developed for metal powders such as the one presented by Mackenzie and Shuttleworth [354]. They developed a sintering model for viscous flow sintering, similar to the following...
equation [355],
\[ p_{\text{dep}}(t) = p_{\text{dep},0} \cdot \exp\left( -\frac{3 \cdot \gamma \cdot t}{d_p \cdot \mu \cdot x} \right), \tag{58} \]
where \( p_{\text{dep},0} \) is the initial deposit porosity, \( d_p \) is the average pore size (average particle size is used in this work), and \( x \) is an added fitting parameter. Fig. 53 shows the calculated sintering behavior of a Pittsburgh #8 ash. An initial porosity of \( p_{\text{dep},0} = 0.5 \) and a fitting parameter of \( x = 1000 \) are assumed to calculate sintering for different temperatures. It can be seen that sintering starts at around 1100 °C. Without the fitting parameter, sintering to \( p_{\text{dep}} = 0 \) would occur within seconds for a temperature of 1100 °C. Meinel [356] used a similar value to fit his results. Generally, a slight increase in temperature leads to a strong decrease in porosity. Eq. (58) depends on deposit viscosity, which is a strong function of temperature. The calculations shown in Fig. 53 are carried out for viscosity measurements of the Pittsburgh #8 ash (see Fig. 46). The surface tension of ash particles is calculated based on Eqs. (50) and (51). Gupta et al. [357] reported the same temperature range in which sintering is observed (900–1200 °C). The presented equations can also be used to describe melting by adjusting the parameter \( x \). Another type of sintering, besides sintering due to viscous forces, is caused by chemical reactions, as described in Section 2.5.4. Typical reactions leading to a decrease in porosity can be carbonization or sulfation [31].

3.9. Thermal conductivity and radiative properties

Thermal conductivity and radiative properties of deposits define the temperature profile in the deposit and thus, heat transfer to the water-steam cycle as illustrated in Fig. 32. Therefore, these parameters are of importance not only for modeling studies, but also for boiler operation. Heat transfer through the deposit is often expressed by an effective thermal heat conductivity, \( k_{\text{eff}} \) that combines heat conduction and radiation which might occur in parallel or in series [273]. Radiation increases the heat conductivity through a porous deposit by penetrating the inside structure and absorption of radiation. Heat conduction through a deposit can then be expressed as one-dimensional, transient heat transfer through a cylindrical shell by:

\[ \rho_{\text{dep}} \cdot c_{p,\text{dep}} \cdot \frac{\partial T}{\partial t} = k_{\text{eff}} \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \theta^2} \right) \tag{59} \]

This equation considers the temperature change as a function of time \( t \) and radial direction \( r \), where \( \rho_{\text{dep}} \) is the deposit density, and \( c_{p,\text{dep}} \) is the deposit heat capacity. This equation can be solved analytically by ignoring the transient term to [32]:

\[ T(r,t) = T_i - \frac{q}{k_{\text{eff}}} \ln \left( \frac{r}{r_i} \right), \tag{60} \]

where \( q \) is the surface heat flux and the index “i” denotes the deposit inner surface. Using this equation, the steady-state temperature profile in a deposit layer can be calculated with the surface heat flux and effective thermal conductivity. The effective thermal conductivity is mainly dependent on deposit characteristics such as:

- porosity and degree of sintering,
- temperature of the deposit,
- particle size,
- chemical composition, and
- radiative properties.

The deposit porosity \( p_{\text{dep}} \) has the strongest impact on the thermal conductivity. A decrease in porosity leads to an increase in the effective thermal conductivity, and enhances heat transfer. Robinson et al. [358] found that the initial layer has a relatively low thermal conductivity due to its particulate structure and relatively high porosity. However, in the case of biomass, this layer can consist of condensates and therefore have a molten, dense structure and high conductivity. Outer layers show a sintered structure with strongly increased thermal conductivities. Fig. 54(a) shows measurements of deposit thermal conductivity with varying porosity values. Rezaei et al. [246] measured the thermal conductivity for a set of different coal ashes. The thermal conductivity strongly depends on the deposit type. It decreases in the order of: powdery > particulate > sintered > molten type of deposit. Typical values range from 0.1 for molten deposit with gas inclusions, up to 0.9 for a loosely-bound, powdery deposit layers [358–360]. The porosity is reduced with time due to sintering. This causes a densification of the deposit, and thus, an irreversible increase in effective thermal conductivity [273].

Fig. 54(b) shows the influence of temperature on measured thermal conductivities. As a general rule, a slight increase in thermal conductivity with increasing temperature, can be observed. Rezaei et al. [246] found that the change in thermal conductivity, is more pronounced at higher temperatures. They explain this behavior by sintering. Above temperatures of 600–800 °C sintering occurs, leading to an irreversible change in morphology and thereby a change in deposit thermal conductivity. Gupta et al. [357] found coal ash sintering between 900 and 1200 °C. This change in structure and particle connectivity leads to a higher thermal conductivity during the cooling of the sample, as shown in Fig. 54(b). A description of the measurement device can be found in the work of Rezaei et al. [246]. Anderson et al. [361] give another explanation for the strong increase at higher temperatures: Thermal radiation is causing an increase, at temperatures above 500 °C. Their measurements show a strong increase at around 1200 °C, which might also be due to fusion of the sample. The samples of Rezaei et al. [246] did not show a significant change in porosity after cooling. They explained the increased thermal conductivity during cooling by sintering, which caused a better connectivity between the individual particles, but only a slight change in porosity. Zbogar et al. [273] give a further explanation, based on changes in emissivity upon structural changes.

Not much literature is available on the influence of particle size on heat conductivity. Rezaei et al. [246] sieved two coal ash samples to particles smaller than \( d_p < 45 \mu \text{m} \) and between \( 45 < d_p < 106 \mu \text{m} \).
Thus, an increased thermal conductivity. This is found a lowered sintering temperature for iron-rich slags, and, small changes at identical sample porosities. But they refer to the lower thermal conductivity, compared to magnetite (Fe₂O₃). A volume-weighted correlation might be suitable to calculate the thermal conductivity of the mixture [273,362]. Wall et al. [367] state that a deposit must have a thickness of 1 mm or more in order to be considered as opaque. The influence of the chemical composition dominates the sintering and melting behavior of ash deposits and therefore also its structure and thermal conductivity. Rezaei et al. [246] found only small changes at identical sample porosities. But they refer to the glass industry, where correlations were developed yielding an equation for a composition-dependent thermal conductivity [366]. Raask [12] found a lowered sintering temperature for iron-rich slags, and, thus, an increased thermal conductivity. This is confirmed by comparing thermal conductivities of different materials, as shown in Table 11. It can be seen that glasses (silica-rich) have a considerably lower thermal conductivity, compared to magnetite (Fe₂O₃). A volume-weighted correlation might be suitable to calculate the thermal conductivity of the mixture [273,362]. Wall et al. [367] also state that the chemical composition affects emissivity. The presence of coloring agents, such as iron, leads to an increased absorptivity, and, thus, a higher deposit temperature, which then influences sintering and deposit properties. An interesting approach is presented by Mills et al. [368] relating the thermal conductivity of a solid ash particle \( k_p \) at room temperature to its chemical composition. The authors use NBO/T ratio, defined as the ratio of non-bridging oxygens to tetrahedral/bridging oxygens in a melt (see [14]) or the Appendix A, Eq. (176), in order to relate chemistry with the experimental data: 

\[
Q = \exp[-0.424 + 0.00002 \cdot \exp(Q/0.299)] 
\]

where the Q value is related to the NBO/T ratio. Eq. (61) is valid in the range of \( 2 < Q < 3.3 \) [368]. With this equation, increased thermal conductivities are predicted when the iron content increases. However, more experimental evidence is needed and the range is very limited.

Radiative properties are difficult to measure and influenced by a number of parameters. They depend on temperature, wavelength of radiation, structure of the deposit, average particle size and its chemical composition. Often, deposit emissivity is treated as a gray body (not a function of wavelength) and as opaque (transmissivity equals zero). Wall et al. [367] state that a deposit must have a thickness of 1 mm or more in order to be considered as opaque. Furthermore, an increased particle size in a deposit leads to a higher emissivity [370]. On the contrary, the emissivity of ash particles strongly depends on iron and residual carbon content. If both, Fe and C, are present, reported emissivity values are considerably higher. Burning char particles show values around \( \varepsilon_p = 0.9 \) depending on char conversion and mineral matter content. Literature values show large variations due to the heterogeneity of particles and deposits as well as the dependence on many process parameters. Typical values for deposit and particle emissivities are given in Table 12.

A mathematical description of thermal conductivity through porous media or a packed bed often applies so-called “unit cell” or

---

**Table 11**

<table>
<thead>
<tr>
<th>Material</th>
<th>( k ) in Wm⁻¹K⁻¹</th>
<th>when ( T )</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Quartz (fused) SiO₂</td>
<td>1.6 – 2.2</td>
<td>( T )</td>
<td>Powell et al. [363]</td>
</tr>
<tr>
<td>Polycrystalline Al₂O₃</td>
<td>1.0 – 1.4</td>
<td>( T )</td>
<td>Powell et al. [363]</td>
</tr>
<tr>
<td>Soda-lime glass</td>
<td>1.8</td>
<td>( T )</td>
<td>Kingery [364]</td>
</tr>
<tr>
<td>Ferrous Oxide FeO</td>
<td>5.0</td>
<td>( T )</td>
<td>Takeda et al. [365]</td>
</tr>
<tr>
<td>Magnetite Fe₂O₃</td>
<td>8.0</td>
<td>( T )</td>
<td>Takeda et al. [365]</td>
</tr>
</tbody>
</table>

---

**Table 12**

<table>
<thead>
<tr>
<th>Material</th>
<th>( \varepsilon )</th>
<th>when ( T )</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Char particle</td>
<td>0.85 – 0.95</td>
<td>( T )</td>
<td>Rego-Barcena et al. [369]</td>
</tr>
<tr>
<td>Ash particle</td>
<td>0.6 – 0.95</td>
<td>( T )</td>
<td>Boow and Goard [370]</td>
</tr>
<tr>
<td>Particulate deposit</td>
<td>0.5 – 0.8</td>
<td>( T )</td>
<td>Mulcahy et al. [371]</td>
</tr>
<tr>
<td>Sintered deposit</td>
<td>0.6 – 0.8</td>
<td>( T )</td>
<td>Mulcahy et al. [371]</td>
</tr>
<tr>
<td>Fused deposit</td>
<td>0.75</td>
<td>( T )</td>
<td>Mulcahy et al. [371]</td>
</tr>
<tr>
<td>Slag</td>
<td>0.83 – 0.90</td>
<td>( T )</td>
<td>Boow and Goard [370], Wall et al. [378]</td>
</tr>
</tbody>
</table>
"pseudo-homogeneous" models; see also the review of Zbogar et al. [273]. The difference between both is the treatment of thermal radiation. "Unit cell" models treat radiation as a local effect taking place between adjacent particle surfaces and voids in the unit cell [273]. They either add the radiative conductivity by
\[
\kappa_{\text{eff}} = \kappa_g + \kappa_{\text{rad}},
\]
where \(\kappa_{\text{eff}}\) is the effective thermal conductivity through the porous media, and \(\kappa_{\text{rad}}\) is the increase in thermal conductivity by thermal radiation. Or they include the radiative conductivity as a resistance in the network. "Pseudo-homogeneous" models consider packed beds to be a continuum for radiation, where the bed is often assumed to be a pseudo-homogeneous medium, in which radiation can penetrate freely [273]. An estimation of theoretical boundaries for thermal conductivities can be achieved by comparing the gas \(\kappa_g\) and solid \(\kappa_s\) thermal conductivity. Rezaei et al. [246], suggest the following empirical, temperature-dependent correlation, for the flue gas thermal conductivity \(\kappa_g\):
\[
\kappa_g = 0.00038 \cdot T^{0.75},
\]
This equation is illustrated in Fig. 54(b) as the lower boundary (dashed line) and roughly yields temperature-dependent values for air. The solid thermal conductivity \(\kappa_s\) (also shown in Fig. 54(b) by the continuous line) is the upper boundary when the deposit has no porosity. It can be estimated by [246]:
\[
\kappa_s = 0.0015 \cdot T^{1.1},
\]
Both Eqs. (63) and (64) can then be applied to calculate theoretical boundaries for heat conduction of packed beds. The upper boundary is given by heat transfer in the direction of parallel layers of gas and solid material. Fig. 54(a) shows this curve as a continuous line. A mathematical expression is given by:
\[
k_{g,s,\text{max}} = \rho_{\text{dep}} \cdot \kappa_g + (1 - \rho_{\text{dep}}) \cdot \kappa_s,
\]
where, \(\rho_{\text{dep}}\) is the porosity of the deposit layer. The lower boundary is expressed by (dashed line in Fig. 54(a)):
\[
k_{g,s,\text{min}} = \frac{k_g}{\rho_{\text{dep}} + \frac{1 - \rho_{\text{dep}}}{\pi \kappa_s}}.
\]

Different models were developed for calculating the thermal conductivity of packed beds. Most common ones, are summarized in Table 13. Mathematical descriptions are given in the review of Zbogar et al. [273]. A comparison of model predictions and measurements available in literature, is given in Figs. 55(a) and (b). It can be seen that best agreement is achieved by the model of Brailsford and Major [381]. At both, low and high temperatures, predictions follow measurements of Rezaei et al. [246] well. Brailsford and Major [381] developed a unit cell model and derived the following complex expression:
\[
k_{g,s} = \frac{[3(1 - p_{\text{dep}}) - 1] \kappa_s + [3p_{\text{dep}} - 1] \kappa_s}{\left[\frac{[(3(1 - p_{\text{dep}}) - 1) \kappa_s + [3p_{\text{dep}} - 1] \kappa_s^2]}{4} + 8 \kappa_s \right]^{0.5}}
\]
An estimation for the radiative conductivity is given by the following equation:
\[
k_{\text{rad}} = 4 \cdot \chi \cdot d_p \cdot T^2
\]
where \(d_p\) is the mean particle diameter of the deposit and \(\chi\) is the radiative exchange factor. It can be calculated using the equation suggested by Godbee and Ziegler [383]:
\[
\chi = \varepsilon_{\text{dep}} / (1 - \rho_{\text{dep}}),
\]
where \(\varepsilon_{\text{dep}}\) is the deposit emissivity. Many other radiation exchange factors have been proposed. They are summarized by Zbogar et al. [273]. Best results are obtained with Eq. (68). Figs. 56(a) and (b) compare the effective thermal conductivity considering both radiation and conduction through a porous media. Measurements of Mulcahy et al. [371] can be fitted with a deposit porosity of \(p_{\text{dep}} = 0.55\), an emissivity value of \(\varepsilon_{\text{dep}} = 0.8\) and a relatively large particle size of \(d_p = 350 \mu\text{m}\). The measurements of Anderson et al. [361] could not be reproduced adequately with the given equations. Deviations are probably due to changing structures during heating such as sintering and fusion. These are often reported to be more important than increased heat conduction through radiation [273].

**Table 13**
Thermal conductivity models and their characteristics (UC stands for “unit cell” and SE for “semi-empirical” models).

<table>
<thead>
<tr>
<th>Model</th>
<th>Type</th>
<th>Characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nimick and Leight [379]</td>
<td>UC</td>
<td>developed for granular porous media</td>
</tr>
<tr>
<td>Hadley [380]</td>
<td>UC</td>
<td>suggested by Zbogar [273] for sintered deposits</td>
</tr>
<tr>
<td>Brailsford and Major [381]</td>
<td>UC</td>
<td>best results for particulate deposits (see Fig. 55)</td>
</tr>
<tr>
<td>Yagi and Kuni [382]</td>
<td>SE</td>
<td>suggested by Zbogar [273] for particulate deposits</td>
</tr>
<tr>
<td>Robinson et al. [358]</td>
<td>SE</td>
<td>two layer approach considering sintering</td>
</tr>
</tbody>
</table>

\[\text{T a g g e d P}\]

**Fig. 55.** Comparison of thermal conductivity models with measurements: (a) for low temperatures, and, (b) for higher temperatures.
3.10. Aerosol properties

Particles in the sub-micron size range exhibit some interesting phenomena. For instance, the melting temperatures of nanoparticles start to decrease [376]. Fig. 57(a) shows the melting temperature of aluminum particles as a function of particle size. Different theoretical studies are in agreement with measurements of Eckert et al. [373]. The melting temperature of aluminum starts to decrease down to values of 200 °C for particles in the size range of 10 nm, compared to melting temperatures of 660 °C of bulk aluminum. Other studies reported a decrease in surface tension for nanoparticles. The surface tension of aerosol depends on the so-called Tolman-length $\delta_{\text{Tol}}$ [377]. Both effects are often studied theoretically since measurements in this size range are highly complex and require high efforts. The role of such effects is questionable. Section 2.3.3 on aerosols has shown that the majority of sub-micron particles is found in the size range of $d_p = 100$–200 nm, probably as agglomerates of smaller particles. If these agglomerates have primary particles below 50 nm, effects can become relevant. However, uncertainty is high and more studies in this field are needed.

4. Ash particle sticking behavior

The probability of an ash particle adhering to a surface — also referred to as substrate — needs to be described by mathematical models. Particle impaction on a substrate is mainly dependent on properties of the particle and the surface. The following list summarizes main parameters influencing particle sticking behavior:

- particle properties such as melt fraction, viscosity, surface tension/energy,
- particle kinetic energy and its deformation upon impaction,
- particle shape and surface roughness,
- the angle of impaction,
- substrate roughness and geometry,
- substrate properties, such as melt fraction, viscosity, surface tension/energy, and
- forces between particles and the surface (e.g. adhesion or van der Waals forces).

Fig. 58 shows five possible scenarios of a particle (molten, partially molten or solid) impacting on a clean, solid substrate. The
Particle impacts at an angle $\varphi$, with a well-defined kinetic energy. The particle kinetic energy $E_{p,\text{kin}} = \frac{1}{2} m_p v_p^2$, without rotational energy, depends on the particle mass $m_p$ and its velocity $v_p$. A particle will remain on the surface (2), if its kinetic energy is dissipated during the collision. If the particle kinetic energy is higher than the energy dissipated during collision, it will rebound (1) \cite{290,384,385}.

The dissipation of energy can be due to deformation, friction between particle and surface, or adhesion \cite{222}. Typically, it is distinguished between an elastic and an inelastic – sometimes referred to as plastic – collision. An elastic collision is defined as a collision of two bodies, where there is no loss in kinetic energy. The kinetic energy of two bodies after collision equals to their total kinetic energy before the encounter. This type only occurs in theory, when there is no conversion of kinetic energy into other forms such as heat. An inelastic collision, in contrast, is a collision in which kinetic energy is converted in other forms. There are energy losses due to e.g. internal friction, plastic deformation, vibrations and others. Ash particles occur as pure solids, liquids and mixtures \cite{323}, and are therefore assumed to collide inelastic, with and without plastic deformation. Examples of collisions with plastic deformation are particles with low viscosity values at high temperatures spreading during impact (3). Particles deform at the surface and retain their deformed shape, either due to cooling and solidification, or low surface tension. The maximum spread diameter $d_{p,\text{max}}$ is frequently used to describe this phenomenon. This type of impaction can be identified by deformed ash particles found in the cross-section of a deposit. Splash (4) or rebound with breakup (5) are not reported for ash particles due to their relatively high viscosity and high surface tension.

The forces acting on a particle settled on a substrate are shown in Fig. 59. The particle is in contact with the surface, forming an interface, which depends on particle and surface properties. The contact diameter $d_{p,\text{max}}$ (also called spread diameter) mainly depends on the particle viscosity, surface tension/energy and roughness. The contact angle $\Theta_c$ is typically large for ash particles, which indicates poor adhesiveness, low wettability due to high surface tension, and low free surface energy. This behavior can also be observed for a liquid water droplet on a hydrophobic surface. The forces acting on the particle can be divided into forces acting parallel and perpendicular to the substrate. Parallel forces are drag, friction and shear forces induced by the flow in the boundary layer. Perpendicular forces are lift, buoyancy, gravity, thermophoresis, and surface forces, being caused by adhesion or van der Waals forces. Depending on the geometry, forces can act in different directions, in particular for a superheater tube. Another parameter affecting particle sticking can be due to shock cooling upon impaction on the surface. The temperature difference between flue gas and clean heat exchanger can be as high as $\Delta T = T_\infty - T_W = 500 \text{ K}$, leading to a rapid cooling of ash particles within the boundary layer and/or during the impaction. Here, the Biot number plays an important role, whether there is a temperature gradient inside the particle ($Bi > 0.1$), or not ($Bi \leq 0.1$). The Biot number is defined as $Bi = \frac{h \cdot d_p}{k_p}$, where $h$ is the total heat transfer coefficient between particle and flue gas. The effects taking place in the boundary layer are rarely addressed in literature. Despite this lack, many different particle sticking criteria have been developed. They can be classified in three main groups - sticking criteria based on the melt fraction of a solid particle, based on the particle viscosity or based on energy conservation during the collision.

### 4.1. Critical melt fraction

This criterion uses the melt fraction of a particle to judge its sticking probability. Is the melt fraction above a critical value, a particle is assumed to adhere. While pure substances melt at a defined temperature, multi-component systems can melt over a wider temperature range. Often, thermodynamic equilibrium calculations are carried out for multi-component system to calculate the melt fraction based on composition and temperature. See for example the work of Wieland et al. \cite{312} who calculated the melting curves for two coal ashes (Pittsburgh #8 and El Cerrejon). Isaak et al. \cite{388,389} were the first to propose the melt fraction as a sticking criteria for salt particles in black liquor combustion systems (black liquor is a Na-rich residue of the pulp and paper industry). Müller et al. \cite{202} used thermodynamic equilibrium calculations for synthetic salt mixtures. Another method is to use simultaneous differential thermal analysis, where the melting curve is measured in a thermo-gravimetric analyzer (TGA). Wieland et al. \cite{312} also conducted this method for coal ashes of the Pittsburgh #8 and El Cerrejon. Müller et al. \cite{202} use a critical melt fraction of $f_p,\text{crit} = 15\%$, at which particles are assumed to adhere. They measured deposition rates on a cooled probe (550 °C) in an entrained flow reactor maintained at 1000 °C and a flow velocity of 2 m/s. Different salt particles are used and 50 g are fed over a time interval of 40 min. They further used numerical simulations to calculate deposition rates on the cooled probe. Müller et al. \cite{202} found that the deposit layer will grow until the surface temperature reaches a value at which 70% are molten. At this point, they assume an equilibrium between incoming particles and deposit flowing off. The sticking probability $p_{\text{stick}}$ is defined as:

$$p_{\text{stick}} = \begin{cases} 0 & \text{for } f_p = 0 - 0.15 \\ 1 & \text{for } f_p = 0.15 - 0.7 \\ 0 & \text{for } f_p = 0.7 - 1 \end{cases}$$  \hspace{1cm} (69)
The numbers of \( f_p = 0.15 \) and \( f_p = 0.7 \) are not universal numbers, and different values can be used instead. A comparison between numerical simulations and experiments shows a good correlation for particles smaller than 75 \( \mu \text{m} \). For larger particles, predictions overestimate the mass deposited. Müller et al. [202] infer that the critical melt fraction is not applicable for larger particles. They suggest an energy criterion based on the work of Mao et al. [390] (see Section 4.3), which yielded better results.

Zhou et al. [391] developed a mathematical model describing the deposit build-up over time. It goes back to work of Hansen et al. [392] and Kær [393]. They apply a critical melt fraction model for particles larger than \( d_p > 10 \mu \text{m} \), in which particles are treated as sticky once they reach \( f_p \geq 10 \). Zhou et al. define a sticking probability for particles between 10% \(< f_p \leq 70\% \). In this region, the sticking probability increases linearly. Unlike Müller et al. [202], every particle above \( f_p > 70\% \) is assumed to stick. Eq. (70) summarizes their model:

\[
\begin{align*}
    p_{\text{stick}} = \begin{cases} 
        0 & \text{for } f_p = 0 - 0.1 \\
        0.05 & \text{for } f_p = 0.1 - 0.7 \\
        1 & \text{for } f_p = 0.7 - 1 
    \end{cases}
\]
\quad (70)
\]

Particles between 10% \(< f_p \leq 70\% \) are assumed to show splash behavior (Nr. 4 in Fig. 58). Only part of the ash particle adheres to the wall, while the remaining mass rebounds. A decrease in deposited mass is described by slag flow and drop-off as erosion. They use a dynamic mathematical model, which is based on a set of equations and estimations. It is not coupled to CFD, and needs many input parameters, such as particle concentration, velocity, and size. Nevertheless, their results show good agreement with experimentally observed deposition rates from a grate-fired boiler using straw as a feedstock. There are further studies using particle sticking criteria based on a critical melt fraction. Akbar et al. [258] uses a similar criterion as Müller et al. [202], however, they do not provide a sticking probability above \( f_p = 70\% \). They studied the deposition behavior of KCl particles from biomass combustion in an entrained flow reactor using a cooled deposition probe with a temperature of 650 °C. Their modeling results indicate the dominant role of condensation effects during early stages in biomass-fired systems. Brink et al. [394] used the melt fraction predicted by TEC in order to describe the particle stickiness. The maximum temperature a particle has reached is typically determined in experiments. This history based approach is an interesting aspect, which should be included in modeling studies, ideally in a comprehensive ash formation model.

### 4.2. Critical viscosity

Another frequently applied particle sticking criterion is based on the viscosity of ash particles. Particles are softer and stickier at lower viscosity values. Different approaches have been proposed in the literature.

A viscosity-based sticking criterion for ash particles was first proposed by Walsh et al. [395]. They carried out ash deposition tests of particles smaller than 75 \( \mu \text{m} \) at 700 - 1100°C. Furthermore, it is reported to behave similar to coal ashes [1]. They used a heated laminar flow furnace, and placed the deposition probe in a conical section. The fluid velocity can be set by changing the position within this conical section. Narrow-sized soda-lime glass particles (28 – 53 and 53 – 74 \( \mu \text{m} \)) were used to fix particle kinetic energy. At a given kinetic energy, the temperature in the system is varied and the threshold, at which sticking begins is determined. This temperature corresponds to the critical viscosity value. Fig. 56 shows the particle kinetic energy \( E_{\text{kin}} \) as a function of critical viscosity \( \mu_{\text{crit}} \). With increasing particle kinetic energy, a lower particle viscosity and thus higher temperature is needed for a particle to stick. In other words, the smaller a particle the higher its sticking

### Table 14

<table>
<thead>
<tr>
<th>Reference</th>
<th>Critical viscosity ( \mu_{\text{crit}} ) in Pa·s</th>
<th>Notes and comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>Walsh et al. 1990 [395]</td>
<td>8 ( \times ) 10&lt;sup&gt;4&lt;/sup&gt; – 10&lt;sup&gt;8&lt;/sup&gt;</td>
<td>measured deposit viscosity at 700 – 1100°C</td>
</tr>
<tr>
<td>Kær 2001 [393]</td>
<td>10&lt;sup&gt;9&lt;/sup&gt;</td>
<td>for two US bituminous coals</td>
</tr>
<tr>
<td>Liebetruth et al. 2002 [396]</td>
<td>2</td>
<td>for German lignite</td>
</tr>
<tr>
<td>Beckmann et al. 2016 [397]</td>
<td>17 - 25</td>
<td>for Middelburg coal (17 Pa·s was measured)</td>
</tr>
</tbody>
</table>

remaining on the surface is calculated by \( \mu_{\text{p,ref}}/\mu_p \). This approach was applied in several studies, however, inaccuracies in the use emerged. Often, a binary sticking criterion was used instead, where \( \mu_{\text{p,ref}} \) is the critical viscosity, at which sticking of particles starts to occur. Above this critical value, particles are assumed to rebound. It is defined as:

\[
    p_{\text{stick}} = \begin{cases} 
        0 & \text{for } \mu_p > \mu_{\text{p,ref}} \\
        1 & \text{for } \mu_p \leq \mu_{\text{p,ref}} 
    \end{cases}
\quad (72)
\]

where \( \mu_{\text{p,ref}} \neq \mu_{\text{p,ref}} \). Richter [222] estimates the following relation \( \mu_{\text{p,ref}} = 0.01/\mu_{\text{p,ref}} \) between reference and critical viscosity. Table 14 summarizes reference and critical viscosity values, found in literature. A large variation between 2 and 10<sup>9</sup> Pa·s can be seen. This variation can have several reasons. The chemistry and melting behavior can have an influence, where at a given viscosity one particle is sticky and another is not. Another reason could be different particle velocities. Studies with low critical/reference viscosity used relatively high particle velocities (Walsh et al. [395] with 15 m/s and experiments of Liebetruth et al. [396] are estimated around 8 m/s). This would indicate a dependence on particle kinetic energy. Another problem is the use of bulk ash chemistry and bulk ash viscosity values. Bulk ash can have significantly higher viscosities compared to individual ash particles forming low-melting eutectics, for example. A large number of modeling studies use bulk ash chemistry and results can be misleading.
probability at a given temperature and chemical composition. Richter [222] did similar experiments in an entrained flow reactor with lower particle velocities and confirmed this relationship. A third study was conducted at the Energy Research Center of the Netherlands (ECN) with higher particle velocities and a cooled steel probe [201]. An overview of experimental conditions is given in Table 15. The following empirical correlation can be derived from the data points by a least square fit. The critical viscosity is a power-law function of the particle kinetic energy, 

$$
\mu_{p,\text{crit}} = A \cdot E_{p,\text{kin}}^{0.12} \cdot E_{p,\text{kin}}^{0.78},
$$

where coefficients $A$ and $B$ are determined from Fig. 60. The particle viscosity is then used in combination with Eqs. (72) and (73). Particles stick to the surface, if the calculated particle viscosity is below the critical viscosity, and rebound if $\mu_p > \mu_{p,\text{crit}}$. Fig. 60 also shows corresponding particle sizes for an exemplary velocity of 10 m/s (secondary horizontal axis), and the equivalent temperature to viscosity values of soda-lime glass particles (secondary vertical axis). Experiments for very small particles are missing. A further binary sticking criteria was proposed by Richards et al. [408]. They define a particle as sticky, when the particle viscosity is below the ash melting viscosity. However, the melting viscosity is difficult to determine and various definitions exist in literature. The criterion uses again the bulk ash and not the individual chemical composition of fly ash particles.

4.3. Energy conservation and critical velocity

A further method is based on energy conservation of a particle, during impact. This method was often applied for solid particles impacting a smooth, flat surface using contact mechanics, or in the field of liquid droplets impinging on a smooth wall. The main difference is the particle/droplet deformation. In the case of solid particles, the impaction process involves elastic deformation and depending on the particle kinetic energy and the material properties also plastic deformation. On the contrary, elastic deformation is negligible during liquid droplet impact. Droplets deform heavily and might break-up. Therefore, the focus is on the energy dissipation due to particle deformation, the particle break-up and phenomena occurring when substrate and particle temperature differ significantly.

4.3.1. Solid particle impacting a solid smooth surface

The energy balance is used to calculate critical parameters, such as the critical velocity. If the particle velocity is smaller than this critical value, particles stick, in all other cases particles rebound. The particle velocity can either be the absolute value $v_p$, or the normal component $v_{p,n}$ relative to the surface, which becomes important for oblique (non-normal) impacts, e.g. on a superheater tube. An energy balance, which might be suitable for ash particle impaction is given by the following equation:

$$
E_{\text{kin},i} + E_{\text{surf},i} = E_{\text{def}} + E_{\text{visc}} + E_{\text{ad}} + E_{\text{el}} + E_{\text{adi}},
$$

where $E_{\text{kin}}$, $E_{\text{surf}}$, $E_{\text{def}}$, $E_{\text{visc}}$, $E_{\text{ad}}$, $E_{\text{el}}$, and $E_{\text{adi}}$ are the kinetic, surface, deformation, viscous dissipation, adhesion, elastic, and energy dissipation due to particle deformation, respectively. The parameters in Eq. (74) are the particle kinetic energies $E_{\text{kin}}$, the particle surface energy $E_{\text{surf}}$, the work of viscous dissipation $E_{\text{visc}}$, the work of adhesion $E_{\text{ad}}$, and the work of deformation $E_{\text{def}}$. The index “i” stands for initial conditions of impacting particles and “r” for rebounding particles. Particles stick, if the kinetic energy on the right equals zero. Further energies involved, such as potential energy, rotational energies of the particle, energy due to van der Waals forces between two solids or elastic wave propagation (during collision, when part of the energy is radiated into the substrate as elastic waves) are often neglected [390]. Eq. (74) can then be applied to calculate critical parameters, such as the critical velocity $v_{p,\text{crit}}$ and evaluate the

<table>
<thead>
<tr>
<th>Study</th>
<th>$d_p$ in μm</th>
<th>$v_p$ in m/s</th>
<th>$\log_{10}(p_{\text{crit}})$</th>
<th>$T_p$ in °C</th>
<th>comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>Srinivasachar et al. [1]</td>
<td>40.5</td>
<td>1</td>
<td>7.2</td>
<td>683</td>
<td>uncooled probe</td>
</tr>
<tr>
<td></td>
<td>40.5</td>
<td>2</td>
<td>6.3</td>
<td>733</td>
<td>uncooled probe</td>
</tr>
<tr>
<td></td>
<td>63.5</td>
<td>4</td>
<td>5.1</td>
<td>810</td>
<td>uncooled probe</td>
</tr>
<tr>
<td></td>
<td>43.5</td>
<td>0.33</td>
<td>8.3</td>
<td>609</td>
<td>uncooled probe</td>
</tr>
<tr>
<td></td>
<td>81.5</td>
<td>0.33</td>
<td>7.6</td>
<td>632</td>
<td>uncooled probe</td>
</tr>
<tr>
<td>Richter [222]</td>
<td>71</td>
<td>3.1</td>
<td>3.2</td>
<td>1010</td>
<td>cooled probe</td>
</tr>
<tr>
<td></td>
<td>105</td>
<td>3.1</td>
<td>3.1</td>
<td>1020</td>
<td>cooled probe</td>
</tr>
<tr>
<td></td>
<td>105</td>
<td>6.2</td>
<td>2.0</td>
<td>1190</td>
<td>cooled probe</td>
</tr>
<tr>
<td>Schulze et al. [201]</td>
<td>71</td>
<td>3.1</td>
<td>3.2</td>
<td>1010</td>
<td>cooled probe</td>
</tr>
</tbody>
</table>
where the critical velocity is estimated by

\[
P_{\text{stick}} = \begin{cases} 0 & \text{for } v_p > v_{p,\text{crit}} \\ 1 & \text{for } v_p \leq v_{p,\text{crit}} \end{cases}
\]

(75)

Thornton and Ning [290], use a simplified energy conservation equation to describe the stick-bounce behavior of adhesive, elastic-plastic spheres. The energy conservation equation is defined as

\[
\frac{1}{2} m v_i^2 = \frac{1}{2} m v_f^2 + E_{\text{ad}}.
\]

(76)

where \(v_i\) and \(v_f\) are the velocities before and after the impact. The parameter \(E_{\text{ad}}\) describes the work of adhesion and \(m\) stands for the equivalent mass of both impact partners “1” and “2” and is calculated by

\[
\frac{1}{m'} = \frac{1}{m_1} + \frac{1}{m_2}.
\]

(77)

If the particle collides with a tube with significantly higher mass, \(m'\) equals the particle mass. Thornton and Ning [290] derived an equation for a sphere impacting on a flat substrate. They express the work of adhesion as a function of particle and substrate properties, and rewrite Eqs. (76) and (77) to

\[
v_{p,\text{crit}} = 1.84 \cdot \left( \frac{(\Gamma')^5}{\rho_p^3 \cdot (E')^4} \right)^{\frac{1}{8}}
\]

(78)

where \(r_p\) stands for the particle radius and the equivalent Young’s modulus \(E’\), is obtained by the following equation,

\[
\frac{1}{E'} = \frac{1 - v_1^2}{E_1} + \frac{1 - v_2^2}{E_2},
\]

(79)

with \(E_1, E_2\) and \(v_1, v_2\) being the Young’s Modulus and Poisson’s ratio of each collision partner. Thornton and Ning [290] do not give an expression for the interface energy \(\Gamma’\). Losurdo et al. [342] use the Young-Dupré equation, for liquid droplets on a solid substrate, in the form of:

\[
\Gamma’ = \gamma_1 + \gamma_2 - \gamma_{12} \cdot \cos \Theta_c,
\]

(80)

where \(\gamma_1\) and \(\gamma_2\) are the surface energy (solids) or the surface tension (liquids) of the collision partners. The parameter \(\gamma_{12}\) is the interfacial tension between two partners, and \(\Theta_c\) is the contact angle. The model of Thornton and Ning [290] is also able to describe the contacting of incoming particles, with particles deposited on a substrate. This equation differs from Eq. (78) and can be found in their publication. Losurdo et al. [342] use Eq. (78) and derive a simple expression, where the critical velocity is estimated by \(v_{p,\text{crit}} = 0.0001 \cdot v_p\). They then calculate the total rebound velocity \(v_{r,\text{tot}}\) of a particle by:

\[
v_{r,\text{tot}} = \sqrt{v_{r,t}^2 + v_{r,f}^2} = \sqrt{(e_n \cdot v_{n,f})^2 + (e_t \cdot v_{t,f})^2},
\]

(81)

where \(v_r, v_n, \) and \(e_n, e_t\) are the normal and tangential velocity components and restitution coefficients. The calculation of the restitution coefficients is not given in their publication. If \(v_{r,\text{tot}} \leq v_{p,\text{crit}}\) the particle is assumed to stick. They applied this model to simulate glass particle deposition experiments, conducted at ECN, and also used in the study of Schulze et al. [201]. Glass particles in the size of 71–105 \(\mu m\) are injected in a lab-scale methane combustor. Particles are then collected on a steel tube maintained at 500°C with a surrounding gas temperature of 1200°C. The simulation shows adequate results and the authors recommend this model.

Wall et al. [414] compared literature data on the critical velocity below which the particle will adhere to the surface. The critical velocity strongly depends on the particle size, and increases with decreasing particle diameter. Different material combinations yield different slopes, ranging from –0.39 to –6.11 as shown in Fig. 61. Dong et al. [420] determined the critical velocity of fly ash particles on stainless steel, however, only at room temperatures. Their data show a strong dependence on the diameter with the highest slopes. A difficulty is the inhomogeneity in fly ash, where particles are not perfectly spherical and differ in chemistry. The authors report that the majority of fly ash particles is composed of quartz and mullite [420]. This data should be extended to higher temperatures, where the ash softens, and impact behavior changes. There is currently no theory incorporating all energies involved during impact and rebound, and thus being able to predict different rebound behavior shown in Fig. 61. Table 16 summarizes major experiment using solid particles impacting on a solid substrate. Typically, this data is used to set up and validate models including elastic and plastic deformation effects. Table 16 focuses on particle impaction studies with diameters and velocity values relevant for ash deposition. Again, studies using high temperatures are not available. Furthermore, the majority uses exotic materials, mostly polymers or metals, with limited application to ash deposition. Brach and Dunn [428] derived a mathematical model for the impaction of micrometer-sized spheres, at moderate velocities and arbitrary angles of impaction on a flat substrate. According to the authors, the model can be applied for solids, for spheres in the transition regime between solid and liquid (i.e. viscoelastic, elastic-plastic), and other materials or combinations. Assumptions of this model, are that the processes of adhesion and material deformation, are independent of each other. They argue that energy loss due to adhesion only occurs during rebound [428]. The model is validated using experimental data from the impaction of ammonium fluorescein spheres against a molybdenum surface. The model is based on Newton’s law, the conservation of momentum, and given by:

\[
m_p \cdot (v_{n,f} - v_{n,i}) = P_p = P_{\text{def}} + P_{\text{ext}} - P_{\text{ad}},
\]

where \(P_{\text{def}}, P_{\text{ext}}, \) and \(P_{\text{ad}}\) are the normal and tangential force components and restitution coefficients. The calculation of the restitution coefficients is not given in their publication. If \(v_{r,\text{tot}} \leq v_{p,\text{crit}}\) the particle is assumed to stick. They applied this model to simulate glass particle deposition experiments, conducted at ECN, and also used in the study of Schulze et al. [201]. Glass particles in the size of 71–105 \(\mu m\) are injected in a lab-scale methane combustor. Particles are then collected on a steel tube maintained at 500°C with a surrounding gas temperature of 1200°C. The simulation shows adequate results and the authors recommend this model.

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\[
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\]

where \(P_{\text{def}}, P_{\text{ext}}, \) and \(P_{\text{ad}}\) are the normal and tangential force components and restitution coefficients. The calculation of the restitution coefficients is not given in their publication. If \(v_{r,\text{tot}} \leq v_{p,\text{crit}}\) the particle is assumed to stick. They applied this model to simulate glass particle deposition experiments, conducted at ECN, and also used in the study of Schulze et al. [201]. Glass particles in the size of 71–105 \(\mu m\) are injected in a lab-scale methane combustor. Particles are then collected on a steel tube maintained at 500°C with a surrounding gas temperature of 1200°C. The simulation shows adequate results and the authors recommend this model.

![Fig. 61. Comparison of literature data showing the critical velocity as a function of particle size (figures reproduced and extended from Wall et al. [414], data from [414–421]).](image-url)
Table 16
Overview on major particle impaction studies and their parameters (data taken and extended from Krijt et al. [422]).

<table>
<thead>
<tr>
<th>Study</th>
<th>$d_i$, mm</th>
<th>$v_i$, m/s</th>
<th>particle material</th>
<th>substrate material</th>
<th>Characteristics and Key Findings</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dahneke 1975 [423]</td>
<td>0.5</td>
<td>5–15</td>
<td>polystyrene latex</td>
<td>quartz</td>
<td>bouncing behavior of normal</td>
</tr>
<tr>
<td>Cheng and Yeh 1979 [416]</td>
<td>0.2–0.5</td>
<td>2–10</td>
<td>polyvinyl-toluene</td>
<td>stainless steel</td>
<td>impact considering adhesion</td>
</tr>
<tr>
<td>Rogers and Reed 1984 [418]</td>
<td>0.2–0.5</td>
<td>2–10</td>
<td>copper/glass</td>
<td>steel</td>
<td>critical velocity determined for different material pairings</td>
</tr>
<tr>
<td>Wall et al. 1990 [414]</td>
<td>0.2–0.5</td>
<td>2–10</td>
<td>steel/glass</td>
<td>glass/steel</td>
<td></td>
</tr>
<tr>
<td>Dunn et al. 1995 [424]</td>
<td>0.1–1</td>
<td>0.2–20</td>
<td>Ag-coated glass</td>
<td>aluminium</td>
<td>impact angle was studied ranging from 20 to 90°</td>
</tr>
<tr>
<td>Li et al. 1999 [425]</td>
<td>0.1–1</td>
<td>0.2–20</td>
<td>steel</td>
<td>silicon</td>
<td>same experimental setup as Dunn et al. 1995</td>
</tr>
<tr>
<td>Kim and Dunn 2007 [426]</td>
<td>0.1–1</td>
<td>0.2–20</td>
<td>acrylic</td>
<td>silicon</td>
<td></td>
</tr>
<tr>
<td>Sorace et al. 2009 [427]</td>
<td>0.1–1</td>
<td>0.2–20</td>
<td>acrylic</td>
<td>silicon</td>
<td></td>
</tr>
<tr>
<td>Dong et al. 2013 [428]</td>
<td>0.1–1</td>
<td>0.2–20</td>
<td>fly ash</td>
<td>steel</td>
<td>coefficient of restitution &amp; $v_{p, crit}$</td>
</tr>
<tr>
<td>Dong et al. 2013 [429]</td>
<td>0.1–1</td>
<td>0.2–20</td>
<td>fly ash</td>
<td>steel</td>
<td>identical to previous study</td>
</tr>
<tr>
<td>Troiano et al. 2017 [456]</td>
<td>0.1–1</td>
<td>0.2–20</td>
<td>fly ash and char</td>
<td>ref. material</td>
<td>hot and cold wall</td>
</tr>
</tbody>
</table>

Using an energy balance between the tangential kinetic energy of the particle and the minimum energy required to break its contact area with the surface according to:

$$v_{p, crit} = \left[ \frac{H \cdot \left( 1 + \frac{1}{R^2} \right)^2}{32 \cdot \rho \cdot \gamma^2} \right]^{1/2},$$

where $\phi$ is the angle of impaction in radians (see Fig. 58) and the parameter $R$ relates the radius of deformation before and after the contact. It can be approximated by $R = 1 - E_{def}/E_{kin}$. Brach and Dunn [428] fit $R$ to measurements, where they found values of 0.952 < $R$ < 0.983 based on experiments with critical velocities in the range of 0.7 < $v_{p, crit}$ ≤ 3.14 m/s. The variable $H$ is a function of material properties, and it is calculated by:

$$H = 0.51 \left[ \frac{5 \cdot \pi^2 \cdot (k_p + k_w)}{4 \cdot \rho \cdot \gamma^2} \right]^{1/2},$$

where $k_p$ and $k_w$ describe the elasticity of the particle and the wall. The particle elasticity can be expressed by $k_p = \left( 1 - v_p^2 \right)/\left( \pi \cdot E_p \right)$. The elasticity of the wall is derived analogously.

Konstandopoulos [429] examined literature data on experiments on non-normal impact and concluded the existence of a critical impact angle $\psi_{p, crit}$. Below this angle, particles will rebound even if the criterion for the critical velocity: $v_{p, crit} \leq v_{p, crit}$, given by Eq. (75), is fulfilled:

$$P_{\text{stick}} = \begin{cases} 0 & \text{for } \psi_p < \psi_{p, crit} \\ 1 & \text{for } \psi_p \geq \psi_{p, crit} \end{cases}$$

The critical angle $\psi_{p, crit}$ shown in Fig. 62(a) is dependent on the material properties of the two collision partners. An expression is derived using an energy balance between the tangential kinetic energy of the particle and the minimum energy required to break its contact area with the surface according to:

$$\tan \left( \frac{\pi}{2} - \psi_{p, crit} \right) = \frac{v_{p,t}}{v_{p,n}} = \frac{f^*}{\left( 32 \cdot \rho \cdot \gamma^2 \right)^{1/2} \sqrt{E^*}}$$

$$\approx 0.034021 \frac{f^*}{\pi / 2} \sqrt{2 \cdot v / (1 - v^2)}$$

where $f^*$ is an effective friction coefficient either set to the friction coefficient itself or $f_0$ and $E^*$, $G^*$ are the effective Young’s modulus and effective shear modulus, respectively. Note, that the letter $f$ is used for the friction coefficient instead of $\mu$, since $\mu$ denotes viscosity in this study. The parameter

$$\beta = \frac{A_0}{A}$$

is defined as the ratio of the maximum possible contact area $A_0$ to the actual contact area $A$ between two colliding objects (see therefor Fig. 77). The contact area $A_0$ can be calculated according to the Johnson-Kendall-Roberts (JKR) theory [431], explained and discussed later on in Section 5.1, with the following expression [429]:

$$A_0 = \frac{9 \cdot \pi \cdot \gamma^2 \cdot d_t^2}{4 \cdot E^*}$$

Konstandopoulos [429] furthermore investigated literature data on the maximum angle of deposition $\theta_{max, dep}$ as depicted in Fig. 62. He showed that the critical angle along the cylinder circumference $\theta_{crit}$ obtained when $\theta_{p,n} \leq \theta_{p, crit}$ is not the limiting angle until which particles will stick. The maximum angle observed in experiments is obtained by using particle trajectory calculations and Eq. (86). Experimental results are from the work of Aylor and Ferrandino [432], who studied the deposition of 15 - 30 µm pollen (ragweed and lycopodium) on glass rods of 3 - 10 mm diameter, and the work of Wang and John [419], who applied monodisperse ammonium fluorescein particles with a size range of 3.35 - 20 µm on stainless steel cylinders of 1.6 and 3.2 mm diameter. The data is illustrated in Fig. 62(b), showing the maximum deposition angle, as a function of the Stokes number. It can be seen that the angle to which particles
sticking, depends on the Stokes number, and the ratio of $\nu_p/\nu_{p,\text{crit}}$. This ratio is known to depend on the physical and material properties of the particle-surface combination as given by Eq. (86). In order to calculate the critical angle $\psi_{p,\text{crit}}$ using Eq. (86), the ratio $(E'/G')$, $\mu^*$ and $\beta$ are needed. The ratio $(E'/G')$ is only a function of the Poisson’s ratio $\nu$, and typical values are about 2.1–2.2 [429]. The data shown in Fig. 62(b) can be applied to estimate the parameter $\beta \approx 0.09–0.15$ with $f = 0.2–0.3$ for the material pair of Wang and John [419].

A similar approach was developed by Rosner and Tandon [433], in order to describe particle deposition rates for a cylindrical target in a dust-laden stream. A model is presented for dry, granular deposition to estimate the parameter $\beta$ and $\nu_{p,\text{crit}}$, where the fraction sticking is described with $p_{\text{stick}} = \frac{1}{1 + 0.8 \cdot \chi(\Theta_i) \cdot (\nu_p/\nu_{p,\text{crit}} - 1)}$ for $\nu_p < \nu_{p,\text{crit}}$ or $p_{\text{stick}} = 0$ for $\nu_p \geq \nu_{p,\text{crit}}$.

The impaction of liquid droplets on a solid surface has been investigated in a large number of studies, often in the field of internal combustion engines, aiming at the deposition of fuel droplets on walls [436–438], fundamental studies using water or alcohol droplets impacting on various solid surfaces [390,435,439–444], or, spray coating [445]. Most studies are used to develop mechanistic or semi-empirical models describing the impaction process for variable droplet sizes, viscosities, surface tensions at different impaction angles and speeds. Fig. 63 shows the stages of a low viscosity droplet such as water impacting on a flat solid surface. The schematic is based on the work of Chandra and Avedisian [435], who used a camera system in order to record different stages of droplet impaction and deformation. Particle or droplet impaction on a solid substrate can be divided into six consecutive stages. Fig. 63 illustrates different stages for a low viscosity liquid. The incoming particle of size $d_p$ and impact velocity $\nu_p$ starts to wet the substrate during stage “1”. This process is strongly dependent on the contact angle $\theta_i$ between the surface and the droplet, which depends on liquid properties and surface characteristics. Young’s equation given by Eq. (52) can be used to relate the contact angle to the surface tension and surface energy. At stage “2”, the maximum spread diameter $d_{p,\text{max}}$ is reached and the kinetic energy approaches zero. At this point, the droplet height finds its minimum $h_{p,\text{min}}$. During the next two stages, the droplet starts to deform back to a sphere and oscillate, forming the maximum height at stage “4”. At stage “5” the droplet either rebounds or sticks, depending on energy dissipation during previous stages. For a low viscosity droplet the sticking probability is quite high due to large deformations. However, splashing is untypical for ash particles since viscosity is still high compared to liquids such as water or gasoline.

![Fig. 62. Oblique impact and sticking criterion according to Konstandopoulos [429]: a) comparing normal and oblique impact angles (shown angle $\psi_p$ equals $\psi_{p,\text{crit}}$ since the particle impacts at the maximum angle, at which sticking can occur $\Theta_{\text{max,dep}}$), and b) dependence of $\Theta_{\text{max,dep}}$ on the Stokes number $St$ for different values of $\nu_p/\nu_{p,\text{crit}}$.](image)

![Fig. 63. Impaction stages for a low viscosity droplet, such as water (adopted from Chandra and Avedisian [435]).](image)
Following expression:

\[
W_{\text{ep}} = \frac{\mu_p \cdot V_p \cdot d_p}{\gamma_p}.
\]  

At low Weber numbers and temperatures below the boiling point \(T_{\text{bp}}\), the droplet will stick due to its low kinetic energy, which is completely dissipated during collision. However, the behavior changes at high surface temperatures, where a vapor film between the droplet and the surface prevents the droplet from wetting and deformation. In this case, rebound is reported. A study of Bai and Gosman further differentiated into break-up, splash and rebound with break-up regimes depending on further characteristic temperatures. Splashing behavior is commonly reported at very high Weber numbers, independent of the substrate temperature. A regime map for ash particle deposition has to consider supercooled liquids instead. Molten particles can solidify in the boundary layer, depending on the particle velocity and boundary layer thickness. Typically, a 20 \(\mu\)m particle with 15 m/s (St \(\approx 1\) for a superheater tube with diameter 30 mm) is the threshold. Larger particles are unaffected and no deceleration and cooling occurs inside the boundary layer, as estimated by Walsh et al. and predicted using CFD (around 30 \(\mu\)m particle with 6.8 m/s was the threshold). This behavior inside the boundary layer can be significant for small particles. Therefore, the applicability of a regime map without considering cooling effects is doubtful. A summary on major experimental droplet impaction studies is given in Table 17. Most investigations use relatively large droplets, with low viscosity values, compared to ash particles. Nevertheless, the experiments are valuable for the development of sticking and rebound models. There are some studies, such as Chandra and Avedisian or Slanciavskas and Kalpokaitis using high viscosity fluids with relevant properties.

Pasandideh-Fard et al. studied the impaction of liquid droplets on solid surfaces using experimental and numerical methods. Impacting water droplets were photographed, and maximum spread diameters and contact angles, were obtained from these images. The droplet diameter was around \(d_p \approx 2\) mm and the impact velocity \(V_p = 1\) m/s. The authors derive correlations for the maximum droplet diameter after impaction \(d_{\text{p,max}}\) (defined in Fig. 63 or 58). After impaction, the droplet deforms, and loses its circular shape, forming a thin film on the substrate, as shown in stage 2, within Fig. 63. This deformation process is described using energy conservation as given in Eq. (74). The authors show that the ratio of maximum spread diameter \(d_{\text{p,max}}\) to initial droplet diameter \(d_p\) can be calculated by:

\[
\xi = \frac{d_{\text{p,max}}}{d_p} = \sqrt{\frac{W_{\text{ep}} + 12}{3 \cdot \left(1 - \cos \Theta_f\right) + 4 \cdot \left(W_{\text{ep}}/\sqrt{R_{\text{ep}}}\right)}}.
\]  

The maximum spread \(\xi\) of the droplet is a function of droplet contact angle \(\Theta_f\), at \(d_{\text{p,max}}\), droplet Weber number \(W_{\text{ep}}\), and, droplet Reynolds number \(R_{\text{ep}} = \rho_p \cdot V_p \cdot d_p / \mu_p\), which are both calculated for a spherical droplet before impaction. The Reynolds number is calculated using the droplet velocity in contrast to Eq. (12), where the viscosity of the surrounding fluid is used instead. Since most droplet impaction studies are conducted at stagnant air flow, it is unclear if the

![Fig. 64. Regime map for droplet-wall interaction (based and modified from Grover and Assanis [446], and, Bai and Gosman [447]; \(T_{\text{bp}}\) stands for the boiling temperature of the liquid droplet).](image)

### Table 17

Overview on major droplet impaction studies and their parameters (data taken and extended from Mahulkar et al. [450]).

<table>
<thead>
<tr>
<th>Study Unit</th>
<th>(d_p) μm</th>
<th>(V_p) m/s</th>
<th>(T_{\text{max}}) °C</th>
<th>liquid Characteristics and Key Findings</th>
</tr>
</thead>
<tbody>
<tr>
<td>Wachters and Westerling 1966 [429]</td>
<td>2000</td>
<td>0–1.7</td>
<td>up to 400</td>
<td>water rebound behavior (n-heptane)</td>
</tr>
<tr>
<td>Chandra and Avedisian 1991 [435]</td>
<td>1500</td>
<td>0.93</td>
<td>24–250</td>
<td>ethanol, water spreading behavior</td>
</tr>
<tr>
<td>Mundo et al. 1995 [440]</td>
<td>60–150</td>
<td>12–18</td>
<td>25</td>
<td>ethanol, water spreading behavior</td>
</tr>
<tr>
<td>Pasandideh-Fard et al. 1996 [441]</td>
<td>2050</td>
<td>1</td>
<td>n.s.</td>
<td>water spreading behavior</td>
</tr>
<tr>
<td>Mao et al. 1997 [390]</td>
<td>1500–3500</td>
<td>0.5–6</td>
<td>25</td>
<td>water–sucrose mixtures spreading behavior</td>
</tr>
<tr>
<td>Aziz and Chandra 2000 [451]</td>
<td>2700</td>
<td>1–4</td>
<td>25–400</td>
<td>tin spreading behavior</td>
</tr>
<tr>
<td>Riboo et al. 2002 [452]</td>
<td>1200–4900</td>
<td>0.78–4.1</td>
<td>n.s.</td>
<td>various spreading behavior</td>
</tr>
<tr>
<td>Bai et al. 2002 [442]</td>
<td>1–300</td>
<td>up to 20</td>
<td>25</td>
<td>iso-octane spreading behavior</td>
</tr>
<tr>
<td>Sikalo et al. 2005 [438]</td>
<td>1000–3000</td>
<td>1.54</td>
<td>25</td>
<td>water, glycerol, iso-propanol spreading behavior</td>
</tr>
<tr>
<td>Slanciavskas and Kalpokaitis 2006 [437]</td>
<td>750</td>
<td>n.s.</td>
<td>400–700</td>
<td>heavy fuel oil spreading behavior</td>
</tr>
<tr>
<td>Shen et al. 2010 [443]</td>
<td>1000–1300</td>
<td>1.18</td>
<td>23–185</td>
<td>water spreading behavior</td>
</tr>
<tr>
<td>Fujiimoto et al. 2010 [457]</td>
<td>530–2500</td>
<td>1.7–4.1</td>
<td>170–500</td>
<td>water spreading behavior</td>
</tr>
<tr>
<td>Negeed et al. 2013 [444]</td>
<td>300–700</td>
<td>1.0–4.0</td>
<td>800</td>
<td>water spreading behavior</td>
</tr>
</tbody>
</table>

n.s. – not specified.

a including acetone, isopropanol, ethanol, water, silicone oils and mixtures of glycerine and water.

b with different surfactant concentrations changing the surface tension and contact angle.
relative velocity between the droplet and the gas flow or the absolute velocity has to be used; however, the latter seems more appropriate. Mao et al. [390] conducted similar experiments, and studied the impaction of droplets composed of a water-sucrose mixture on glass, steel or paraffin substrates. Studied droplets had diameters of 1.5 < dp ≤ 3.5 mm and velocities in the range of 0.5 < vp ≤ 6 m/s. The authors used a similar energy-based approach as Pasanideh-Fard et al. [441], but with a changed formulation for the surface energy at the particle thermal conductivity, where the excess rebound energy after impaction. The authors use a parameter called excess rebound energy EERE in order to estimate the rebound behavior of droplets. Deformation and maximum spread are affected if the substrate temperature is below the melting temperature of the droplet. Deformation and maximum spread, which then contracts to form a ring after maximum spread, which then contracts to form a ring after maximum spread, which then contracts to form a ring after maximum spread. Mao et al. [390] compared the solution of Eq. (93) with measurements and found a maximum deviation of 10%. They observed the formation of a ring after maximum spread, which then contracts towards its center forming a conical droplet, and separates from the substrate. The droplet rebounds, if the energy dissipated due to viscous forces and the work of adhesion is higher than the surface energy after impaction. The authors use a parameter called excess rebound energy EERE in order to estimate the rebound behavior of droplets. The droplet will stick (pstick = 1) if EERE ≤ 0 and rebound otherwise (pstick = 0) [390]:

\[
p_{\text{stick}} = \begin{cases} 
0 & \text{for } E_{\text{ERE}} > 0 \\
1 & \text{for } E_{\text{ERE}} \leq 0 
\end{cases}
\]

(94)

where the excess rebound energy EERE is calculated by the following expression:

\[
E_{\text{ERE}} = \frac{1}{4} \xi^2 (1 - \cos \Theta_k) - 0.12 \cdot \xi^2 \cdot (1 - \cos \Theta_k)^{0.63} \cdot \frac{1}{3} \xi - 1 \leq 0
\]

(95)

Aziz and Chandra [451] studied the impact and solidification of molten tin droplets on a flat steel plate with varying temperature (dp ≈ 2.7 mm and vp = 1–4 m/s). The rebound behavior can be affected if the substrate temperature is below the melting temperature of the droplet. Deformation and maximum spread dp,max are influenced by solidification and smaller compared to studies without a cooled substrate. Aziz and Chandra [451] used the following expression to estimate the maximum spread:

\[
\frac{\xi}{\xi_{\text{max}}} = \frac{3 - \frac{4}{3} \xi^2}{\xi_{\text{max}}^2} = \frac{3}{3} \cdot \frac{W_{\text{Eo}} + 12}{W_{\text{Eo}} + 12 + 1} \cdot \left(1 - \cos \Theta_k\right) + 4 \cdot \left(W_{\text{Eo}}/\sqrt{V_p}\right)
\]

(96)

The parameter S* is the dimensionless thickness of the solidified droplet. It is estimated by:

\[
S^* = \frac{s^*}{d_p} = \frac{s^*}{3} \cdot \frac{3 - \frac{4}{3} \xi^2}{\xi_{\text{max}}^2} = \frac{3}{2} \cdot \frac{k_w - \rho_w \cdot c_p_w}{2 \cdot \pi \cdot P_e - k_p \cdot \rho_p \cdot c_p}_w
\]

(97)

where s is the thickness of the solidified droplet, kw is the wall and particle thermal conductivity, St is the Stefan number, and Pe the Peclet number. The Stefan number is a measure for the duration of the solidification process, and is defined as St = (κp · (Tm – Tw))/Hj, with the heat capacity of the particle cp, the melting temperature of the droplet Tm, the wall temperature Tw, and the latent heat of fusion Hj. The Peclet number is a measure of advective to diffusive transport and defined as Pe = νp · dp · ρp · c_p/κp [451]. Eq. (96) simplifies to Eq. (92) if there is no temperature difference between the droplet and the substrate (S* = 0). Ni et al. [333] used the findings of Aziz and Chandra [451] and applied the given equations for a sticking criterion in slag-flow gasification systems. However, there is no validation of the model. They carried out parameter studies for relatively large ash particles, and used the viscosity model of Browning et al. [314] as well as measurements of the apparent contact angle of Abbots and Austin [350]. Their parameter study showed versatile behavior. Generally, the sticking probability increases with increasing temperature. Sticking was also be found for small particles with low velocities (dp ≪ 1 mm and vp ≪ 1 m/s) and large particles with relatively high impact velocities (dp > 3 mm and vp > 3 m/s) [333].

4.4. Evaluation of sticking criteria

A simple comparison of presented sticking criteria is shown in Table 18. It can be seen that sticking criteria are in agreement on the effect of individual parameters, such as changing particle temperature, diameter, velocity or angle of impaction. Generally, the probability of an ash particle to stick to a heat exchanging surface is high for small particles with high temperatures, which impact with a low velocity and small impaction angle. However, the role of the impact angle is barely understood, mainly due to the scarcity of measurements and the fact of contradictory models and experimental results [428,429]. The models presented in Table 18 require a number of temperature- and composition-dependent properties. One can imagine that with a higher number of parameters, it is more difficult to use such a model. Therefore, simple correlations and equations are favorable over complex models, such as the one of Thornton and Ning [290]. The biggest challenge is to find temperature-dependent properties for different ash particle compositions and structures.

4.5. Role of existing deposit layers and limitations

Most of the sticking criteria described above are developed for a clean, often flat surface with well-defined properties. For such a surface, particle impaction and sticking rates can be predicted, such as the ones shown in Fig. 65(a). Walsh et al. [460] calculated the sticking probability for sodium sulfate-coated calcium aluminosilicate particles and found a narrow range of sizes around 10–15 μm, which is able to deposit. Particles smaller than 10 μm did not impact on the surface since diffusional effects and thermophoresis are not considered. On the other hand, large particles did not stick, which goes along with the sensitivity study shown in Table 18. The sticking probability decreases with increasing particle size. In comparison to a clean surface, there are a number of changes for heat exchanging surfaces in a power plant. Sticking criteria are typically missing effects such as surface roughness or stickiness of the substrate. Once there is a deposit layer (powdery, sintered or molten) the sticking

<table>
<thead>
<tr>
<th>Critical parameter</th>
<th>References</th>
<th>Properties needed</th>
<th>Sticking probability due to increase of</th>
</tr>
</thead>
<tbody>
<tr>
<td>Melt fraction</td>
<td>Zhou et al. [391]</td>
<td>Tp</td>
<td>↑</td>
</tr>
<tr>
<td>Viscosity</td>
<td>Walsh et al. [395]</td>
<td>dp, vp</td>
<td>↑</td>
</tr>
<tr>
<td></td>
<td>Srinivasachar et al. [1]</td>
<td>µp</td>
<td>↑</td>
</tr>
<tr>
<td></td>
<td></td>
<td>µp, ρp</td>
<td>↑</td>
</tr>
<tr>
<td></td>
<td></td>
<td>µw, ρw</td>
<td>↓</td>
</tr>
<tr>
<td>Velocity</td>
<td>Thornton and Ning [290]</td>
<td>νTp, νw, µp, ρp</td>
<td>↓</td>
</tr>
<tr>
<td></td>
<td>Losurdo et al. [342]</td>
<td>νTp, νw, µp, ρp</td>
<td>↓</td>
</tr>
<tr>
<td></td>
<td>Brach and Dunn [428]</td>
<td>νTp, νw, µp, ρp</td>
<td>↓</td>
</tr>
<tr>
<td>Spread diameter</td>
<td>Pasanideh-Fard et al. [333,390,441]</td>
<td>µp, νp, µw, ρw</td>
<td>↓</td>
</tr>
</tbody>
</table>
tendency changes due to changed surface properties. This is particularly challenging when describing the deposit build-up. Fig. 65(b) illustrates the process of deposit formation. A clean tube collects only sticky particles, which then solidify as long as the layer is thin [395]. With an increasing deposit layer, the surface temperature increases becoming sticky itself, causing an increase in collection efficiency. Non-molten, dry ash particles can adhere to a sticky surface. The viscosity approach of Walsh et al. [395], is one of the few approaches considering the stickiness of the surface. They use the following equation to describe the net mass fraction sticking to the surface \( p_{\text{stick, tot}} \):

\[
p_{\text{stick, tot}} = p_{\text{stick, p}}(T_g) + [1 - p_{\text{stick, p}}(T_g)] 
- k_e [1 - p_{\text{stick, p}}(T_g)] - [1 - p_{\text{stick, w}}(T_W)],
\]

(98)

where the particle and wall sticking probabilities are calculated, using Eq. (71). The viscosity in Eq. (71), can be calculated using the corresponding particle and wall temperature in combination with the chemical composition. The parameter \( k_e \) describes the erosivity of the dry ash particles towards the deposit. The overall deposit growth rate in mass per unit area and time, can be calculated according to [395]:

\[
\frac{1}{A} \frac{dm_{\text{dep}}}{dt = f_{\text{imp}} \cdot p_{\text{stick, tot}} - k_{\text{shed}} \cdot \left( \frac{m_{\text{dep}}}{A} \right)^{1/\omega_u}},
\]

(99)

where \( A \) is the projected area of the tube in a plane perpendicular to the undisturbed flow direction, \( f_{\text{imp}} \) is the mass of ash particles impacting on the tube per unit time and unit projected area in kg/(m²s), \( \omega_{\text{shed}} \) is the order of the shedding process, and \( k_{\text{shed}} \) is the shedding frequency in 1/s when \( \omega_{\text{shed}} = 1 \) [265,395]. For long periods, the deposit mass per area approaches the following expression:

\[
\frac{m_{\text{dep}}}{A} \rightarrow_\infty = \left( \frac{f_{\text{imp}} \cdot p_{\text{stick, tot}}}{k_{\text{shed}}} \right)^{1/\omega_u}.
\]

(100)

This expression is however only valid if sintering or changes in deposit strength do not occur [395]. Further investigations of particles impacting a powdery or liquid layer are discussed in Section 5.3, dealing with the particle rebound. Another very critical factor is the heterogeneity of ash particles. Often sticking criteria use bulk ash chemistry to calculate deposition rates. An individual treatment on a particle-by-particle basis is essential. A low melting iron-sulfide particle might stick at temperatures as low as 1000 °C, whereas a quartz particle needs temperatures above 1600 °C. However, finding temperature-dependent properties for all possible chemical compositions of ash particles is rather impossible.

Therefore, due to the large diversity of ash particles in terms of chemical composition, size, density and shape, it is straightforward to use simple sticking criteria, without the need of knowing all particle and wall properties, e.g. Young’s modulus, Poisson’s ratio, contact angle or viscosity.

### 4.6. Parameters affecting the stickiness and Poisson ratio

Most ash particle sticking criteria are based on ideal conditions, when spherical particles or droplets impact on a flat solid surface. However, within solid fuel-fired boilers different and much more complex scenarios can occur. Fig. 66 summarizes a number of possible phenomena. Ash particles can be trapped by a molten sticky layer, as outlined in the previous section. Furthermore, a solid, powdery deposit can act as a filter element for particles. The flow might be able to penetrate the inside of the deposit, however, the particles are not. They are collected by the porous structure. Condensation and/or chemical reactions of alkali vapors with fly ash particles can change the stickiness as found by Wibberley and Wall [406].

A thin, low viscosity layer forms around silicate ash particles and allows particles to deposit on a cooled steel surface (600 °C) free from condensed material [406]. Another mechanisms is the cementation of solid fly ash particles. Particles impacting on the surface are followed by a molten droplet acting as a glue between the surface and the fly ash particle. This mechanism, however, is difficult to verify in experiments. A further interesting aspect is the deposition of unburnt char containing molten and/or solid ash grains. The remaining char will oxidize and ash remains on the heat exchanging surface. This mechanisms is mainly reported for entrained flow gasifiers. Another phenomena could be the sintering and reaction of particles during the contact. However, experimental evidence is again missing.

Rarely discussed is the deposition of agglomerates or thermal effects at the interface as shown by the last two mechanisms. The ash particle shape is often ignored in literature. Fly ash particles are commonly irregular formed agglomerates with different impaction, and deformation behavior. An agglomerate is able to dissipate kinetic energy by rearrangement of its structure and therefore its sticking probability might be higher compared with spherical particles of the same size. Furthermore, its impact velocity is lower compared with a spherical particle at the same flow conditions due to its high surface to volume ratio and thus its high drag coefficient. An aspect that misses in Fig. 66 is the formation of a scale and/or oxide layer. The dynamics of oxide layer formation is illustrated in Fig. 67. The following steps are reported [66]:

---

*Fig. 65. Ash deposition in PF fuel combustion: (a) particle size distribution, calculated impaction efficiency, and sticking probability for a lignite [460], and (b) layer formation and growth for a bituminous coal [395]. Reprinted with permission from Walsh et al. [460]; copyright 1992 American Chemical Society.*
Step 1: The formation of a thin, initial oxide layer due to oxidation. It is expected that ash particles do not play a significant role here. However, the presence of gaseous chlorine or SO$_2$/SO$_3$ significantly increases the rate of layer formation.

Step 2: In the following step, the oxide layers starts to grow due to the higher diffusion rate of iron compared with chromium and nickel. Alkali chloride or alkali sulfate vapors begin to condense on the oxide layer. Reactions between Cl/S and the oxide layer further increase the growth and porosity, where the porosity might be caused by the release of volatile metal chlorides. Furthermore, it was found that an increasing K-content in the ash leads to a strong increase in oxide layer thickness, as shown in the SEM images (c)–(e) in Fig. 67.

Step 3 and 4: Cracks and gaps form in the oxide layer, as shown in Fig. 67(b). Detachment can occur due to thermal stresses or growth stresses between different layers. An increase in surface temperature leads to an accelerated particle collection promoting ash deposition. The temperature increase is caused by the insulating oxide layer and/or by detachment and insulating gas between oxide layers. Higher ash accumulation rates increase the chlorine content in the deposit enhancing corrosion rate.

Depending on the chemical bonding between the interfaces, oxide layers might detach, and existing deposits and oxide layers are removed, leading to a repetition in the above-mentioned steps [66].
are compared: 
Particle impact are presented in Table 19. Three different scenarios of parameters and their ranges, as well as energies involved during sticking and rebound criterion. A comparison studying ash deposition, however, it can play an important role. It is tagged P

T a g g e d P

reactions with three synthetic ashes at 600 °C for 15 hours with 7, 15 and 20 wt.% K2O, respectively (rest is composed of: SiO2, D 2 5 X X

Fig. 67. Formation of scale and oxide layer leading to enhanced ash particle collection and corrosion (mechanism and SEM images from [66]). SEM images (a) and (b): cross-section and top view of a scale layer on a X20CrMoV12-1 steel after 5 hour exposure to a co-firing ash at 600 °C; SEM images (c), (d) and (e): scale and deposit morphologies after reactions with three synthetic ashes at 600 °C for 15 hours with 7, 15 and 20 wt.% K2O, respectively (rest is composed of: SiO2 = 37, Fe2O3 = 1, Al2O3 = 3, CaO = 5 and Na2O = 5 wt.%).

The oxide layer formation is often neglected, or not mentioned when studying ash deposition, however, it can play an important role. It is essential to estimate and know relevant mechanisms, when developing an ash particle sticking and rebound criterion. A comparison of parameters and their ranges, as well as energies involved during particle impact are presented in Table 19. Three different scenarios are compared:

- First, the deposition of a small, sub-micron, salt-rich ash particle formed by inorganic vapor condensation. This particle slows down drastically inside the boundary layer and migrates with a very small velocity magnitude to the surface. The particle temperature is identical to the superheater tube during impact.
- Second, the deposition of a large, massive Fe-rich particle. The particle originates from pyrite and forms a low melting eutectic.

Table 19

Parameters and properties of fly ash particles upon contact with heat exchanging surface. Values are used for estimating energies involved during sticking and rebound. Lower boundary is estimated for a sub-micron salt particle at low temperatures, upper boundary for a large, Fe-rich and low melting particle, and a typical aluminosilicate particle with 20 μm.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Symbol</th>
<th>Unit</th>
<th>small salt-rich</th>
<th>large Fe-rich</th>
<th>typical Al-Si</th>
</tr>
</thead>
<tbody>
<tr>
<td>Particle temperature</td>
<td>( T_p )</td>
<td>°C</td>
<td>500</td>
<td>1200</td>
<td>1100</td>
</tr>
<tr>
<td>Particle velocity</td>
<td>( v_p )</td>
<td>m/s</td>
<td>0.1</td>
<td>15</td>
<td>7</td>
</tr>
<tr>
<td>Particle diameter</td>
<td>( d_p )</td>
<td>μm</td>
<td>0.01</td>
<td>100</td>
<td>20</td>
</tr>
<tr>
<td>Particle density</td>
<td>( \rho_p )</td>
<td>g/cm³</td>
<td>2.0</td>
<td>5.5</td>
<td>2.6</td>
</tr>
<tr>
<td>Particle viscosity</td>
<td>( \mu_p )</td>
<td>Pa s</td>
<td>10⁻³</td>
<td>10⁻²</td>
<td>10⁻¹</td>
</tr>
<tr>
<td>Particle surface tension</td>
<td>( \gamma_p )</td>
<td>m</td>
<td>0.6</td>
<td>0.2</td>
<td>0.4</td>
</tr>
<tr>
<td>Contact angle with substrate</td>
<td>( \theta )</td>
<td>°</td>
<td>160</td>
<td>40</td>
<td>120</td>
</tr>
<tr>
<td>Particle kinetic energy</td>
<td>( E_{kin, p} )</td>
<td>J</td>
<td>5.8 \times 10⁻²⁴</td>
<td>3.2 \times 10⁻⁷</td>
<td>3.3 \times 10⁻¹⁰</td>
</tr>
<tr>
<td>Particle potential energy</td>
<td>( E_{pot, p} )</td>
<td>J</td>
<td>1.1 \times 10⁻²⁵</td>
<td>2.8 \times 10⁻¹³</td>
<td>1.3 \times 10⁻¹⁵</td>
</tr>
<tr>
<td>Particle adhesion energy</td>
<td>( E_{ad, p} )</td>
<td>J</td>
<td>1.1 \times 10⁻¹⁸</td>
<td>2.7 \times 10⁻⁹</td>
<td>9.2 \times 10⁻¹²</td>
</tr>
<tr>
<td>Particle deformation energy</td>
<td>( E_{def, p} )</td>
<td>J</td>
<td>7.0 \times 10⁻¹⁵</td>
<td>9.3 \times 10⁻⁸</td>
<td>6.9 \times 10⁻¹⁰</td>
</tr>
<tr>
<td>Particle van der Waals energy</td>
<td>( E_{v, p} )</td>
<td>J</td>
<td>6.4 \times 10⁻¹⁶</td>
<td>1.6 \times 10⁻¹⁰</td>
<td>2.6 \times 10⁻¹²</td>
</tr>
<tr>
<td>Particle friction energy</td>
<td>( E_{fr, p} )</td>
<td>J</td>
<td>2.5 \times 10⁻²⁰</td>
<td>1.5 \times 10⁻¹²</td>
<td>1.1 \times 10⁻¹⁶</td>
</tr>
<tr>
<td>Sticking probability (energy balance) ( \gamma E_f )</td>
<td>( \rho_{mink} )</td>
<td>–</td>
<td>1</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>Particle Stokes number</td>
<td>( St )</td>
<td>–</td>
<td>2.3 \times 10⁻⁹</td>
<td>5.7 \times 10⁻¹</td>
<td>6.0 \times 10⁻¹</td>
</tr>
<tr>
<td>Particle Knudsen number</td>
<td>( Kn )</td>
<td>–</td>
<td>4.1 \times 10⁻¹</td>
<td>8.6 \times 10⁻³</td>
<td>3.7 \times 10⁻²</td>
</tr>
<tr>
<td>Particle Reynolds number</td>
<td>( Re_p )</td>
<td>–</td>
<td>2.2 \times 10⁻¹⁰</td>
<td>8.3 \times 10⁻⁴</td>
<td>3.9 \times 10⁻³</td>
</tr>
<tr>
<td>Particle Weber number</td>
<td>( We_p )</td>
<td>–</td>
<td>3.7 \times 10⁻⁴</td>
<td>6.2 \times 10⁴</td>
<td>6.8 \times 10⁹</td>
</tr>
<tr>
<td>Particle spread factor</td>
<td>( \zeta )</td>
<td>–</td>
<td>0.11</td>
<td>2.7</td>
<td>0.21</td>
</tr>
<tr>
<td>Particle spread factor</td>
<td>( \zeta )</td>
<td>–</td>
<td>0.81</td>
<td>2.2</td>
<td>0.58</td>
</tr>
</tbody>
</table>

\( a \) small particles migrate to the surface and have the local gas temperature. 
\( b \) calculated using a distance between the particle and the surface of \( \Delta = 10 \) nm [462,463].
\( c \) calculated using the Hamaker constant of \( A_H = 7 \times 10⁻²⁵ \) J [462,463].
\( d \) calculated using a friction coefficient of \( f = 0.2 \).
\( e \) estimated using different viscosity values.
\( f \) \( E_{fr, p} \) and \( E_{pot, p} \) minus the remaining energies. 
\( g \) calculated with a tube diameter of \( D = 30 \) mm, and the viscosity of N₂ at a gas temperature equal to \( T_p \). 
\( h \) mean free path length calculated for a gas temperature equal to \( T_p \) with Eq. (17).
(Fe-O-S melt) caused by reducing furnace conditions. The particle is not affected by the boundary layer and its temperature is identical compared to the flue gas temperature of $T_{\text{fl}} = 1200 ^\circ \text{C}$. The particle velocity is also unchanged at high values of $15 \text{ m/s}$.

- And third, a typical aluminosilicate (Al–Si) particle with a size of $20 \mu \text{m}$ impacting with moderate velocity of $7 \text{ m/s}$. This particle is difficult to judge since it could be affected by the boundary layer depending on the position and angle of impact.

For all three particles, a normal impact, at the front face of a cylinder (superheater tube with diameter of $30 \text{ mm}$), is assumed. Particle properties are estimated using equations from Section 3, or taken from literature. The particle viscosity shows the largest deviation. The sub-micron particle is solid with a relatively high, estimated value of $\mu_p \approx 10^{12} \text{ Pa} \cdot \text{s}$, compared to the very low value of $\mu_p \approx 10^{-2} \text{ Pa} \cdot \text{s}$ for the Fe-rich particle. The variation in surface tension is low as long as particles are liquid. In the case of solid particles, surface energy values have to be used. Using these values, energy ranges can be calculated. The particle kinetic energy for instance spans over 17 orders of magnitude. All calculated energy values are illustrated in Fig. 69. The calculation of a potential energy is questionable since particles do not drop from a certain height, instead, they are entrained in the flow. However, it is shown that potential energy is orders of magnitude smaller, compared to other energy values and thus negligible. The energy loss caused by frictional forces can be estimated using the following relation:

$$E_{\text{fr,p}} = -f \cdot F \cdot \zeta \cdot d_p$$  \hspace{1cm} (101)

where $f$ is the friction coefficient, $F$ is the net force acting on a settled particle, and $\zeta \cdot d_p$ is the contact diameter between the ash particle and the substrate. The net force $F$ can be a combination of forces acting at the interface, as illustrated in Fig. 59. Depending on this force, the friction coefficient can differ quite significantly, however, it is relatively small compared to the particle kinetic energy. The estimation of energy losses due to van der Waals forces is difficult. Van der Waals forces are known as the non-covalent interaction between atoms or molecules at interfaces. Fig. 68(a) shows how momentary dipoles form at the interface due to random movement of electrons. The majority of particles carry a small net charge that will lead to an attractive force to an opposing charge found at surfaces. The dipoles and resulting forces contribute to particle adhesion alongside with surface tension effects and electrostatic forces [158,244]. Fig. 68(b) shows the impact of rough surfaces on a microscopic scale. There are only few contact points and contact surface area is reduced. The van der Waals energy can be viewed as the work/energy required to separate two bodies in contact, without other forces such as adhesion, gravity. The energy due to van der Waals forces between a sphere and a wall can be calculated according to the following equation [462,463]:

$$E_{\text{vdw}} = A_H \cdot \frac{d_p}{12 \cdot \Delta}$$  \hspace{1cm} (102)

where $A_H$ is the Hamaker constant set to a value of $A_H = 7 \cdot 10^{-20} \text{ J}$ and $\Delta$ is the distance between the particle surface and the wall as shown in Fig. 68(b). This distance is difficult to estimate. If two perfectly smooth bodies are in contact, their distance might be in the range of $\Delta \approx 0.2 \text{ nm}$. However, most ash particles are not perfectly smooth, leading to much higher values of $\Delta \approx 10 \text{ nm}$ [463]. Eq. (102) predicts considerably higher energy values due to van der Waals forces, compared to friction and potential energy. Values are slightly lower, compared with adhesion energy. The adhesion energy of a particle in contact with a substrate is calculated using Eq. (141), introduced later on. The contact area and the contact angle between the deformed particle and the surface are crucial. By far the highest energy losses are due to particle deformation no matter if the particle is solid or liquid. In Table 19 it is assumed that the small salt-rich particle has an extrapolated, high viscosity. The work against viscosity required to deform the particle to the predicted spread factor $\zeta$
can be as high as its kinetic energy. In this case, all energy is dissipated, and the particle will stick if the connectivity between the substrate and the particle surface is high enough to overcome shear forces, caused by the flow. The error in predicting the deformation energy for small, high viscosity particles is expected to be high, and future research should be directed towards this issue. A further mechanism which might be of relevance is the thermal expansion coefficient, which can vary with temperature and material. Thermal stresses at the interface can occur leading to a detachment and re-entrainment of a fly ash particle. The sticking probability can be judged using Table 19. When the energy loss due to deformation, adhesion and van der Waals forces exceed the kinetic and potential energy, the particle will stick. Comparing all three cases, surprising results can be observed. The small, salt-rich particles and Al-Si particle stick, whereas the large, low viscosity, Fe-rich particle will rebound. The small particle sticks since it has an almost negligible adhesion and van der Waals forces large enough to cause deposition/sticking. In the case of the Al-Si, the deformation and thus, the work against viscosity, leads to the sticking behavior. On the contrary, the kinetic energy of the Fe-rich particle is too high and cannot be completely dissipated, even though the deformation is high ($\zeta > 2$).

Table 19 further gives dimensionless numbers. The Stokes number in a power plant can range from extremely low values of $St \approx 10^{-9}$ up to $St \approx 60$. Inertial impaction becomes dominant at around $St \approx 0.5$, which is in the region of a 20 $\mu$m particle (see Fig. 26). The Knudsen number ranges from low values for large particles to high values for the sub-micron particle. Thus, sub-micron particles do not follow the Stokes drag law and the thermal conductivity ratio does not influence thermophoretic force. The particle Reynolds number ($Re_p = \rho_p \cdot v_f \cdot d_p/\mu_p$) and Weber number also span over more than ten orders of magnitude. This huge spread is the main problem for finding generally valid correlations. It can be seen that the particle spread factor can differ significantly for small particles when using different correlations. The correlation of Mao et al. [390] predicts higher spread factors and thus higher dissipation rates compared with correlations suggested by Chandra and Avedisian [435].

4.7. Sticking behavior of aerosols

Experimental studies dealing with aerosol impaction and deposition are rare. The main difficulty is the small particle size. Particles are difficult to handle and not visible with standard optical devices such as camera systems. Most of the work is theoretical in nature and uses models to predict aerosol sticking. Often it is assumed that every aerosol that impacts on a wall will stick. The common believe is that they are kept along surfaces by relatively weak van der Waal and electrical forces. However, experimental evidence is still due. A lot of work on aerosol deposition was conducted in the filtration industry, e.g. the work of Wang and Kasper [467]. They compare the critical velocity with typical particle impact velocities and derive laws and models for the filtration efficiency. According to their study, the mean particle impact velocity for the diffusion-dominated particle impaction regime is characterized by its thermal velocity following the Maxwell-Boltzmann distribution analogously to Eq. (14):

$$v_{imp} = v_{thermal} = \frac{48 \cdot k_B \cdot T_g}{\pi \cdot \rho_p \cdot d_p^2} \quad (103)$$

The critical velocity is calculated in the work of Wang and Kasper [467], by equating the elastically stored kinetic energy of the particle and the adhesion energy $E_{ad}$ according to:

$$v_{cr} = \sqrt{\frac{2 \cdot E_{ad}}{\rho_p \cdot d_p^2}} \quad (104)$$

The parameter $e$ stands for the restitution coefficient, which will be introduced later on in Section 5. For nano-particles or molecules, the coefficient of restitution is commonly assumed to be unity, hence a perfectly elastic collision without energy losses [467]. When using Eq. (104), an expression for the adhesion energy is needed. One approach goes back to the work of Bradley [475] and Hamaker [462], referred to as the Bradley–Hamaker adhesion energy. It integrates all molecular attractions over the entire volume. Substituting their expression in Eq. (104), leads to the following expression:

$$v_{cr,B-H} = \sqrt{\frac{A_H}{\pi \cdot \rho_p \cdot d_p^2 \cdot \Delta}} \quad (105)$$

where $A_H$ is again the Hamaker constant and $\Delta$ the minimum separation between particle surface and wall. The main drawback of the B-H theory is that it assumes point contact between the particle and wall, where in reality a finite contact area forms [467]. Another commonly used model, which overcomes this shortcoming, goes back to the JKR model [431]. The JKR theory calculates the critical velocity by:

$$v_{cr,JKR} = \sqrt{\frac{3^{3/4} \cdot (k_w + k_p)^2 \cdot \sigma_{fw}^5}{\rho_p^4 \cdot d_p^2}} \quad (106)$$

where $k_w, k_p$ are again the elasticity parameters of wall and particle, and $\sigma_{fw}$ is the specific adhesion energy at the interfacial contact area. Another interesting theory was presented by Derjaguin et al. [476], who studied the effect of contact deformations on the adhesion of particles and reported that the adhesion energy is equivalent to the first power of the particle diameter. The same dependency is predicted when using Eq. (105). Slightly different is Eq. (106), where the critical velocity varies with $d_p^{5/6}$. A comparison of different equations is shown in Fig. 70. It can be seen that both models predict

![Fig. 70. Comparison of particle mean thermal velocity with critical velocity values predicted using different theories and measured critical velocities (adopted from Wang and Kasper [467], measurements from [415,419,468]). Parameters for the prediction of curves are: $A_H = 0.7 \cdot 10^{-20}$ J, $\Delta = 0.4$ nm, $\rho_p = 2$ g/cm$^3$, $k_w, k_p = 5 \cdot 10^3$ N/m, $\sigma_{fw} = 0.04$ J/m$^2$.](image-url)
quite similar results: an increasing critical velocity with decreasing particle diameter. Interesting is the behavior of the mean thermal impact velocity $v_{\text{imp}}$, which increases strongly as the particle size becomes smaller. According to this theory, particles smaller than $d_p = 2$ nm will rebound. This controversy effect is known as thermal rebound [473]. However, for ash deposition it is most likely not relevant, since, even aerosols are significantly larger. As shown in Fig. 70, all larger particles will stick. Since typical combustion aerosols are much larger, with sizes around 100-300 nm, it is confirmed that these particle will stick no matter of bulk flow conditions or temperatures. However, a recent experimental study reported a different behavior for nanoparticles. Rennecke and Weber [468] used for the first time a low pressure impactor in order to determine the critical velocity of nanometer-sized NaCl and Ag particles on a mica substrate, avoiding contact charging. The authors used the JKR theory assuming full plastic failure of the particle during the approach regime, adhesion during particle rebound and constant hardness as well as constant surface energy during collision. With these assumptions Weir and McGavin [469] derived the following equation:

$$v_{\text{cr,JKR}} = \sqrt{\frac{16 \cdot \gamma^2}{3^{1/4} \cdot 5 \cdot \rho_p \cdot Y \cdot d_p^2}}$$

(107)

where $\gamma$ is the surface energy. Parameters for Eq. (107) can be found in Table 20. Rennecke and Weber [468] found a relatively steep curve for the particle critical velocity, which implies that particles around 50 nm rebound above velocities much smaller than predicted by the JKR and B-H model. They further showed a relatively high critical velocity for porous NaCl particles compared with dense NaCl particles. This is useful information for aerosols, which are typically agglomerates, and thus, also porous. Hence, it is assumed that agglomerates dissipate much kinetic energy during collision due to deformation and rearrangement and, thus, have a high sticking probability. It was further predicted that very small particles experience plastic deformation, which is in contradiction to previous studies assuming that aerosols impact perfectly elastic. There are many unknown phenomena and to date there are only few experiments in this area. Further studies should focus on a combination of experimental work and new modeling approaches, such as improved theories implementing a reduced particle stiffness [474]. The goal should be a comprehensive model being able to predict nanoparticle sticking and rebound.

Two important characteristics for aerosol deposition on heat exchanging surfaces are illustrated in Fig. 71. Fig. 71(a) shows the effect of a porous deposit layer collecting all incoming particles. If particles are small, inertia is low and the probability of shedding diminishes. All incoming particles are collected no matter if they are sticky or not. A second important parameter is the particle shape. As illustrated in Fig. 71(b) agglomerates impact on a wall, deform and rearrange their structure. It is assumed that a large fraction of the particle kinetic energy is dissipated during this process, leading to an increased sticking efficiency of agglomerates compared with perfectly spherical ash particles. However, further work in this field is needed.

Further frequently cited aerosol deposition models can be found in health studies dealing with particle deposition in the respiratory tract. Typical particle capture efficiencies as a function of particle size can be seen in Fig. 72. These models incorporate particle impact and sticking efficiency in the form of the capture efficiency. It can be seen that very small and coarse particles are captured within the respiratory tract, whereas only 20–30% of particles with a size of around 400 nm reach the surface and stick. The capture efficiency depends on the breathing frequency and the tidal volume, and thus, the channel diameter. Various, mostly empirical models have been developed and used to validate experimental results. Predictions show that only smallest particles are able to travel down to the alveolar, whereas larger particles deposit much earlier in the bronchial and extrathoracic tract. In general, an increased capture efficiency is observed for a larger tidal volume, probably caused by lower velocities and increased residence times. The application of health models for ash deposition studies is questionable. Physics of both, particles and deposition surface are quite different. Furthermore, they are based on an internal flow problem, compared with an external flow around tubes and along walls within a power plant.

In general, aerosol deposition behavior is relatively unknown. Only few experimental studies can be found and their applicability to boilers is questionable. The role of higher temperatures and rough surfaces might change the deposition process significantly. Furthermore, strong temperature gradients lead to an increased deposition velocity, as shown and discussed in Section 2.5.2. More or less
unknown is the role and effect of electrostatic forces during impaction on heat exchangers in solid fuel fired boilers. Further work is needed in particular for aerosols and agglomerates at high temperatures. In addition, studies should focus on how aerosols affect the deposit formation and consolidation over time.

4.8. Overview on modeling studies

Modeling solid fuel combustion, ash formation and deposition started using one-dimensional stand-alone tools. There are various studies reporting good agreement of ash formation models with measurements, such as the work of Kang et al. [477,478], who calculated time-dependent char combustion and coalescence of ash grains with a cluster composed of char and ash sites. In this model, oxidation leads to particle shrinkage and partial coalescence of ash or char fragmentation. Monroe [23] studied ash formation at the MIT and developed a stand-alone tool based on Monte Carlo simulations of single coal particles for the prediction of ash formation. An interesting work was proposed by Charon et al. [85] and Barta et al. [72], the so-called “urn”-model, as mentioned earlier. This model enables the prediction of ash PSD and chemistry, simultaneously. A number of eleven mineral classes is used, which might be too low in order to predict the vast variance among fly ash particles, and their chemistry. Nevertheless, the approach is promising. Another highlight is the work of Wilemski and Srinivasachar [104], who used a scaled Monte Carlo simulation for mineral distribution. Char conversion includes a fragmentation model and considers different char structures. Good agreement for a bituminous coal is reported, whereas a second coal fails. The authors underline the importance of knowledge on the non-random mineral distribution and char structure. In general, most of the above mentioned stand-alone models report relatively good agreement with measured particle size distribution. These fundamental models are much more sophisticated compared with current CFD methods. Models predicting both, ash PSD and chemistry, are rare and require in-depth fuel characterization methods. Early deposition models used an Eulerian approach and go back to Friedlander and Johnstone [217]. In this model, there is no slip between the gas flow and the particle velocity. The concentration of particles in the flow parallel to the wall, is used to estimate a deposition rate. It is assumed that turbulent diffusion leads to particle transport towards the laminar sublayer. Only particles with high velocities are able to penetrate through this layer. However, this velocity has to be estimated and leads to high uncertainties. Baxter and DeSollars [13] developed the standalone code ADLVIC, which includes inertial impaction, thermophoresis, condensation, chemical reactions and uses bulk ash composition in order to predict the deposit chemistry. A good agreement with measurements is reported. Further standalone tools are included in the “Fuel Quality Advisor” developed at the Electric Power Reasearch Institute (EPRI). They include FOULER and SLAGGO, which have several submodels for ash formation, mineral transformation, and ash deposition. They predict the heat penalty caused by deposits. A similar code is developed at the University of North Dakota called LEADER predicting fouling propensities inside a boiler [57]. An inclusion of these or other sophisticated models in a CFD code enables the prediction of fuel conversion, slagging and fouling locations, their extent, and the optimization of operation or design. However, the incorporation of such standalone models into CFD codes is lacking behind [70]. Often too simple models are used, which may lead to wrong conclusions. A comprehensive overview of CFD studies on industrial boilers or pilot-scale test-rigs, is given in Table 21. Most studies on predicting ash deposition can be found for PF systems. There are some studies dealing with grate and FB combustion, however, modeling the combustion and ash formation process in fixed or moving beds is challenging. An overview on CFD studies dealing with FB can be found in the work of Singh et al. [479].

Among the pioneers in using CFD codes for the prediction of slagging and fouling are the studies of Boysan et al. [398], who calculated the rate of char impacting on walls, Richards et al. [408], and Wang and Harb [480]. Both of the latter two studies used the PCGC code, developed at the Brigham Young University. Richards et al. [408] applied two-dimensional simulations for a 1 MWth test facility to calculate deposition rates. A first three-dimensional model was applied for a PF boiler, by Wang and Harb [480]. The PCGC code uses a different particle treatment compared with Lagrangian tracking, where particle clouds and their transport are calculated instead of individual tracks. Particle impaction and deposition rates are estimated based on particle concentrations near the walls. The authors use the viscosity concept of Walsh et al. [395] to calculate the deposition of a representative number of particles. The positions, at which slagging and fouling rates were predicted inside a boiler, were reduced to approximately 100–200 [480] and deposition rates were interpolated in between. Pseudo-transient calculations are used to account for deposit stickiness. A highlight is the use of CCSEM data, which enables the prediction of deposit chemistry. Many of today’s CFD studies are still not able to predict chemistry and do not consider individual particle composition.

Lee and Lockwood [492] studied ash deposition of three British coals in a small combustion test rig using the CFD code CINAR. They use CCSEM data to predict fly ash composition in a pre-processor. A specified number of particle size classes and chemistry classes are used. This enables the prediction of deposit chemistry. Lee and Lockwood [492] used a critical velocity and viscosity approach. Particles with a velocity higher than the critical value are able to reach the wall. In the next step the viscosity decides whether a particle sticks or not. An increased iron deposition was found for early stages, whereas in later stages, the deposition composition was similar to the fly ash.

Bozić [184] used the code FLOREAN of University of Braunschweig to predict mineral transformation and deposition. He used a post-processor and included 50 mineral matter transformation processes, in which chemical reactions and their kinetics, diffusion limitations, fusion, crystal and glass formation are incorporated. This process is highly complex, but enables studying the role of atmosphere and time on ash deposition. This model was further used and improved by Strelow [488]. Both report a relatively good agreement.

![Fig. 72. Capture efficiency of aerosols in the respiratory tract as a function of particle size (unit density spheres), volume and breathing frequency in respiratory tract. Data points in figure: squares: tidal volume of 2000 cm³ and breathing frequency of 3.75 min⁻¹; circles: 1000 cm³ and 7.5 min⁻¹. Data compiled from different studies [464–466].](image-url)
Table 21
Overview of CFD studies predicting fly ash formation and deposition in GF, FB and PF combustion systems. Modified and extended from Weber et al. [384].

<table>
<thead>
<tr>
<th>References</th>
<th>System*</th>
<th>Fuel</th>
<th>Code</th>
<th>Turbul. model</th>
<th>Radiation modelb</th>
<th>Particle transp.</th>
<th>Devol. modelc</th>
<th>Char Comb.d</th>
<th>Ash formation</th>
<th>Ash chemistry</th>
<th>Sticking criteria</th>
<th>Deposition mechanisms*</th>
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<td></td>
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<td></td>
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<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Wang and Harb 1997 [480]</td>
<td>PF: 85 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>bit. coal</td>
<td>PCGC-3</td>
<td>k – e</td>
<td>DO</td>
<td>LT</td>
<td>TR</td>
<td>own model</td>
<td>mineral distr. based on</td>
<td>CCSEM, using full,</td>
<td>n.s.</td>
<td>IN</td>
<td>boiler walls</td>
</tr>
<tr>
<td>Bernstein et al. 1999 [481]</td>
<td>PF: 800 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>brown coal</td>
<td>Fluent</td>
<td>n.i.</td>
<td>n.i.</td>
<td>n.i.</td>
<td>n.i.</td>
<td>n.i.</td>
<td>n.s.</td>
<td>melting curve</td>
<td>IN</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Fan et al. 2001 [482]</td>
<td>PF: 300 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>hard coal</td>
<td>in-house</td>
<td>k – e</td>
<td>Monte-Carlo</td>
<td>LT</td>
<td>SR</td>
<td>own model</td>
<td>bulk ash</td>
<td>Walsh</td>
<td>IN</td>
<td></td>
<td>boiler walls</td>
</tr>
<tr>
<td>Eddings et al. 2001 [483]</td>
<td>PF: 900 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>bit. coal</td>
<td>GLACIER</td>
<td>k – e</td>
<td>n.s.</td>
<td>n.s.</td>
<td>n.s.</td>
<td>separate treatment for</td>
<td>pyrite stand-alone tool, fly ash as separate injection</td>
<td>bulk ash</td>
<td>Walsh, Senior</td>
<td>IN, TP, EI</td>
<td>boiler walls</td>
</tr>
<tr>
<td>Richter 2002 [484]</td>
<td>PF: 450 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>brown coal</td>
<td>AIOLOS</td>
<td>k – e</td>
<td>LT</td>
<td>SR</td>
<td>KD</td>
<td>melting curve</td>
<td>IN</td>
<td>free-board, boiler walls</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Müller et al. 2003 [485]</td>
<td>BFB: 35 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>wood</td>
<td>Fluent</td>
<td>k – e</td>
<td>DO</td>
<td>LT</td>
<td>own model</td>
<td>thermodynamic equilibrium, calculations</td>
<td>16 minerals for 4 size fractions</td>
<td>individual particles n.s.</td>
<td>melting curve</td>
<td>IN, furnace walls</td>
<td></td>
</tr>
<tr>
<td>Bozić 2003 [184]</td>
<td>PF: 600 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>lignite</td>
<td>FLOREAN</td>
<td>k – e</td>
<td>flux model</td>
<td>LT</td>
<td>SR</td>
<td>KD</td>
<td>melting curve</td>
<td>IN, TP, EI</td>
<td>platen superheater, tubes</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Müller et al. 2005 [486]</td>
<td>BFB: 295 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>peat/forest residue</td>
<td>Fluent</td>
<td>k – e</td>
<td>DO</td>
<td>LT</td>
<td>SR</td>
<td>own model</td>
<td>based on measurements of fly ash, ash particles released from the freeboard</td>
<td>two particle types n.s.</td>
<td>melting curve</td>
<td>IN</td>
<td></td>
</tr>
<tr>
<td>Kar et al. 2006 [487]</td>
<td>GF: 8.3 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>straw</td>
<td>Fluent</td>
<td>k – e</td>
<td>DO</td>
<td>LT</td>
<td>SR</td>
<td>own model</td>
<td>melting curve</td>
<td>IN, TP, EI</td>
<td>platen superheater, tubes</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Lundmark et al. 2010 [488]</td>
<td>BFB: 295 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>peat/forest residue</td>
<td>Fluent</td>
<td>k – e</td>
<td>DO</td>
<td>LT</td>
<td>SR</td>
<td>own model</td>
<td>bulk ash</td>
<td>none</td>
<td>n.s.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Vuthaluru et al. 2011 [489]</td>
<td>PF: 330 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>sub-bit. coal</td>
<td>Fluent</td>
<td>k – e</td>
<td>P1</td>
<td>LT</td>
<td>SR</td>
<td>KD</td>
<td>melting curve</td>
<td>IN, FP</td>
<td>platen superheater, tubes</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Strelow 2013 [490]</td>
<td>PF: 944 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>lignite</td>
<td>FLOREAN</td>
<td>k – e</td>
<td>flux model</td>
<td>LT</td>
<td>SR</td>
<td>KD</td>
<td>identification of regions based on particle tracks</td>
<td>mineral distribution/transformations, based on oxide analysis</td>
<td>n.s.</td>
<td>IN</td>
<td>boiler walls</td>
</tr>
<tr>
<td>Taha et al. 2013 [491]</td>
<td>PF: 518 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>coal-meat &amp;</td>
<td>CFX</td>
<td>k – e</td>
<td>DO</td>
<td>LT</td>
<td>SR</td>
<td>KD</td>
<td>melt fraction</td>
<td>IN</td>
<td>location on boiler walls</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Kreutzkam 2014 [492]</td>
<td>PF: 350 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>bit. coal</td>
<td>Fluent</td>
<td>k – e</td>
<td>DO</td>
<td>LT</td>
<td>SR</td>
<td>KD</td>
<td>char fragmentation, influences remaining PSD, full coalescence was assumed</td>
<td>condensed condensation and aerosol formation</td>
<td>bulk ash</td>
<td>FactSage meltin curve</td>
<td>IN</td>
</tr>
<tr>
<td>Leppänen et al. 2014 [493]</td>
<td>Kraft recovery boiler</td>
<td>black liquor</td>
<td>Fluent</td>
<td>k – e real.</td>
<td>DO</td>
<td>LT &amp; EF</td>
<td>droplet evap.</td>
<td>alkali compounds n.s.</td>
<td>TP, CO, DI</td>
<td>platen heat exchangers</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Lab- or pilot-scale systems**

<table>
<thead>
<tr>
<th>References</th>
<th>System*</th>
<th>Fuel</th>
<th>Code</th>
<th>Turbul. model</th>
<th>Radiation modelb</th>
<th>Particle transp.</th>
<th>Devol. modelc</th>
<th>Char Comb.d</th>
<th>Ash formation</th>
<th>Ash chemistry</th>
<th>Sticking criteria</th>
<th>Deposition mechanisms*</th>
<th>Regions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Richards et al. 1993 [494]</td>
<td>PF: 1 MW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>bit. coal</td>
<td>PCGC-2</td>
<td>k – e</td>
<td>DO</td>
<td>LT</td>
<td>TR</td>
<td>const. rate none</td>
<td>fly ash is used as a separate cloud injection</td>
<td>bulk fly ash n.s.</td>
<td>Walsh / Urbain</td>
<td>IN</td>
<td>deposition panels</td>
</tr>
<tr>
<td>Huang et al. 1996 [495]</td>
<td>PF: 100 kW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>two US coals</td>
<td>Fluent</td>
<td>n.s.</td>
<td>LT</td>
<td>none</td>
<td>none</td>
<td>fly ash is injected using RR PSD</td>
<td>CCSEM of fly ash, is injected at specified locations</td>
<td>individual particles</td>
<td>Walsh</td>
<td>IN, TP</td>
<td>cooled tubes</td>
</tr>
<tr>
<td>Lee &amp; Lockwood 1998 [496]</td>
<td>PF: 150 kW&lt;sub&gt;net&lt;/sub&gt;</td>
<td>bit. coals</td>
<td>CINAR</td>
<td>k – e</td>
<td>DTM</td>
<td>LT</td>
<td>SR</td>
<td>KD</td>
<td>viscousity, Urbain</td>
<td>IN</td>
<td>different positions</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(continued on next page)
<table>
<thead>
<tr>
<th>References</th>
<th>System/ Fuel</th>
<th>Code</th>
<th>Turbul. model</th>
<th>Radiation model$^a$</th>
<th>Particle transport$^a$</th>
<th>Devol. model$^b$</th>
<th>Char Comb.$^d$</th>
<th>Ash formation</th>
<th>Ash chemistry</th>
<th>Sticking criteria</th>
<th>Deposition mechanisms$^e$</th>
<th>Regions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pykkönen and Jokinemi 2003 [99]</td>
<td>Kraft recovery boiler, isolated platen superheater black liquor</td>
<td>Fluent 2D</td>
<td>k – ε RNG</td>
<td>none</td>
<td>EF</td>
<td>none</td>
<td>fine dust is modeled</td>
<td>alkali comp.</td>
<td>n.s.</td>
<td>TP, EI, DI</td>
<td>platen superheater</td>
<td></td>
</tr>
<tr>
<td>Forstner et al. 2006 [493]</td>
<td>GF: 440 kW in grate-fired combustion unit coal</td>
<td>Fluent</td>
<td>k – ε real.</td>
<td>DO LT em. bed model</td>
<td>8 classes of ash released from bed different minerals are considered</td>
<td>n.s.</td>
<td>Walsh</td>
<td>KCl &amp; Si-rich particles</td>
<td>melt fraction</td>
<td>IN, CO</td>
<td>boiler walls</td>
<td></td>
</tr>
<tr>
<td>Tomeczek and Wacławia 2009 [253]</td>
<td>PF: isolated superheater tube coal</td>
<td>Fluent 2D</td>
<td>k – ε</td>
<td>none LT none</td>
<td>none</td>
<td>none</td>
<td>n.s.</td>
<td>Si- &amp; salt-rich viscosity/ melt fraction</td>
<td>IN, CO</td>
<td>on a probe and furnace walls</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Reddy et al. 2010 [258]</td>
<td>PF: 0.5 MW in KSVA furnace, Stuttgart Germany straw</td>
<td>AIOLOS</td>
<td>k – ε</td>
<td>n.s LT SR KD</td>
<td>n.s.</td>
<td>n.s.</td>
<td>various</td>
<td>IN, CO, TP</td>
<td>walls</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Schulze et al. 2010 [495]</td>
<td>GF: 70 kW in pellet furnace wood pellets</td>
<td>Fluent</td>
<td>k – ε real.</td>
<td>DO LT bed model</td>
<td>bed model releases vapors and ash particles are injected</td>
<td>bulk ash</td>
<td>Brach &amp; Dunn</td>
<td>cooled deposition</td>
<td>deposition panels</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Ai and Kuhlman 2011 [297]</td>
<td>Lab-scale deposition test rig coal fly ash</td>
<td>Fluent 2D</td>
<td>k – ε</td>
<td>n.s LT none</td>
<td>none</td>
<td>none</td>
<td>ash particles are injected</td>
<td>bulk ash</td>
<td>Energy balance</td>
<td>IN, TP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Degereji et al. 2012 [496]</td>
<td>PF: 0.2 MW in furnace, Leeds UK bit. coals</td>
<td>Fluent</td>
<td>k – ε RNG</td>
<td>DO LT FG-DVC intrinsic n.s.</td>
<td>bulk ash</td>
<td>Energy balance</td>
<td>IN, TP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Losordo et al. 2012 [342]</td>
<td>PF: lab-scale combustor, ECN Netherlands bit. coals</td>
<td>Fluent</td>
<td>k – ε</td>
<td>n.s LT n.s. n.s. n.s.</td>
<td>n.s.</td>
<td>n.s.</td>
<td>bulk ash</td>
<td>Walsh, Urbain</td>
<td>IN, TP</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Venturini et al. 2012 [346]</td>
<td>PF: lab-scale combustor straw in-house mod. k – ε</td>
<td>Fluent</td>
<td>k – ε</td>
<td>none LT none</td>
<td>none</td>
<td>none</td>
<td>ash particles are injected</td>
<td>bulk ash</td>
<td>IN, TP</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Beckmann et al. 2016 [397]</td>
<td>PF: lab-scale plug flow reactor, IEVB Germany bit. coals</td>
<td>Fluent</td>
<td>k – ε</td>
<td>n.s LT TR intrinsic</td>
<td>n.s.</td>
<td>n.s.</td>
<td>bulk ash</td>
<td>various</td>
<td>IN, TP</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Pérez et al. 2016 [301]</td>
<td>Kraft recovery boiler, isolated superheater tubes black liquor</td>
<td>Fluent 2D</td>
<td>k – o SST unsteady</td>
<td>none LT none</td>
<td>none</td>
<td>none</td>
<td>ash injected</td>
<td>bulk ash</td>
<td>Konstandopoulos</td>
<td>IN, TP</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Yang et al. 2016 [303]</td>
<td>PF: EFR with co-firing coal/palm kernel</td>
<td>Fluent 2D</td>
<td>k – o SST</td>
<td>DO LT SR intrinsic</td>
<td>diameter change</td>
<td>bulk ash</td>
<td>melt fr./ Mao et al.</td>
<td>IN, TP</td>
<td>cooled dep. probe</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Yang et al. 2017 [304]</td>
<td>PF: 300 kW in pilot-scale furnace Zhundong lignite</td>
<td>Fluent 2D</td>
<td>k – o SST</td>
<td>DO LT none</td>
<td>none</td>
<td>none</td>
<td>ash injected</td>
<td>bulk ash</td>
<td>melt fraction</td>
<td>IN, TP, CO</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Wang et al. 2017 [455]</td>
<td>tube of MSW economizer MSW ash</td>
<td>Fluent 3D</td>
<td>k – ε RNG</td>
<td>none LT none</td>
<td>none</td>
<td>none</td>
<td>ash injected</td>
<td>bulk ash</td>
<td>Konstandopoulos</td>
<td>IN, TP</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

n.s. - not specified or mentioned in the publication, n.i. - no information available

$^a$ System: PF - pulverized fuel, FB - fluidized bed, GF - grate firing, CHP - combined heat and power
$^b$ Radiation: DO - discrete ordinates, DTM - discrete transfer method
$^c$ Particle transport: LT - Lagrangian tracking, EF - Eulerian formulation
$^d$ Devolatilization: SR - single rate model, TR - two-competing rates model and char combustion: KD - kinetics, diffusion limited model
$^e$ Deposition mechanism: IN - inertial impaction, TP - thermophoresis, CO - condensation, EI - eddy impaction, DI - diffusional deposition, CR - chemical reactions

not clearly stated

RR – Rosin Rammler, PSD – Particle Size Distribution
with measurements in test facilities and conducted calculations for full-scale boilers. An interesting approach is presented by Bernstein et al. [481], in which they conducted coupled calculations between the fireside and the water-steam cycle. By using such a method, more appropriate boundary conditions, in particular temperatures, can be obtained for the fouling and slagging propensity. However, complexity increases strongly.

In the early 2000’s, modeling studies for biomass combustion and ash deposition emerged; mainly in the Scandinavian region. Pyykönen and Jokiniemi [99], developed a condensation model for the formation of alkali chloride aerosols. The transport of aerosols is computed using a general dynamic equation in the Eulerian frame of reference. In this equation, additional velocity components on particles due to thermophoresis or Brownian diffusion are incorporated leading to aerosol deposition. Three deposition paths are identified, which are the formation of sub-micron fume particles in the flow and their deposition via thermophoresis, the direct condensation of vapors on heat exchangers, or the nucleation of finest particles in the boundary layer during cooling and their deposition. Kar [497] conducted CFD simulations on a straw-fired grate using ANSYS CFX. In a later study, Fluent was used instead [360]. The simulations include the release of combustible gases and fly ash particles from a grate model. The model considers both fine sub-micron particles similar to Pyykönen and Jokiniemi [99], and coarse fly ash particles. Melting curves were obtained using thermodynamic equilibrium calculations and used for an ash particle sticking criterion. Location, amount and chemistry of ash deposits were predicted and were in-line with observations during real operation. Lepänä et al. [103] developed a condensation model for the sub-micron particle formation in a Kraft recovery boiler burning black liquor, a residue of the paper industry. The modeling included particle dynamics and equilibrium chemistry for alkali compounds in a full, three-dimensional CFD model of the boiler. Fine particle transport is modeled using the Eulerian formulation and deposition is calculated based on a similar approach as used by Pyykönen and Jokiniemi [99], considering diffusion effects and thermophoresis. The model is partially validated with measurements from heat exchanging surfaces. The predicted chemistry of particles extracted from the flue gas agrees well with model results.

The majority of studies mentioned above estimate the amount of ash accumulation using the particle concentration near the wall and the concept of the deposition velocity, e.g. see [360]. The actual calculation would require a highly resolved boundary layer, and the exact geometry of thousands of convective heat exchanger tubes. Single tube studies were conducted by Tomeczek and Wactawiaź [253], Haugen and Kragset [226], Venturini et al. [496], Weber et al. [206], Pérez et al. [300–302]. Typically, all these studies do not include combustion and ash formation processes. Ash particles are injected in a small domain, such as the flow around a superheater tube. Tomeczek and Wactawiaź [253] were among the first to present an interesting deposit built-up model accounting for the forming layer. Later on, Weber et al. [206,384] identified an important and crucial aspect when predicting impaction rates of small particles. If the boundary layer is not resolved properly by a specified number of nodes in radial as well as circumferential direction, impaction rates for small Stokes numbers \( St < 1 \) are highly overestimated. This is crucial in particular for predicting the deposition of particles with small sizes and clean tubes. Furthermore, this effect can explain relatively high deposition rates predicted by early CFD studies as shown in Table 7. The group of Weber [206,384] recommends to place at least one node in radial direction within the displacement thickness and 384 nodes around the cylinder circumference in order to accurately predict particle tracks and deposition rates. Pérez et al. [301,302], who used a highly-resolved grid, studied the deposition of small ash particles on tubes using unsteady simulations. They developed a comprehensive energy-based sticking criterion, found time-dependent deposition around the full circumference of the tubes and vortexes between the tubes affecting ash deposition. A further model including a dynamic built-up by grid manipulation was presented [300]. By using this model, they found that tube arrangement affected vortexes and by this also deposition rates.

An important question is, how to use information from CFD simulations for practical aspects, such as boiler operation and optimization. First of all, if predictions are able to accurately predict locations of deposit formation, the position of soot-blowers as well as soot-blowing intervals can be optimized. Furthermore, this allows to design flow paths as well as the ideal location for the injection of additives. However, further work in this area is needed, in particular addressing the role of deposit structure and how to consider this in advanced CFD models.

4.9. Analogies to other research fields

There are many research areas dealing with similar problems of particle deposition and fouling. Often, literature from other fields is ignored and not used. Table 22 summarizes the main research areas, and highlights their parameters. Related fields of research are the icing of air crafts, ash deposition in aero-engines caused by volcanic ash particles, deposition of fine particles or vapors in gas turbines, spray deposition in internal combustion engines, spray coating, and aerosol deposition in the human body, such as the respiration tract. The major differences to other fields are relatively low particle velocities and high viscosity values of ash particles in combustion systems. Models from one field do not necessarily work in other fields, however, often they can be adjusted or extended. Further fields involve heat exchanger fouling in various industries such as crude oil, food, desalination, automotive or other processes. A good overview on heat exchanger fouling is given in the work of Müller-Steinhagen and Zettler [498].

5. Ash particle rebound behavior

Theories on the rebound behavior of solid particles on a substrate are often based on the pioneering work of Hertz [507] and Lord Rayleigh [508]. The majority of new models extend the basic theory for

<table>
<thead>
<tr>
<th>Research field</th>
<th>Deposition mechanism</th>
<th>Deposition velocity in m/s</th>
<th>Temperature range °C</th>
<th>Particle type &amp; composition</th>
<th>Particle size in μm</th>
<th>References</th>
</tr>
</thead>
<tbody>
<tr>
<td>Icing on air crafts</td>
<td>IN, CO</td>
<td>70–250</td>
<td>–50–0</td>
<td>water droplets</td>
<td>10–50</td>
<td>[499,500]</td>
</tr>
<tr>
<td>Ash dep. in aero-engines</td>
<td>IN, TP</td>
<td>30–350&lt;sup&gt;a&lt;/sup&gt;</td>
<td>0–1400&lt;sup&gt;a&lt;/sup&gt;</td>
<td>volcanic ash particles</td>
<td>1–100</td>
<td>[501,502]</td>
</tr>
<tr>
<td>Dep. in gas turbines</td>
<td>TP, DI</td>
<td>30–350&lt;sup&gt;a&lt;/sup&gt;</td>
<td>0–1400&lt;sup&gt;a&lt;/sup&gt;</td>
<td>soot, aerosols</td>
<td>&lt; 10</td>
<td>[502]</td>
</tr>
<tr>
<td>Respiratory tract</td>
<td>IN, DI</td>
<td>0–5</td>
<td>–20–40</td>
<td>aerosols or sprays</td>
<td>0.01–50</td>
<td>[465,503,504]</td>
</tr>
<tr>
<td>Spray coating</td>
<td>IN</td>
<td>0–150</td>
<td>–100 to 800&lt;sup&gt;a&lt;/sup&gt;</td>
<td>droplets of paint</td>
<td>1–100</td>
<td>[505]</td>
</tr>
<tr>
<td>Diesel engines</td>
<td>IN</td>
<td>0–200</td>
<td>–20 to 1000&lt;sup&gt;a&lt;/sup&gt;</td>
<td>diesel droplets</td>
<td>0.1–300</td>
<td>[506]</td>
</tr>
</tbody>
</table>

<sup>a</sup> partly estimated.
phenomena such as plastic deformation and/or adhesion. Many studies can be found on the impact mechanics, however the phenomena of sticking and rebound is still poorly understood [414]. Most studies use idealized conditions, with the following assumptions [509]:

- There is no viscous drag due to a fluid phase between the particle and the surface,
- particles are smooth, non-rotating spheres,
- substrate is assumed to be smooth, flat and solid, and
- particles approach the surface with an initial kinetic energy much smaller than the thermal energy required to melt the particle.

Different stages of the impact of a solid particle with a solid substrate, and their respective energies, are shown in Fig. 73. A particle of mass \( m_p \) is colliding with the surface at an impact velocity \( v_i \) under an angle \( \phi_i \) (velocity and energy components do not use the index “p” for particle in order to enhance readability). The tangential velocity component of an impacting particle \( v_{r,i} \) can be responsible for rolling and sliding events upon impact (stage 2), where the friction coefficient \( \mu \) between the particle and the surface determines the behavior during stage 2 [222]. Losses occur during the transformation of the tangential kinetic particle energy \( E_{kin,t,i} \) into translational \( E_{t} \) and rotational \( E_{rot} \) energy. The losses are caused by friction \( E_{fr,i} \) or due to work of the rotating particle against the particle adhesion in tangential direction \( E_{ad,t} \). The normal kinetic energy \( E_{kin,n,i} \) is responsible for particle deformation. The deformation subside into elastic and plastic deformation stages. The energy involved during plastic deformation, \( E_{pl} \), is lost in contrast to the energy stored during elastic deformation, \( E_{el} \). This energy is left for particle rebound with a particle velocity \( v_r \). Using the energy balance leads to the following expressions for the impact and rebound kinetic energy [222,510]:

\[
E_{kin,i} = E_{el} + E_{pl} + E_{rot} + E_{fr,i} + E_{ad,t}
\]

Eq. (108) and (109) can be used to set up a sticking criteria when \( E_{kin,i} > 0 \). The kinetic energy during rebound is:

\[
E_{kin,t} = E_{kin,i} - (E_{pl} + E_{fr,i} + E_{ad,n} + E_{ad,t})
\]

Using an expression for the kinetic energy \( E_{kin,i} = 1/2 m_v v_i^2 \) one can obtain the following relation for the absolute rebound velocity \( v_r \):

\[
v_r = \sqrt{v_i^2 - \frac{2(E_{pl} + E_{fr,i} + E_{ad,n} + E_{ad,t})}{m_p}}
\]

The velocity component in normal direction \( v_{r,n} \) depends on \( E_{pl} \) and \( E_{ad,n} \), the components in tangential direction \( v_{r,t} \) on the other hand depend on the \( E_{ad,t} \) and \( E_{fr,i} \). Often, the so-called coefficient of restitution (COR or \( e \)) is used to predict rebound behavior. It is defined as the ratio of rebound to impact velocity according to the following expression:

\[
e = \frac{v_r}{v_i} = \frac{1 - 2(E_{pl} + E_{fr,i} + E_{ad,t} + E_{ad,n})}{m_p \cdot v_i^2}
\]

Eq. (111) can also be rearranged for a critical particle velocity \( v_{p,crit} \) below which particles will stick. Therefore, the rebound velocity is set to zero \( v_r = 0 \), yielding the following expression:

\[
v_{p,crit} = \sqrt{2(E_{pl} + E_{fr,i} + E_{ad,t} + E_{ad,n})}
\]

The exact value depends on the material properties, the velocity and energy components do not use the index “p” for particle in order to enhance readability). The tangential velocity component of an impacting particle \( v_{r,i} \) can be responsible for rolling and sliding events upon impact (stage 2), where the friction coefficient \( \mu \) between the particle and the surface determines the behavior during stage 2 [222]. Losses occur during the transformation of the tangential kinetic particle energy \( E_{kin,t,i} \) into translational \( E_{t} \) and rotational \( E_{rot} \) energy. The losses are caused by friction \( E_{fr,i} \) or due to work of the rotating particle against the particle adhesion in tangential direction \( E_{ad,t} \). The normal kinetic energy \( E_{kin,n,i} \) is responsible for particle deformation. The deformation subside into elastic and plastic deformation stages. The energy involved during plastic deformation, \( E_{pl} \), is lost in contrast to the energy stored during elastic deformation, \( E_{el} \). This energy is left for particle rebound with a particle velocity \( v_r \). Using the energy balance leads to the following expressions for the impact and rebound kinetic energy [222,510]:

\[
E_{kin,i} = E_{el} + E_{pl} + E_{rot} + E_{fr,i} + E_{ad,t}
\]

\[
E_{kin,t} = E_{el} + E_{rot} + E_{fr,i} + E_{ad,n} - E_{ad,t}
\]

5.1. Normal impact and rebound on a solid, smooth surface

Most experimental studies are carried out for normal impact, when the impact angle equals \( \phi_i = 90° \). These experiments also yield the critical particle velocity, when sticking occurs \( e = v_r/v_i = 0 \). The
critical particle velocity was found to depend on the impact angle \( \theta \) and on the particle size \( d_p \). The study of Wang and John [419] showed that at constant impact velocity \( v_i \) and with decreasing impact angle \( \theta \), the critical velocity \( v_{p,\text{crit}} \) decreases. Wall et al. [414] conducted a large number of experiments on the collision of different-sized particles with surfaces. Different material pairs were investigated by varying both, particle and substrate. The authors studied the collision over a broad spectrum of particle impact velocities (1 m/s < \( v_i < 100 \) m/s). They found a critical particle velocity, which decreases with increasing particle size. Fig. 74 shows the restitution coefficient \( e \), as a function of the impact velocity \( v_i \), for a normal impact experiment. The results are obtained using ammonium (NH₄) fluorescein particles with varying size on molybdenum (Fig. 74(a)) and tedlar surfaces (Fig. 74(b)). It can be seen that the critical velocity depends on the particle size and the substrate when comparing both figures. The softer surface tedlar leads to a larger critical velocity and lower restitution coefficients. The particles of size \( d_p = 2.58 \) \( \mu \)m show a critical velocity of around 10 m/s, which decreases to around 3.8 m/s on a molybdenum substrate. The rebound velocity strongly increases with increasing impact velocity, reaching to a uniform value of \( e = 0.8 \), for all particle sizes. This behavior is explained by a strong decreasing ratio of \( E_{\text{ad}}/E_{\text{kin}} \), i.e., the relevance of adhesive forces decreases with increasing impact velocities [222]. Wall et al. [414] furthermore observed a decreasing restitution coefficient at very high impact velocities (\( v_i > 100 \) m/s). This is explained by plastic deformation caused when the stress inside the particle exceeds the material strength.

Often, the restitution coefficient \( e \) is measured as a function of the particle normal impact velocity \( v_{n,i} \). Most studies use a setup with an impact angle of \( \theta = 90^\circ \) and a camera system, in order to measure particle velocity and height after rebound. Fig. 75(a) shows measurements on the restitution coefficient \( e = v_{n,f}/v_{n,i} \) as a function of the normal impact velocity \( v_{n,i} \). The data taken from Dunn et al. [424], was obtained using Ag-coated glass spheres on a stainless-steel surface. Given intervals show the scattering within which 95% of all data were found. It can be seen that the restitution coefficient increases with increasing impact velocity until a material-dependent, steady-state value of around \( e \approx 0.8 \) is reached. No decrease is observed indicating that no plastic deformation occurred. Dong et al. [420] studied the normal rebound behavior of fly ash particles, with a size of 75 ± 5 \( \mu \)m, which were mainly composed of quartz and mullite. A maximum value of \( e = 0.43 \) was observed followed by a decrease at higher impact velocity values. A similar behavior was found with the same device and material in an accompanying study as shown in Fig. 75(b). The role of particle size was studied and higher restitution coefficients were observed for larger particle sizes probably caused by higher kinetic energy. Interesting is the point where the restitution coefficient decreases, which is shifted to higher values when using larger particle sizes. They relate this phenomena to the work needed to break the connection between the two bodies. A possible explanation for the relatively low values of \( e \) is the particle shape, which was not perfectly spherical.

Thornton and Ning [290] developed a mathematical description of the restitution coefficient for adhesive elastic and adhesive elastic-
plastic spheres. In the latter case, plastic deformation occurs after the particle deforms elastically, as shown in Fig. 73. The model for both scenarios is based on the theory of Johnson, Kendall and Roberts [431], commonly known as the JKR-theory. According to this theory, when two colliding surfaces come into contact, the normal force between the two bodies drops to a certain value (defined in [290]), due to van der Waals attractive forces. The velocity of the impacting sphere is then reduced gradually, accompanied with elastic wave propagation into the substrate. The incoming (loading) stage is completed as soon as the contact force reaches the maximum value, and the velocity reduces to zero. During the recovery stage, the stored elastic energy is then released and converted into kinetic energy moving the particle in the opposite direction. The work done during the loading stage is then recovered, but the particle still remains adhered to the surface caused by adhesive forces [290]. This idea is used in Eq. (76), in which Thornton and Ning [290] derive the critical velocity \( v_{p,cr} \). They rewrite Eq. (76) for the case \( v_i > v_{p,cr} \) to the following form,

\[
1 - \left( \frac{v_i}{v_{p,cr}} \right)^2 = \left( \frac{v_{p,cr}}{v_i} \right)^2, \tag{114}
\]

where \( v_i/v_{p,cr} \) is the definition for the restitution coefficient \( e \):

\[
e = \sqrt{1 - \left( \frac{v_{p,cr}}{v_i} \right)^2}. \tag{115}
\]

The restitution coefficient for an elastic impact, as a function of the normalized impact velocity, can be seen in Fig. 76(a). Below \( v_{p,cr}/v_i = 1 \), a particle will stick. With increasing impact velocity \( v_i \) the restitution coefficient approaches a value of unity. In the case of elastic deformation, the maximum stress distributes as shown in Fig. 77(a) according to the Hertz theory [507] and Hertz pressure distribution. In case of plastic deformation, irreversible deformation occurs and the material strength is exceeded as shown in Fig. 77(b). Typically, the maximum contact pressure \( p_y \) is described as \( p_y = \lambda \cdot Y \), where \( Y \) is the unaxial yield stress of the particle material (shown in Fig. 40), and \( \lambda \) is a parameter which can vary from \( \lambda = 1.59 \) to 3.20. According to van Beek [267], \( \lambda = 1.59 \) is the limiting case for elastic deformation, and \( \lambda = 3.20 \) occurs when the whole particle deforms plastically [267,301]. A case in between is shown in Fig. 77(b). The pressure reaches its maximum value in the region \( r < r_p \), where \( r_p \) is the radius within which plastic deformation occurs. In the outer part \( (r > r_p) \) but \( r < r_t \), elastic deformation is observed. The total contact radius \( r_c \) can be used to calculate the contact area between the substrate and the deformed particle. Pérez et al. [301] uses the following linear relation, in order to estimate the ratio of the area with plastic deformation, and the total contact area:

\[
\lambda \approx 1.59 + \left( \frac{r_p}{r_t} \right)^2 \cdot (3.20 - 1.59) \tag{116}
\]

Thornton and Ning [290] defined a yield velocity \( v_y \), below which the impact is assumed to be perfectly elastic. Above this velocity, the impact leads to plastic deformation. The yield velocity for a particle impacting on a flat surface is obtained by:

\[
v_y = 1.56 \left( \frac{p_y^2}{E^2 r_p} \right)^{1/2} \quad \text{with} \quad p_y = \lambda \cdot Y \tag{117}
\]
where \( p_c \) is the limiting contact pressure shown in Fig. 77(b), and \( Y \) is the yield stress. Thornton and Ning [290] used the JKR theory for adhesive elastic-plastic spheres, however, they did not solve equations analytically due to their complexity. Instead it was assumed that the work dissipated due to plastic deformation and the work dissipated due to adhesive rupture are additive. This simplified the problem and three regimes are derived to describe the coefficient of restitution: for \( v_i \leq v_{p,crit} \)

\[
e = 0,
\]

for \( v_{p,crit} \leq v_i \leq v_Y \)

\[
e = \left( 1 - \left( \frac{v_{p,crit}}{v_i} \right)^2 \right)^{2/2}
\]

and for \( v_i \geq v_Y \)

\[
e = \frac{6\sqrt{3}}{6} \left[ 1 - \frac{1}{6} \left( \frac{v_Y}{v_i} \right)^2 \right] \frac{(v_i)}{(v_i) + 2 \sqrt{5} - 3 (v_i)^2} \right]^{1/2} - \frac{v_{p,crit}^2}{v_i^2}.
\]

Eqs. (118)−(120) can be used to generate Fig. 76(b), by plotting the coefficient of restitution against the normalized velocity \( v_i/v_Y \), for different ratios of \( v_{p,crit}/v_Y \) [290]. At \( v_i/v_Y = 1 \), plastic deformation begins and with increasing impact velocity a decrease in the coefficient of restitution is predicted, as observed in the experiments illustrated in Figs. 75(a) and (b), or as shown by the experiments of Wall et al. [414]. The model of Thornton and Ning [290] yields quite good results over a wide range, and is therefore often applied. Numerous models can be found in literature, and it is out of the scope of this review to discuss them all. Interesting might be for instance the work of Kim and Dunn [426], Krijt et al. [422], or Hærvig et al. [474].

5.2. Oblique impact and rebound on a solid, smooth surface

In the case of non-normal impact, which is typical for a PF power plant with superheater tubes, the determination of the restitution coefficient is more complicated. The rebound angle \( \psi_r \) is not identical to the impact angle \( \psi_i \). There are some studies [512,514] reporting larger rebound angles than impact angles, which seems to be odd at the first glimpse. The particles seem to gain rebound velocity \( v_{r,n} > v_{i,n} [301] \). This behavior is explained by surface roughness effects and becomes important when a particle interacts with a fouled layer. In this case, the angle of rebound can become unpredictable, showing a probability distribution. During oblique impact, frictional forces play an important role and have to be considered [512]. Fig. 78 shows definitions of angles, coordinates and the velocity components. The rebound angle and velocity of spherical particles depend on [513]:

- the impact angle \( \psi_i \)
- the initial impact speed \( v_i \)
- the particle spin \( \omega_h \)
- the normal coefficient of restitution \( e_n \)
- the surface roughness and surface energy of the particle and the substrate, and
- the impulse ratio of incoming and rebounding particle, which depends on the interface friction coefficient \( f \).

The restitution coefficient, can be split into the normal and tangential component, according to the following definitions [513]:

\[
e_n = -\frac{v_{r,n}}{v_{i,n}}
\]

\[
e_t = \frac{v_{r,t}}{v_{i,t}} = 1 - f \cdot (1 + e_n)\tan(\psi_i)
\]

Wu et al. [513], suggest the following equation for the calculation of the tangential restitution coefficient:

\[
e_t = 1 - \frac{2 d_p}{2(\psi_i - \psi_r)} \frac{f \cdot v_{in}}{\cos(\psi_i)}
\]

The rebound angle can then be calculated using the following relation:

\[
\tan(\psi_r) = \frac{v_{r,n}}{v_{r,t}} = \frac{e_n \tan(\psi_i)}{e_t}
\]

An analysis of the tangential coefficient of restitution \( e_t \) was conducted in a previous study by Wu et al. [515]. They used FEM simulations to predict the tangential restitution coefficient \( e_t \), as shown in Fig. 79(b). At low impact angles \( \psi < 30^\circ \), sliding is frequently reported and dominates [512]. The friction coefficient \( f \) is too low to slow down the particle. At higher impact angles of \( \psi \geq 30^\circ \) a value of \( e_t \approx 5/7 \) is reported to be a good approximation [515]. Pérez et al. [301] used an expression based on the experiments of Brach et al. [512]. The restitution coefficient is calculated according the following expression:

\[
e_n = -\frac{v_{r,n}}{v_{i,n}} = \max(0.75; 2.00 - 2.04 \cdot \psi_i)
\]

Stanton and Rutland [517] and O’Rourke and Amsden [518] studied droplet-wall interaction and suggested the following restitution coefficient:

\[
e_n = 0.993 - 1.76 \cdot \psi_i + 1.56 \cdot \psi_i^2 - 0.49 \cdot \psi_i^3
\]

where the angle has to be used in radians. Attention has to be paid for the definition of the impact angle \( \psi_i \) with the substrate. Different definitions can be found in literature. A comparison of Eqs. (125) and (126) with experimental values of Li et al. [516] is shown in Fig. 79(a). The rebound angle can be calculated using the continuous line of Fig. 79(b), Eqs. (124) and (125). The result is illustrated in Fig. 80(a). At low impaction angles, higher rebound angles are predicted. However, the random distribution of rebound angles cannot be covered. The random rebound angle, often mentioned in experimental studies, can be explained by Fig. 80(b). The microscopic surface is rough and small particles barely hit the surface at the macroscopic angle. Therefore, following the suggestion of Pérez et al. [301] to use a probability function to calculate a random rebound angle, seems meaningful. However, the limit of these angles should be determined experimentally. Pérez et al. [301] suggested limits between \( \psi_r = \arcsin(-v_{r,n}/v_i) \) and \( \psi_r = \psi_i \) (equations differ in original publication due to a different angle definition).

Tabakoff [519] studied the rebound characteristics of fly ash particles of 15 \( \mu \)m size on different metal surfaces and varying impact angles. Studied surface materials were stainless steel, aluminum, titanium and some others. Furthermore, equations predicting
erosion behavior at high temperatures were presented. Findings of Tabakoff are presented in Figs. 81(a) and (b). Fig. 81(a) shows the velocity ratio of incoming and rebounding particles. With decreasing impact angle, the ratio approaches unity. The trend of mean measured points is well captured by Eq. (126), however with an offset. In addition, statistical distributions are shown within the figure for each measured point. Values are typically found within 20% showing a Gaussian distribution. Fig. 81(b) illustrates the so-called particle directional coefficient, which is obtained by dividing the rebound angle with the impact angle. The rebound angle seems to equal the impact angle at low impingement angles. However, with increasing impingement angles, the ratio drops to around 0.6 implying a reduced rebound angle compared with the impaction angle. A similar study was performed by Reagle et al. [520] using elevated temperatures (up to 800 °C) and high velocities (up to 102 m/s). The study uses road dust particles impacting stainless steel surfaces simulating the deposition of micro-particles under gas turbine conditions. Results indicate that temperature plays a minor role in energy transfer between particle and impact surface below a critical temperature. At 800 °C, the coefficient of restitution is reduced by an average of 16% compared with ambient temperature experiments. Their decrease is explained by an increase in velocity accompanied by the temperature rise. At higher temperatures reduced elastic modulus and yield strength are assumed to become relevant. A summary and overview on experiments aiming at particle deposition in gas turbines can be found in the work of Hamed and Tabakoff [502]. Particle velocities are considerably higher compared to power plants and therefore not included in this study. Values range from 65 up to 366 m/s [502]. A recent study dealing with ash and char particle rebound behavior was presented by Troiano et al. [456]. The authors studied particle-wall interaction phenomena for entrained flow gasifier using biomass ash and char particles from wood chips and corn stover. The impaction of particles on inclined hot and cold refractory material was recorded using a high speed camera. The authors found that even at ambient temperature, there are indications for plastic deformation. At high temperatures, there is a drop of the restitution coefficients in particular for low impact velocities. Typical restitution coefficients at room temperature were in the region of \( e = 0.2 - 0.6 \). At 1400 °C, values dropped to \( e = 0.05 - 0.4 \).

5.3. Impact and rebound on a powdery layer

Studies on particles impacting a powdery layer are rare in literature. However, these are the most realistic scenarios, in particular
within the convective section of a power station such as the economizer region. An interesting work was presented by van Beek et al. [268]. They studied the impaction of 50 µm glass particles on a thin layer of glass particles representing the fouling layer. Ash particles were simulated using glass spheres. Different scenarios were studied using a powdery (loose) or glued layer of glass, a varying impact angle in the range of 60 ≤ θi ≤ 90° and varying incident particle velocities in the range of 0.5 to 1 m/s. Experiments were recorded in a vacuumed column using a digital camera system [268]. Experimental results were modeled using a two-body collision model based on the rigid body theory (see Goldsmith [521]). This theory assumes that deformation during contact is negligible and the impact is described using linear and angular momentum conservation. In this theory, only two possible scenario can occur during rebound: sliding throughout the contact and rolling at exit [268]. Van Beek and co-workers [268] assumed that both the incident particle and the target particle are initially non-rotating and the target particle is resting with zero initial velocity. For the sliding-case, the normal and tangential rebound velocity components of the incident particle are calculated by [268, 521]:

\[
\begin{align*}
\vec{v}_{r,n} &= v_{i,n} - (1 + e_n) \cdot \frac{m_{p,2}}{m_{p,1} + m_{p,2}} \cdot \vec{v}_{i,n} \\
\vec{v}_{r,t} &= v_{i,t} - f \cdot (1 + e_n) \cdot \frac{m_{p,2}}{m_{p,1} + m_{p,2}} \cdot \vec{v}_{i,t}
\end{align*}
\]

(127)

In above equations, \(m_{p,1}\) and \(m_{p,2}\) are the mass of the impacting and target particle, respectively, and the parameter \(f\) denotes again the Coulomb friction coefficient. The relation given in Eq. (128) is only valid in the case when the particles remain sliding over each other (φi < 30°). When rolling occurs (slip velocity is reduced to zero), the rebound velocity of the incident particle can be calculated by [268]:

\[
\begin{align*}
\vec{v}_{r,t} &= v_{i,t} - \frac{2}{7} \cdot \frac{m_{p,2}}{m_{p,1} + m_{p,2}} \cdot \vec{v}_{i,t}
\end{align*}
\]

(129)

The minimum friction coefficient \(f_{min}\) required to bring the slip velocity to zero just at the end of the impact is given by [268]:

\[
f_{min} = \frac{2/7 \cdot \cot (\phi_i)}{1 + e_n}
\]

(130)

The friction coefficient \(f\) and the normal restitution coefficient \(e_n\) were determined from experiments using a flat, solid glass target, where \(m_{p,2} \gg m_{p,1}\). Using velocity components from the camera system, both parameters can be quantified using the following simplified equations:

\[
\begin{align*}
\vec{v}_{r,n} &= -e_n \cdot \vec{v}_{i,n} \\
\vec{v}_{r,t} &= \vec{v}_{i,n} - f \cdot (1 + e_n) \cdot \vec{v}_{i,n}
\end{align*}
\]

(131, 132)

As already mentioned above, the normal restitution coefficient \(e_n\) accounts for the energy loss due to plastic deformation and adhesion. The measured normal restitution coefficient as a function of impact angle is shown in Fig. 82(a). It can be seen that with increasing angle, the coefficient of restitution increases, to \(e_n \approx 0.8\) at normal impact. Van Beek et al. [268] conclude using the theory of Thornton and Ning [290], that the velocity is too low for plastic deformation and too high for adhesive forces to become important. Values agree with the study of Li et al. [516] at high impact angles. However, the relatively low value and the increase with increasing angle could not be explained. Results for the friction coefficient as a function of impact angle are shown in Fig. 82(b). Eq. (130) together with Eq. (125) are used to calculate \(f_{min}\). At an impact angle of \(\phi_i = 33°\), the measured value is far below \(f_{min}\), indicating that sliding occurs during the exit (rebound). A value of \(f_{glass/glass} \approx 0.17\) is used for angles \(\phi_i < 45°\) [268]. A significant difference in studies using a powdery layer is that rebound velocities are typically lower, rebound angles show a broad scattering and particles from the substrate can be ejected. The lowered rebound velocity is mainly caused by the particulate layer absorbing kinetic energy of incoming particles. Particles inside the bed rearrange and typically a larger mass for the target particle is used for prediction as suggested by Werner [522] in the following form:

\[
m_{p,2} = C_m \cdot m_{p,1}
\]

(133)

where \(C_m\) is a proportionality factor. The effective mass of the target particle is always larger than the mass of the target particle itself, considering the momentum transfer into the bed of particles around and beneath the target particle [268]. Van Beek et al. [268] found that the proportionality factor \(C_m\) is dependent on the bed porosity, the stickiness of bed particles, the layer thickness and the binding between target particles, and can be viewed as a system parameter. Is the binding perfect (e.g. for a molten layer or a solid, rough surface), the mass \(m_{p,2}\) and \(C_m\) approach infinity. For a glass particle bed it was found to be in the range of \(C_m = 2.6 \text{ to } 3.5\) depending on the diameter ratio of incident to target particles. A smaller value of \(C_m\) is observed when the diameter of the incoming particle increases compared to the target particle diameter.
Fig. 83(a) shows a recorded image illustrating the impaction of a particle and the ejection of bed particles from a powdery surface. These images are used for the determination of rebound angles and velocity ratios. The measurements on the absolute rebound angle as a function of normal velocity ratio are shown in Fig. 83(b). The maximum rebound velocity ratio and thus the normal restitution coefficient is around $e_n = 0.58$. Most values are in the region $0.1 \leq e_n \leq 0.3$, indicating a high damping of a powdery glass layer. The absolute rebound angle shows a broad scattering with most particles rebounding at an angle of $\psi_r \approx 40^\circ$. A rebound in the negative tangential direction (left side) was nearly as common as a rebound to the positive tangential direction (right side). Therefore, when a particle impacts a rough surface a random distribution around $\psi_r \approx 50^\circ$ to $\psi_r \approx -50^\circ$ is observed. Van Beek et al. [268] used the two-body collision model described by Eqs. (127)–(130) together with Eq. (133) with $C_m = 3.5$ in order to predict rebound angles. Relatively good agreement with experiments is reported for the rebound angle and its distribution as well as the rebound velocity ratio. Thus, this kind of model can be applied.

It can be summarized that the normal coefficient of restitution and the friction coefficient are highly dependent on material properties of both collision partners - Young's modulus, yield stress - and process parameters - impaction velocity, impaction angle, particle sizes and surface roughness [268]. The tangential coefficient of restitution seems to be dependent on the friction coefficient of the material combination and can be approximated using the following equation:

$$f = \min\left( f_{\text{mat,1}} f_{\text{mat,2}} \frac{2}{7} \cot \psi_i \frac{1}{1 + e_n^3} \right).$$

(134)

where $f_{\text{mat,1}}$ and $f_{\text{mat,2}}$ is the friction coefficient of material 1 and 2. Using this equation and data from van Beek et al. [268], Fig. 84 can be calculated. It shows the tangential coefficient of restitution as a function of impact angle, analogously to Fig. 79(b). Predictions are compared to measurements of Müller et al. [523], who investigated the impaction of $\text{Al}_2\text{O}_3$ particles on steel at various impact angles. Relatively good agreement can be seen and a similar curve as predicted by Wu et al. [515], shown in Fig. 79(b), is obtained. However, a high sensitivity towards the friction coefficient $f$ at high angles of impaction ($\psi_i > 60^\circ$) is observed.

Abd-EIhady et al. [524] used the same equipment as van Beek et al. [268] and studied the interaction and ejection of particles from a bed upon incoming particles. The two-body collision model was replaced by the so-called discrete element method (DEM), in which every particle contact including rearrangements in the bed, is described. Konstandopoulos [434] reports that the two-body collision model (with a higher effective mass for the target particle according to Eq. (133)) fails at higher kinetic energies of impacting particles, when they induce rearrangements or erosion of pre-deposited particles [434,524]. The DEM, developed by Cundall and Strack [525], treats every particle as a discrete entity, which interacts at its interface when in contact with other particles [524]. This method is
often extended for plastic deformation upon contact using e.g. the model of Thornton and Ning [290] or the one proposed by Rogers and Reed [418]. An overview on the DEM and its capabilities can be found in the review of Li et al. [526]. Abd-Elhady et al. [524] conducted 490 experiments using spherical copper particles with a diameter of 54 µm and different impact speeds. The particles impact vertically on a bed which is composed of the same particles and had a porosity of 0.42. Experiments were conducted at room temperatures and the number of ejected particles were recorded. A regime map is derived from the experiment showing different zones - sticking, rebound and rebound with ejection of bed particles. The regime map is shown in Fig. 85. The particles will stick below a critical velocity of $v_{p,n} < 0.3$ m/s. Rebound, is observed in the region of $0.18 < v_{p,n} < 1.1$ m/s. At higher values of $0.6 < v_{p,n} < 1.8$ m/s, the ejection of an additional particle, besides the incident particle, is observed. Two and more additional particles are ejected at $v_{p,n} \geq 1.5$ m/s. The overlap was explained by the impact angle. The incident particle can hit a bed particle at various microscopic angles, similar to Fig. 80. The DEM conducted by Abd-Elhady et al. [524] was able to predict the critical velocity and rebound velocity with a slight deviation. Furthermore, equations for energy loss due to plastic deformation, adhesion and stored elastic energy are given. In addition, equations for the ejection time and the maximum deformation also referred to as the interpenetration distance of two equal sized particles as a function of material properties are presented and discussed. The maximum indentation of an incident particle hitting a bed of particles is shown to be directly proportional to the incident particle velocity and diameter if plastic deformation occurs [524].

An early study using DEM simulations in order to predict deposit growth for uniform particles was presented by Konstandopoulos [434]. Simulations were carried out in a three-dimensional domain using the FORTRAN code "FROZEN". The calculation is performed until a total number of $10^5$ particles are deposited on 63x63 particle radii substrate with periodic boundaries [434].

The following parameters were chosen for the simulation: $e = 0.9$, $f = 0.2$, $E_0 = 0$, 0.01, 0.1, and $v = 0.33$ [434,527], where $E_0$ is a dimensionless number relating kinetic energy to rotational energy. It relates the rotational energy barrier to the normal adhesion barrier [434]. Simulations are carried out using dimensionless parameters, where the velocity is normalized using the kinetic energy and particle mass. Model results are shown as two-dimensional cross-sections in Fig. 86 for different dimensionless impact velocities and impact angles. The author reports many common features compared with real particulate deposit pictures in literature. At low impact velocities, a "roughening" is observed which increases with decreasing impact angle. Orientated voids are caused by regions, where particle deposition is prevented and rebound will occur. These voids decrease with increasing particle velocity. At high impact velocities, the effect of impact angle diminishes and denser deposits are obtained. This is also reported by other studies such as the work of Ots [528]. Another finding shows that with increasing deposition velocity the number of rebounding particles increases. This is supported by experiments of Tsai and Cheng [529] using high loadings and an uncoated flat impaction surface. Furthermore, the number of impactions that a particle requires until it rests/sticks increases with increasing impact velocity. The results show that rebound velocity shows a multimodal nature and particles take up spin after collision. DEM simulations can be a useful, but computationally expensive, tool for the prediction of deposit structure, in particular at low temperatures such as the economizer region. At higher temperatures, sintering and melting occur leading to changes in structures and deposit growth. With this method, effects such as shedding and erosion can be predicted.

5.4. Impact and rebound on a liquid layer

Studies of particles impacting a solid substrate overlaid with a liquid layer are rare. These collision can be relevant for a variety of industries such as filtration or ash particle impaction on a slagged wall. Barnocky and Davis [530] conducted a series of experiments in which a solid ball drops on a quartz disk overlaid with a thin layer of Newtonian oil. Ball size and thus kinetic energy was varied from 1.6 to 6.4 mm, and material was either steel or polymer (lucite). Studied parameters comprise of the fluid layer thickness and viscosity, the ball size, density and elasticity. In their experiments, Barnocky and Davis [530] determined the critical drop height, and thus the critical velocity, that allowed the ball to rebound out of the fluid layer. The critical velocity, below which particles will stick, can be approximated by neglecting the air resistance $v_{p,crit} = \sqrt{2 \cdot g \cdot h_{crit}}$. According to the authors, this equation is valid within 5% accuracy for their experiments [530]. Results of their study can be seen in Figs. 87(a) and (b). In general, an increased critical drop height (height of falling, above which rebound begins) is observed with increasing fluid layer thickness. The particle is able to penetrate the fluid layer deeper and thus dissipation of the initial kinetic energy is increased. In the case of rebound, particles must deform elastically and thus be in close contact with the underlying solid surface. Fig. 87(a) shows the effect

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**Fig. 84.** Comparing measured and predicted tangential coefficient of restitution. Experimental points taken from a study of Müller et al. [523], who investigated Al2O3 particle impacton steel at various impact angles.

**Fig. 85.** Regime map showing the number of ejected particles from a bed as a function of incident particle vertical speed. Data and map from experiments of Abd-Elhady et al. [524] using uniform copper particles impacting a layer of copper particles at room temperature.
Fig. 86. Deposit morphologies predicted with DEM simulations using the FROZEN code at various normalized impact velocities \( v_i \) and angles of impact \( \phi_i \) (taken from Konstandopoulos [434]).

Fig. 87. Critical drop height versus film thickness: (a) for steel balls with \( d_p = 3.2 \) mm colliding with a smooth quartz surface overlaid with fluids of various viscosities, and (b) for steel balls of various size colliding with a rough surface overlaid with a fluid of viscosity \( \mu_{\text{film}} = 1.7 \) Pa·s. Data taken from Barnocky and Davis [530].
of fluid viscosity on the rebound behavior of 3.2 mm steel balls. With increasing fluid viscosity, the drop height increases since a fluid with higher viscosity is able to dissipate more of the particle's kinetic energy. This energy misses for particle deformation and rebound. Fig. 87(b) illustrates the effect of surface roughness on the rebound behavior. Here, 75 μm glass beads (particles) were fixed to the land- ing surface using epoxy resin. The density was 17 beads/mm² [530]. The beads were half imbedded in the epoxy yielding a surface with 38 μm hemispherical bumps with a mean center to center distance of 150 μm. These bumps with a radius of x₀ = 38 μm are overlaid with a film of viscous fluid. When comparing experimental results with a smooth surface, approximately one order of magnitude thicker fluid film is needed for the same critical height leading to particle rebound. Thus, the liquid film can be considerably thicker and the particle will still stick. A ball of the size 1.6 m dropped from 0.6 m, rebounds at a film of approximately 60 μm for a smooth substrate compared to around 220 μm, for a rough surface. Barnocky and Davis [530] explain this drastic increase using a theory presented by Davis et al. [531], which is based on Hertz contact theory of solid elasticity together with viscous lubrication theory.

Particles stick if:

\[ P_{\text{stick}} = \begin{cases} 0 & \text{for } St > St_{\text{crit}} \\ 1 & \text{for } St \leq St_{\text{crit}} \end{cases} \]  

(135)

where the Stokes number is calculated by 

\[ St = \left( \frac{2 \cdot m_p \cdot v_f}{\frac{1}{3} \cdot \pi \cdot \mu_{\text{film}} \cdot d_p^2} \right) \]  

using the viscosity of the liquid film \( \mu_{\text{film}} \) and the initial, relative particle velocity \( v_{p0} \) at an initial separation \( x_0 \) between the undeformed surfaces of both solid bodies (i.e. distance between surface and particle with a viscous fluid in between, e.g. oil in the study of Barnocky and Davis [530]). The initial velocity is estimated by \( v_i = \sqrt{2 \cdot g \cdot h} \), again neglecting air resistance. The Stokes number calculation is based on the force that acts on the particle, and is caused by the surrounding fluid \( F = \frac{3}{2} \cdot \pi \cdot \mu_{\text{film}} \cdot d_p^2 \cdot v_f / \kappa \), assuming moderate fluid deformation, where \( x \) is the changing distance between the undeformed surfaces. Analysis by the authors showed that viscous forces dominate over any other force such as gravity or inter-particle van der Waals forces [530]. The critical Stokes number can be estimated using the following condition for a smooth surface underneath the liquid film:

\[ St_{\text{crit}} = \ln(x_0 / x_1) \]  

for a smooth underlying surface. 

(136)

where \( x_0 \) is again the distance between the undeformed surfaces. This distance is not exactly equal to the film thickness \( \delta \) since the nose of the particle must be wetted. The authors use the following expression for \( x_0 = 2 / 3 \delta \), where \( \delta \) is the liquid film thickness. Here it is important that \( x_0/d_p < 1 \), which might be critical for ash particles known to be significantly smaller than the balls in the experiment of Barnocky and Davis [530]. The authors further argue, that for \( St > 1 \), the fluid velocity is only reduced by a few percent. Additionally, the authors use the capillary number defined as \( Ca = \mu_{\text{film}} \cdot v_f / \gamma_{\text{film}} \), where \( \gamma_{\text{film}} \) is the air-liquid surface tension, in order to show that surface tension effects are negligible. For their experiments the Ca number is in the range of \( 10^2 \rightarrow 10^3 \). On the contrary, in filter fibers with aerosol Ca numbers are in the region of \( 10^{-1} \rightarrow 10^{-2} \). Thus surface tension effects may sometimes be important, when \( Ca < 1 \) [530]. The parameter \( x_1 \) in Eq. (136) is the elasticity length scale. At this length scale, particles have enough inertia to penetrate to a distance, where deformation of the incoming particle can occur. It is defined as:

\[ x_1 = \left[ \frac{4 \cdot E^* \cdot \mu_{\text{film}} \cdot v_f \cdot (d_p / 2)^{2 / 3}}{E \cdot \mu_{\text{film}} \cdot v_f \cdot (d_p / 2)^{2 / 3}} \right]^{2 / 5}, \]  

(137)

where \( E^* \) is the elasticity parameter calculated with:

\[ E^* = \frac{1 - v_f^2}{\pi \cdot E_1} + \frac{1 - v_f^2}{\pi \cdot E_2}, \]  

(138)

The indices 1 and 2 in Eq. (138) stand for the particle and solid substrate, respectively. The elasticity length scale in the experiment of Barnocky and Davis [530] is in the range of \( 1 < x_0 < 10 \mu m \) and thus small compared to surface roughness effects. In the case of a rough surface, the following relation is used to predict the critical Stokes number and thus the sticking and rebound threshold:

\[ St_{\text{crit}} = (1 + 1/e) \ln(x_0 / x_1) \]  

for a rough underlying surface. 

(139)

where \( e \) is the restitution coefficient and \( x_0 \) is the surface roughness. Both Eqs. (136) and (139) show relatively good agreement with experiments with \( e = 1 \). At higher Stokes numbers of \( St > 4 \) equations show some deviations, where particle deformation might become too large and the restitution coefficient is smaller than unity \( e < 1 \). It is shown that surface roughness has a strong effect on the rebound behavior when the roughness \( x_0 \gg x_1 \).

The applicability of this theory for PF combustion, however, has still to be proven. The particle size is considerably smaller and thus less inertia (kinetic energy of particles) for penetrating the liquid film is available. Furthermore, the film layer viscosity is considerably higher with \( 10^3 \rightarrow 10^4 \) Pa·s for molten slag compared to \( 1.7 \rightarrow 39 \) Pa·s of oil in the study of Barnocky and Davis [530]. In addition, the film thickness can reach much higher values and rebound is unlikely. This confirms that if a particle impacts a liquid slag layer it will stick and rebound is very unlikely.

6. Comparison of different sticking criteria

Sticking criteria presented in Section 4 comprise of relatively simple models with just one parameter, up to complex models that require a number of temperature-dependent material properties for their mathematical description. These properties should ideally be known for all possible ash particle compositions. In addition, the majority of models does not account for a sticky surface or rebound behavior. Therefore, the goal of this section is a comparison and validation of different sticking criteria, the development of a mechanistic model considering all important parameters including the description of rebound behavior.

6.1. Experimental setup and results

In order to eliminate the influence of particle to particle variation in chemistry and size, soda-lime glass particles within a narrow size range are used. These particles have been applied in previous studies [1,201,222] and exhibit similar properties as ash particles. Glass particle deposition tests are conducted using an entrained flow reactor (EFR) for three size-graded particle classes (40–70, 150–210 and 500 μm) and three wall temperatures (800, 900 and 1000°C). A detailed description of the test rig can be found elsewhere [185,188]. Tests are conducted for a short period, \( t_{\text{exp}} \approx 10 \) min, in order to eliminate sintering and erosion effects and reduce the influence of the deposit on capture efficiency. Experimental conditions and results are given in Table 23. Deposited mass is determined by weight difference. A previously described optical system is used to determine layer thickness and growth dynamics [188,312]. Deposition rates \( m_{\text{dep}} \) given in Table 23, show that at 800°C only the smallest particle size leads to deposition formation. A minor amount is found for the intermediate particle size and no deposition occurs for large particles. The main reason for this is the lower temperature of large particles when impacting on the deposition probe. Residence times are too short and heating rates too low for larger particles to reach the wall temperature. At 900°C, deposit formation is also observed for the intermediate particle size, 150–210 μm, whereas the largest
particles still rebound. Increasing the EFR wall temperature to 1000 °C revealed similar results with increased deposition rates. The deposit structure is mostly particulate and only experiment 8 showed a molten layer.

6.2. CFD model and comparison of results

Experimental results are used, and recalculated with a CFD model. The model predicts the flow field, temperatures as well as glass particle trajectories. The computational grid has a total number of 1.56 million nodes. Special attention is paid to an adequate resolution of the deposition probe, following suggestions established in the work of Weber et al. [206]. Two nodes are placed within the displacement thickness in radial direction in order to resolve the boundary layer and predict accurate particle tracks as well as impaction rates. A total number of 96 nodes around the circumference of the probe revealed independent deposition rates. The number is lower compared to the recommendation of Weber et al. [206], who suggested 384 nodes around the circumference. This could lead to an over prediction of the impaction efficiency at small Stokes numbers St < 1. However, since glass particles in the present work are relatively large, with smallest sizes in the range of 24.3 µm as given in Table 24, deposition rates are not over predicted and numerical accuracy is given. This grid revealed identical deposition rates compared to a mesh with four million nodes. More details on the computational mesh, the model selection and sensitivity studies can be found elsewhere [185,188]. In the CFD model, glass particles are injected as inert material, with a narrow-sized Rosin–Rammler distribution, fitted to measurements. Particle temperature is calculated using heat balance [534].

Particles close to the reactor wall almost reached the wall temperature, whereas particles in the center stayed below this value. Temperature-dependent properties of soda-lime glass are implemented in the CFD code, based on a literature review. Thermophysical properties of glass particles are calculated at each position using the local particle temperature, and thus consider a temperature change within the boundary layer of the probe. Hence, adhesion properties are calculated using local temperatures and not bulk values, which is a crucial aspect, in particular for small particles $d_p < 10 – 20$ µm, which cool down in the vicinity of a cold tube. Properties, PSD and glass composition are summarized in Appendix B. In addition, properties for the deposition probe, composed of $Al_2O_3$, are given. The only required quantity that is not found in the literature is a temperature-dependent contact angle of soda-lime glass on a ceramic substrate. In order to obtain values, the ash melting microscope EM 201 of the company “Hesse Instruments” is used [532]. A soda-lime glass sphere with a diameter of 1.5 mm is placed on a ceramic plate composed of the same material as the deposition probe. Three different heating rates are tested to ensure independent results. Fig. 88 shows shadow images recorded at different temperatures. The contact angle $\theta_c$ is determined graphically from these images using the software ImageJ. The results are fitted with Eq. (54). The coefficients are determined as $A = 0, B = 180, C = 930$ and $D = 100$. The results are illustrated in the left part of Fig. 88. Deviations at lower temperatures are due to an insufficient resolution of the camera. The image at ambient temperature does not change up to 700 °C. Only values above that temperature can be determined properly, caused by a shade of the ceramic plate. The plate shadow makes it difficult to determine small changes in the contact angle at low temperatures. Nevertheless, values above $\theta = 100^\circ$ can be calculated using Eq. (54). Once all required properties of soda-lime glass are known, sticking criteria can be investigated. A total of eight sticking criteria are implemented in the code and CFD results are compared with measurements. The sticking criteria are:

- C1: melt fraction, Eq. (69), proposed by Müller et al. [202],
- C2: melt fraction, Eq. (70), proposed by Zhou et al. [391],
- C3: critical viscosity as a function of particle kinetic energy, Eqs. (72) and Eqs. (73), [1,222].

<table>
<thead>
<tr>
<th>Table 23</th>
</tr>
</thead>
<tbody>
<tr>
<td>Experimental conditions and results, as well as a comparison to CFD simulations with different sticking criteria C1 to C8.</td>
</tr>
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</table>

<table>
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<th>Cases</th>
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<th>$\text{Exp. 4}$</th>
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<td>$T_{\text{wall}}$ $\text{in } ^\circ\text{C}$</td>
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<td>800</td>
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<tr>
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<td>70</td>
<td>171</td>
<td>483</td>
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<td>$d_{p,50}$ $\text{in } \mu\text{m}$</td>
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<td>679</td>
<td>631</td>
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<td>0.90</td>
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<tr>
<td>$T_{\text{C}}$ $\text{in } ^\circ\text{C}$</td>
<td>–</td>
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<td>$C_1$</td>
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<tr>
<td>$C_4$</td>
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</tr>
<tr>
<td>$C_5$</td>
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<td>–</td>
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<td>$m_{\text{dep}}$ $\text{g/h}$</td>
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<td>1.4</td>
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<td>$d_{p,50}$ $\text{in } \mu\text{m}$</td>
<td>19.80</td>
<td>763</td>
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<td>$\tau_p$ $\text{in m/s}$</td>
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<td>723</td>
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<td>$T_{\text{C}}$ $\text{in } ^\circ\text{C}$</td>
<td>17.2</td>
<td>1.89</td>
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<td>$C_1$</td>
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<td>$C_2$</td>
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<td>$C_3$</td>
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<td>$m_{\text{dep}}$ $\text{g/h}$</td>
<td>450</td>
<td>63</td>
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<td>$d_{p,50}$ $\text{in } \mu\text{m}$</td>
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<td>1.5</td>
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<td>807</td>
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<th>Root mean square error (RMSE):</th>
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<td>Correlation coefficient:</td>
<td>0.55</td>
<td>0.90</td>
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Table 24

| Soda-lime glass particle size distribution and characteristic temperatures (size fraction with uniform 500 µm particles could not be measured due to the large particle size). |

<table>
<thead>
<tr>
<th>Variable</th>
<th>$d_{p,10}$ $\mu\text{m}$</th>
<th>$d_{p,50}$ $\mu\text{m}$</th>
<th>$d_{p,90}$ $\mu\text{m}$</th>
<th>IDT</th>
<th>ST</th>
<th>HT</th>
<th>FT</th>
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<tr>
<td>Glass 0-50</td>
<td>24.3</td>
<td>43.4</td>
<td>68.3</td>
<td>777</td>
<td>791</td>
<td>944</td>
<td>1175</td>
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<tr>
<td>Glass 40-70</td>
<td>48.3</td>
<td>62.7</td>
<td>79.1</td>
<td>790</td>
<td>790</td>
<td>961</td>
<td>1188</td>
</tr>
<tr>
<td>Glass 150-210</td>
<td>134.3</td>
<td>171.3</td>
<td>216.8</td>
<td>804</td>
<td>828</td>
<td>935</td>
<td>1161</td>
</tr>
</tbody>
</table>
C4: critical viscosity, Eq. (72), proposed by Srinivasachar et al. [1].
C5: reference viscosity, Eq. (71), proposed by Walsh et al. [395].
C6: critical velocity, Eqs. (75)–(80), proposed by Thornton and Ning [290].
C7: critical velocity, Eqs. (75), (83) and (84), proposed by Brach and Dunn [428].
C8: energy conservation and excess energy using Eqs. (91)–(95) proposed by Mao et al. [333,390,441].

Fig. 89(a) shows a graphical comparison of C2 (Zhou et al. [391]) and C5 (Walsh et al. [395]). The model of Zhou et al. [391] uses the melt fraction in order to calculate the sticking behavior. In the present case, thermodynamic equilibrium calculations using the software FactSage are applied to obtain the melt fraction as a function of temperature. However, it is questionable if it is meaningful to calculate the melt fraction for amorphous material, where there is no crystal formation. Nevertheless, this criterion is tested for completeness. Further details on FactSage can be found in the publication of Wieland et al. [312]. The model of Walsh [395] uses a reference viscosity of \( \mu_{ref} = 100 \, \text{Pa} \cdot \text{s} \), based on their experiments. The curve slope and the horizontal position can be adjusted by changing the reference viscosity. In addition Fig. 89(a) shows measured ash fusion temperatures for soda-lime glass as illustrated as vertical lines A, B, C and D. Softening (A) starts at around 790 °C and fluid temperature (D) is reached at 1170 °C. This range is used for glass particle sticking tests and simulations. Particle trajectories are calculated in ANSYS Fluent, exported and evaluated with sticking criteria C1 to C8 using a Matlab code. If a particle sticks to the reactor wall or the deposition probe, the calculation ends. If the particle rebounds, it will continue its track. Deposition rates are calculated for all ten experiments (Exp. 1 to Exp. 10) and compared with measurements. The root mean square error (RMSE) and the correlation coefficient are used as a quality indicator. It is calculated using all experiments and numerical simulation results. Simulation results and the coefficients are given in Table 23. The best correlation coefficient and RMSE are obtained for the model of Srinivasachar et al. [1] (C3) using Eq. (73), where critical viscosity is dependent on particle kinetic energy and thus its size, density and velocity. A parity plot comparing experiments and simulations is shown in Fig. 89(b). It can be seen that all three sticking criteria underpredict deposition rates, with the best agreement for Srinivasachar et al. [1] (C3). The higher deposition rates in the experiments are probably due to the stickiness of the deposit during build-up. The highest deposition rates are calculated for C4 and C5 as shown in Table 23. Both use a viscosity value at which sticking begins. They might yield better results by changing the critical or reference viscosity. However, Scholz [459] tested the sensitivity towards this threshold and results only improved slightly. Criteria based on energy or momentum conservation (C6, C7 or C8) yield acceptable results, when comparing the RMSE and correlation coefficient in Table 23. Here, the main difficulty is to find appropriate material properties, such as the Young’s modulus as a function of

![Fig. 89. Contact angle measurements of a 1.5 mm soda-lime glass particle on an Al₂O₃ ceramic substrate using an ash melting microscope and varying heating rates [532].](image)

![Fig. 88. Glass particle sticking probabilities: (a) comparison of sticking criteria and melt fraction as a function of temperature, and (b) comparison of experimental values with numerical results for three sticking criteria. Probe diameter and length inside the reactor are 15 mm and 120 mm, respectively.](image)
temperature and for different ash particle chemistry. Relatively good results are achieved with criteria based on the melt fraction. A solution could be the coupling of thermodynamic equilibrium calculations with CFD. By far the best agreement is achieved by using criterion C3, which is simple, reliable and only requires one chemistry-dependent parameter: particle viscosity.

6.3. Mechanistic modeling approach

In the following part, the mechanistic model of Mao et al. [390] (criterion C8) is examined in detail in order to explain the dependence of the critical viscosity on the particle kinetic energy (shown by criterion C3). Part of this explanation was published previously [532] and is extended here. Mechanistic expressions for ash particle rebound or sticking behavior are rare in literature. The majority of studies with mechanistic models can be found in the field of liquid droplet impaction on a solid substrate. The deformation during impact is predicted and typically validated using photographs and images from experiments. However, there is very little work on ash particles and their rebound behavior. In this section, literature equations from experiments. However, there is very little work on ash impact is predicted and typically validated using photographs and images from experiments. However, there is very little work on ash particles and their rebound behavior. In this section, literature equations are investigated in terms of their suitability for a mechanistic ash particle sticking and rebound criterion. Mechanistic models are typically based on energy conservation, as already mentioned in Section 4.3. The impaction and deformation process is subdivided into five consecutive stages as shown in Fig. 90. The energy of a particle during impaction at stage “0” is the sum of the kinetic $E_{KE,0}^p$, and the surface energy $E_{SV,0}^p$:

$$E_0 = E_{KE,0}^p + E_{SV,0}^p = \pi d_p^2 \gamma_p + \frac{1}{12} \pi d_p^3 \rho_p \gamma_p^2,$$

where $\rho_p$ is the particle density and $\gamma_p$ the droplet surface tension. Often, potential energy is neglected due its small magnitude compared to kinetic and surface energy. At stage “2”, when the particle deformation reaches its maximum, as shown in Fig. 90, the kinetic energy approaches zero $E_{KE,2}^p \approx 0$, yielding:

$$E_2 = E_{SV,2}^p = E_{SV,2,LV}^p + E_{SV,2,SL}^p - E_{SV,2,SV}^p = \left( \frac{\pi}{4} d_{p,\text{max}}^2 + \frac{2}{3} \frac{d_p^3}{\sigma_{\text{max}}} \right) \gamma_{LV} - \frac{\pi}{4} d_{p,\text{max}}^2 (\gamma_{SV} - \gamma_{SL}).$$

(141)

where surface energy at stage two $E_{SV,2}^p$ can be expressed as the sum of liquid-vapor (LV) surface energy $E_{SV,2,LV}^p$, the energy of the new solid-liquid (SL) surface $E_{SV,2,SL}^p$ minus the solid–vapor (SV) surface energy $E_{SV,2,SV}^p$, lost in the process [390]. The indices “SL”, “SV” and “LV” stand for the solid-liquid, solid-vapor and liquid-vapor surface tension. Young’s equation is used to express the unknown $\gamma_{SV} - \gamma_{SL}$ by:

$$\gamma_{SV} - \gamma_{SL} = \gamma_{LV} \cdot \cos \Theta_c,$$

(142)

where the liquid-vapor surface tension is approximated with the particle surface tension $\gamma_{LV} = \gamma_p$. Rewriting Eq. (141) and (142) yields then:

$$E_2 = E_{SV,2}^p = \left[ \frac{\pi}{4} d_{p,\text{max}}^2 (1 - \cos \Theta_c) + \frac{2}{3} \pi \frac{d_p^3}{\sigma_{\text{max}}} \right] \gamma_p.$$

(143)

Eqs. (143) and (140) assume that the particle is shaped as a thin circular disk [390,435,441]. Major studies in this field [390,435,441] calculate the maximum spread factor, defined by $z = d_{p,\text{max}}/d_p$ in order to predict the impaction behavior of a liquid droplet: e.g. sticking, rebound or splashing. Energy conservation between stage “0” and “2” yields [390]:

$$E_{SV,0}^p + E_{SV,0}^p = E_{SV,2}^p + E_{SV,2}^p - E_{SV,2,SV}^p.$$

(144)

$E_{SV,0}^p$ stands for the energy losses due to viscous dissipation. This term is usually estimated from empirical correlations or theoretical considerations as [390,441]:

$$E_{SV,0}^p = \int_0^\infty \int_0^\infty \phi \nu dt \approx \phi \nu \tau_c,$$

where $\nu$ stands for the volume of the viscous layer, $\tau_c$ for the time from initial surface contact to the maximum spread, and $\phi$ for the viscous dissipation function given by:

$$\phi = \mu \left( \frac{\partial u}{\partial x} + \frac{\partial \nu}{\partial y} \right)^2 = \mu \left( \frac{\partial u}{\partial x} \right)^2.$$

(146)

The definition of the spatial directions $x$, $y$ and the velocity components $u$, $\nu$ in Eq. (146) is shown in Fig. 63. The parameter $\mu$ is the particle dynamic viscosity, and $dud\nu/dy$ is the normal velocity gradient in the boundary layer. Eq. (146) has been widely used, however, the determination of $\phi$, $V$ and $\tau_c$ varies. Mao et al. [390] for instance distinguished between low and high viscosity droplets. High viscosity droplets are defined for cases in which the theoretical boundary layer thickness $\delta$ is larger than the droplet height. The following expression is presented for estimating the deformation energy between stage “0” and “2”:

$$E_{SV,0}^p = 0.53 \frac{W_{\nu}}{R_{\nu}^2} \gamma_p \pi d_p^4 \gamma_p^2$$

(147)

$$\frac{1}{4} \left( 1 - \cos \Theta_c \right) + 0.2 \frac{W_{\nu}}{R_{\nu}^2} \left( \frac{4 \pi d_p^3}{\zeta} \right)^2 \frac{1}{2} \gamma_p \frac{W_{\nu}}{R_{\nu}^2} \left( \frac{4 \pi d_p^3}{\zeta} \right)^2 \left( 1 + \frac{1}{12} \right) \zeta + 2 - \frac{3}{3} = 0.$$

(148)

where the resulting cubic equation of type $x^3 + px + q = 0$ can be solved easily. As mentioned in numerous studies, the maximum spread factor $\zeta$ highly depends on the droplet viscosity and the ability to deform [532]. Eqs. presented above are developed for low

![Fig. 90. Impaction stages for a high viscosity particle. Rebound probability strongly increases due to decreased deformation and energy dissipation [532].](image)
viscosity droplets such as water or alcohol droplets. Ash particles on the contrary, can have a significantly higher viscosity values in the range of $0.001 - 10^8 \text{ Pa} \cdot \text{s}$. Fig. 90 illustrates the expected impaction stages for a high viscosity fluid, e.g. a molten ash particle [532]. Estimations based on Eq. (148) yield spread factors for ash particles in the range of $0 \leq \xi \leq 2.2$. A sticking or rebound criterion can only be derived if energy losses occurring during stage “3” and “4” are considered. A particle will stick if all energy from stage “0” is dissipated. If energy is left, the particle will rebound. Therefore, the energy dissipated during droplet deformation between stage “2” and “4” $E_{DE}^4 - E_{DE}^2$, and the surface energy at stage “4” $E_{SE}^4$ have to be expressed. The droplet shape at different stages illustrated in Fig. 90 is more or less unknown for ash particles and should be studied in the near future in order to determine the exact deformation. In general, a droplet will rebound from its substrate if the following equation is satisfied:

$$E_4 = E_2 - E_{DE}^4 - E_{SE}^4 > 0. \quad (149)$$

The particle shape is needed in order to estimate the surface energy $E_{SE}^4$ at stage “4”. Mao et al. [390] assumed a spherical droplet, however, theoretical CFD simulations of Mahulkar et al. [450] predict an elliptical shape. In previous work [532], the particle shape was assumed to be a cylinder with $d_p, \min \approx 0.4 \cdot d_p$ and two hemispheres at each end. This leads to:

$$E_{SE}^4 = 43/25 \cdot d_p^2 \gamma_p. \quad (150)$$

The energy dissipated due to viscous deformation is calculated using the empirical correlation suggested by Mao et al. [390]:

$$E_{DE}^4 = 0.12 \cdot \rho \cdot \xi^2 \cdot (1 - \cos \Theta_s) \cdot \pi \cdot d_p^2 \gamma_p. \quad (151)$$

Eqs. (150) and (151) can be substituted into Eq. (149) and divided by Eq. (150) yielding:

$$E_{ERE} = 25/172 \cdot \rho \cdot \xi^2 \cdot (1 - \cos \Theta_s) + 5/125 \cdot \rho \cdot \xi - 3/43 \cdot \rho \cdot \xi^2 \cdot (1 - \cos \Theta_s) \cdot \pi \cdot d_p^2 \gamma_p > 0. \quad (152)$$

Eq. (152) calculates the excess rebound energy $E_{ERE}$, a parameter indicating whether there is energy left for rebound ($E_{ERE} > 0$) or all energy is dissipated during deformation ($E_{ERE} \leq 0$). Eq. (148) and (152) can be employed in order to predict glass particle deposition behavior as illustrated in Fig. 91. However, this requires temperature-dependent glass particle properties, which are again taken from the Appendix B. In total, ten equations are used to identify the critical temperature and thus, the critical viscosity, at which glass particles rebound and Eq. (152) fulfills the condition $E_{ERE} = 0$. These ten equations comprise of temperature-dependent properties that are viscosity, density, surface tension and contact angle, the Reynolds and Weber number, Eqs. (152) and (148), including equations for $p$ and $q$ of the cubic expression given by Eq. (148) [532]. The goal is to find the critical viscosity as a function of particle kinetic energy. Therefore, the particle kinetic energy is varied using a different particle velocities, whereas the particle diameter is kept constant at $d_p = 50 \mu m$. The same particle size was used in experiments shown in Fig. 91.

A comparison of the above-mentioned model, and equations originally proposed by Mao et al. [390] with glass particle measurements is presented in Fig. 91(a). It can be seen that the present model fits considerably better than the original equations of Mao et al. [390]. The difference between both approaches is the particle shape at stage 4 - given by Eq. (150). Equations of Mao et al. [390] predict the critical viscosity by four to five orders of magnitude. Hence, resulting deposition rates are also expected to be under predicted. This is confirmed by simulations in Table 23 for criterion C8. Müller et al. [202] applied equations of Mao et al. [390], and found that the model does not work for particles smaller than $d_p < 75 \mu m$. Instead, they used the melt fraction criterion for small particles, where particles containing $\geq 15\%$ molten phase are assumed to be sticky. Large particles with $d_p \geq 75 \mu m$ rebounded, which was successfully predicted using the model of Mao et al. [390]. Some uncertainty concerning the grid resolution exists in this study. Weber et al. [206] found in a later study, that a relatively fine grid is needed for predicting accurate particle impaction rates. Nevertheless, it is concluded that this model might be suitable for larger particles and fails in the case of small ash particles [532].

An explanation, why the model of Mao et al. [390] works for larger particles, can be seen in Fig. 91(a). The critical viscosity increases at a particle kinetic energy of $E_{p, kin} = 10^{-8} \text{ J}$, which implies that high inertia particles are sticky even at lower temperatures. It can be explained by an increased particle deformation, and thus, less remaining energy for rebound. This behavior is more pronounced for particles impacting at high velocities or for large particles. However, experimental evidence is still due, and should be studied in future work. The presented equations can explain why particles with low

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**Fig. 91.** Ash particle sticking and rebound behavior: (a) mechanistic model results compared with literature measurements [532], and (b) parameter variation of the contact angle.
The amount of kinetic energy, which can be dissipated during deformation or melting, is split into a normal (index n) and tangential (t) component. Wetting. A graphical illustration is shown in Fig. 92. When the angle deviates slightly from $\phi = 90^\circ$, the contact angle plays a minor role. Furthermore, a considerably lower sticking probability is again observed when using the equations of Mao et al. [390].

A crucial parameter is the angle of impaction $\phi$ since it influences the amount of kinetic energy, which can be dissipated during deformation and wetting. A graphical illustration is shown in Fig. 92. Particle velocity is split into a normal (index n) and tangential (t) component according to $\tan \phi = v_{p,n}/v_{p,t}$. The normal velocity is assumed to determine the impaction kinetic energy $E_{p,kin} = \pi/12 \cdot \rho_p \cdot d_p^2 \cdot v_{p,n}^2$ with $v_{p,n} = \sin \phi \cdot v_p$, which can be dissipated during impact. Solving Eq. (152) for a varying angle of impaction and determining the change in critical viscosity due to non-normal impact leads to Fig. 93(b). It can be seen that viscosity is strongly reduced, when the angle deviates slightly from $\phi = 90^\circ$. Fig. 93(a) shows a calculated sticking regime map for different angles of impaction. This map can be explained using an example: A small glass particle, with a kinetic energy of $10^{-12}$ J, will stick upon normal impact ($\phi = 90^\circ$) if its viscosity is below $10^{10}$ Pa·s. The same particle but with an impaction angle of $\phi = 75^\circ$ will stick at a considerably lower viscosity of $10^5$ Pa·s, as shown by the dashed line in Figs. 93(a) and (b). The corresponding threshold temperatures are 606°C for normal and 816°C for non-normal ($75^\circ$) impact. Thus, a decrease in impaction angle reduces the sticking probability at a given temperature. The curve shown in Fig. 93(b) can be fitted using a tangent law, as given by the second term in Eq. (154).

The equations described above require temperature-dependent properties and involve complex expressions. Therefore, a simpler model is desired. Furthermore, they are obtained for a clean and solid substrate. However, clean heat exchanger surfaces can only be found during the commissioning of a power station. Therefore, there is a need to consider an existing deposit layer and its stickiness. Typically, deposits are classified into three categories: particulate, sintered or molten [266]. The impaction of solidified fly ash particles on a particulate deposit is highly complex, as shown and discussed in Section 5.3. These solid and maybe sharp particles can lead to erosion, shedding, or they can be captured in the porous structure. In case of a molten deposit layer, e.g. on a wall of a slagging gasifier, the problem simplifies [532]. If either the particle or the surface is sticky, the particle will adhere:

$$p_{sticking} = \begin{cases} 0 & \text{for } \mu_p > \mu_{p,cri} \quad \text{and} \quad \mu_{dep} > \mu_{p,cri} \\ 1 & \text{for } \mu_p \leq \mu_{p,cri} \quad \text{or} \quad \mu_{dep} \leq \mu_{p,cri} \end{cases}$$

(153)

It is unclear if this equation is valid in case of particulate or sintered deposit. When sticking criteria are used, it is recommended to estimate the wall temperature and in case of a deposit layer its viscosity and the porosity. For CFD modeling, this can be done on a cell by cell basis as well as for wall faces. For highly porous layers, e.g. $\rho_p > 0.7$, an impacting particle can lead to shedding or more likely it is captured inside the structure, similar to a fabric filter. In all other cases, Eq. (153) can be used. Critical viscosity is then calculated using particle kinetic energy and an empirical equation fitted to measurements as shown in Fig. 91(a). It is recommended to only use the absolute particle velocity as suggested by Weber et al. [206]. The angle of impaction is introduced in a second term, using a tangent law, according to the following expression:

$$\mu_{p,cri} = A \cdot E_{p,kin}^{12} \cdot \tan^{12}(\phi) = 5 \cdot 10^{-12} \cdot E_{p,kin}^{12.78} \cdot 10^{-6.36} \cdot \tan^{12}(\phi)$$

(154)

The particle kinetic energy in Eq. (154) is calculated with $E_{p,kin} = \pi/12 \cdot \rho_p \cdot d_p^2 \cdot v_p^2$. By using Eqs. (153) and (154) a sticking regime map, as shown in Fig. 94, can be calculated. The following steps are necessary: First, the deposit and particle viscosity have to be calculated temperature- and composition-dependent. Second,
The isolines are derived using Eq. (154), sticking area is plotted for a particle kinetic energy of and the impaction angle equals the impact angle. However, in real combustions systems, particles impact on a rough surface and deformation occurs. Asymptotic approach towards the critical viscosity values as already shown in Fig. 97(a) and (b), follows the order from high to low: particle viscosity > particle temperature, an even higher sensitivity is found for the particle viscosity. If the particle viscosity is below this behavior underlines the existence for a critical value. Since viscosity is coupled exponentially to particle temperature, an even higher sensitivity is found for particle temperature. The sensitivity towards particle properties, as shown in Fig. 97(a) and (b), follows the order from high to low: viscosity > surface tension > density > contact angle. The sticking criterion given by Eqs. (153) and (154) can be implemented in CFD codes using subroutines with several sub-models for particle viscosity and density, which are all calculated composition-dependent and temperature-dependent. A possible improvement can be achieved by incorporating van der Waals forces for small particles. However, additional parameters, in particular the distance between two surfaces in contact, are needed and unfortunately unknown. Often, it is discussed, whether surface tension effects and contact angle are important. Bennett and Poulikakos [533] compared different correlations predicting the spreading of droplets during impaction. They derived regimes in which viscous dissipation, or surface tension and wetting effects dominate. Their analysis showed that if

\[ \Delta E = E_0 - E_1 \]  
(155)

and the impaction angle \( \psi \). For an elastic collision on a smooth, clean surface with no particle deformation, friction or rolling, the rebound angle equals the impact angle. However, in real combustion systems, particles impact on a rough surface and deformation occurs.

A parameter study is conducted in order to evaluate model sensitivity towards process conditions and particle properties. Studied process conditions include particle diameter, velocity and temperature; thermo-physical properties are particle viscosity, surface tension, density and contact angle with the substrate. The latter are studied individually, even though they all change with a temperature increase. Fig. 96(a) and (b) show the effect of particle diameter and particle impact velocity on the excess rebound energy. Parameters used for the sensitivity study are summarized in Table 25. The base case uses soda-lime glass particles at 800 °C. As long as the particle velocity is below \( v_p = 1 \) m/s, particle remain in the sticking regime. For instance, a 100 µm particle will rebound in between \( v_p = 1...30 \) m/s. At higher values, plastic deformation cannot dissipate all kinetic energy, and particles will rebound. A much lower sensitivity is observed for the impaction angle \( \psi \). But still, decreasing the impact angle from \( \psi = 90° \) to \( \psi = 30° \) changes the deposition characteristics significantly. At \( \psi = 90° \) all particles smaller than \( d_p = 2 \) µm stick, where this boundary moves to \( d_p = 0.3 \) µm at \( \psi = 30° \). There is a non-linear behavior at small impaction angles. The highest sensitivity for particle properties is found for the particle viscosity. If the particle viscosity is below \( \mu_p = 10^5 \) Pa·s, all particles will stick, no matter which size. But a change to \( \mu_p = 10^3 \) Pa·s leads to rebound for all particles larger than \( d_p = 2 \) µm. This behavior underlines the existence for a critical value. Since viscosity is coupled exponentially to the particle temperature, an even higher sensitivity is found for particle temperature. The sensitivity towards particle properties, as shown in Fig. 97(a) and (b), follows the order from high to low: viscosity > surface tension > density > contact angle.

Here, further work is needed to address this issue. A good assumption is to calculate the normal coefficient of restitution with 

\[ e_n^2 = \frac{\Delta E}{E_{0,n}}. \]  
(156)

This equals the ratio of normal velocity components before \( v_{p,n,0} \) and after \( v_{p,n,5} \) impaction 

\[ e_n^2 = v_{p,n,5}^2/v_{p,n,0}^2. \]

### 6.4. Model sensitivity

<table>
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<th>Parameter</th>
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<th>( v_p )</th>
<th>( \psi )</th>
<th>( T_p )</th>
<th>( \mu_p )</th>
<th>( \gamma_p )</th>
<th>( \rho_p )</th>
<th>( E )</th>
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<td>°</td>
<td>Pa·s</td>
<td>N/m</td>
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</tbody>
</table>

| Sensitivity | *** | *** | *** | *** | *** | *** | *** | *** |

|   |   |   |   |   |   |   |   |   |

\[ ^a \text{ at a temperature of } T = 800 °C \]  
\[ ^b \text{ Values taken from Fig. 96.} \]  
\[ ^c \text{ normal impact.} \]  
\[ ^d \text{ standard deviation of all values calculated for a particle size of } d_p = 10 \mu m \text{ at } T = 800 °C. \]
the following condition

\[ \text{We}_p < 2.80 \cdot Re_p^{0.457} \]  \hspace{1cm} (157)

is full-filled, surface tension and wetting become important. Above this criterion, spreading is dominated by the droplet viscosity and their ability to deform, as shown in Fig. 95. In this region, wetting and contact angle only marginally affect the deposition process. Fig. 95 shows a regime map including glass particle studies, a large Fe-rich particle at 1200 °C, and a typical Al–Si particle at 1100 °C. It can be seen that all particles are in the viscous dissipation domain, underlining the importance of viscosity. Deposition might be affected by surface tension and contact angle effects, however, controlling is the particle viscosity and the ability to deform due to low viscosity values. A further interesting topic is solidification of ash particles during the contact with the surface. Theoretical considerations and experiments of Aziz and Chandra [451] show that solidification does not change impaction as long as \( \text{Ste} / \sqrt{\text{Pe}} \cdot \sqrt{\gamma_w / \gamma_p} < 1 \). For the investigated glass particle experiments the term yields low values of 0.04. Nevertheless, it is assumed that solidification and thermal stresses induced by different thermal expansion of the steel tube and ash particles lead to rebound of a molten ash particle upon the contact. Shrinking during solidification might lead to detachment. Further research should also be directed towards this issue. The formation of a solid skin around a molten particle might also be of importance. The surface starts to cool inside the boundary layer through convection leading to a solid shell. Their role and effect on impact dynamics is, however, unknown.

7. Recommendations for modeling ash formation and deposition

Modeling ash formation, deposition and predicting the deposit chemistry, require simple and reliable models in particular when coupled with CFD in order to predict slagging and fouling propensities. There are excellent individual/standalone models available for predicting ash formation, rebound behavior or fuel conversion, however, if all models are combined and one model is inaccurate, others might suffer and the overall accuracy is not satisfying. The particle transport and the sticking criterion play a crucial role since they lead to selective deposition, where the sticking propensity mainly depends on the particle chemistry, size, velocity and temperature. Future studies predicting slagging and fouling should avoid using bulk ash chemistry. Instead detailed information on individual particle chemistry, e.g. provided by CCSEM, should be used instead. Otherwise, the prediction of the deposit chemistry, which is known to differ from the bulk ash, is not possible. Often, it is shown that ash deposits are enriched in iron [186] and/or alkali metals [535], depending on the fuel and location inside the boiler. Studies on co-combustion of wood and coal have shown that the deposit chemistry on the cylinder front face is similar to the fly ash fraction at around 2.5 μm, and the leeside deposit is similar to the sub-micron fraction at around 150 nm [66]. Hence,
models using bulk ash cannot predict ash deposit chemistry properly. A modeling approach should include solid fuel combustion, ash formation including the release of inorganics and aerosol formation, ash particle transport, ash deposition and deposit build-up. In order to describe the first three steps a number of fuel properties have to be measured or determined in advance. Fig. 97 shows the most important properties. They can be divided into fuel composition and fuel reaction kinetics. Fuel composition uses standard fuel characterization methods (ultimate, proximate and heating value analysis), particle size distribution, mineral analysis using CCSEM, as well as chemical fractionation. The first two are essential. CCSEM analysis are needed for individual particle inorganic chemistry, enabling the prediction of ash formation and deposit chemistry. X-ray powder diffraction analysis might also be a good alternative, in particular for biomass. For coal, the maceral-mineral association is important in order to model the distribution and number of mineral inclusions/grains per fuel particle. Chemical fractionation becomes more important for lower-grade fuels such as lignite or biomass with a high share of organically-bound inorganics. Components leachable in water and ammonium acetate are assumed to vaporize during devolatilization and char combustion, and thus, be responsible for chemical reactions and aerosol formation.

Reaction parameters include the kinetic parameters for devolatilization, and char combustion. The determination of these parameters requires high experimental efforts, and, carefully conducted experiments. Often, kinetic data is taken from literature using similar fuels. However, this can lead to high uncertainties. If fuel conversion and flame properties are of interest, the kinetic parameters have to be measured. With all fuel properties and kinetics being available, simulations on ash formation and deposition can be conducted. The ash formation model should be able to predict the vaporization of inorganic elements and the re-condensation of these inorganic vapors. Furthermore, coalescence, char and mineral fragmentation as well as shedding should be included - a challenging and difficult task. Here, a promising approach are percolation models such as the work of Kang et al. [477,478]. Devolatilization and char combustion are known to influence ash formation. Once ash formation can be predicted accurately in terms of chemistry and size distribution, ash deposition mechanisms are required. The most important ones are inertial impaction, thermophoresis and diffusion of aerosols. Eddy impaction can only be predicted when using unsteady simulations, ideally resolving small turbulent scales in space and time.

The ash particle sticking and rebound behavior can be described by a large number of models with varying level of detail. The following suggestions are based on the review in this work. Four different scenarios are discussed and recommendations are given:

**Salt-rich ashes**: typical for straw and herbaceous biomass

- Recommendation: Melt fraction as proposed by Isaak et al. [388,389] using Eq. (70). The melt fraction should be calculated as a function of temperature, ash particle chemistry, and gas composition surrounding the particle. Again, bulk ash should be avoided and particle to particle variation in chemistry should be considered. For the calculation of the melt fraction, commercially available tools can be used.

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**Fig. 97.** Particle sticking behavior for soda-lime glass spheres as a function of particle thermo-physical properties during the impaction: (a) particle viscosity, (b) particle surface tension, (c) particle density and (d) contact angle with the substrate at a particle velocity of 5 m/s. If one parameter is varied, others are fixed to values at 800 °C.
**Strengths:**
- Gas atmosphere (reducing or oxidizing) can be considered
- Relatively simple and straightforward
- Can be used for a wide range of ash chemistry

**Problems:**
- Thermodynamic equilibrium calculations assume infinite time, which is not given in real combustion systems
- Deposition of solid particles cannot be predicted (e.g. small solidified particles)
- Inaccuracy for large molten particles, when rebound is likely (as shown by Müller et al. [202])
- Deposit viscosity/stickiness is currently not incorporated
- Impact angle is not considered
- Difficult to implement in CFD codes and computationally expensive, when coupled with thermodynamic equilibrium calculations

**Silicate-rich ashes:** typical for coals in particular bituminous coals

**Recommendation:** Critical viscosity as a function of particle kinetic energy using Eqs. (153) and (154) together with a suitable viscosity model. The choice of viscosity model is difficult. Typically, models are valid in the Newtonian range. The sharp viscosity increase at lower temperatures is normally not considered. The only model is the one proposed by Senior and Srinivasachar [316]. However, other models are more accurate in the Newtonian range. Another suggestion is to use the model of Browning et al. [314] together with a model considering the formation of crystals in the melt as presented by Eq. (49). In this case, the melt fraction is required and should be calculated using thermodynamic equilibrium calculations.

**Strengths:**
- Predicts sticking of small, unmolten particles
- Considers the impact angle and the deposit/surface stickiness
- Predicts rebound of large, molten particles with high kinetic energy
- Very simple to implement in CFD codes

**Problems:**
- Relies on the accuracy of the viscosity model, which is only valid within a certain range
- When combined with the solid fraction in the melt: difficult to implement in CFD codes
**Tagged P**

**Economizer region:** for solidified ash particles at low temperatures ($T < 500 \, ^\circ C$)

- **Recommendation:** Critical velocity given by Eqs. (75) and (78) as suggested by Thornton and Ning [290]. An interesting model considering the impact angle is based on the work of Konstandopoulos [434], Eqs. (85) and (86) as used by Pérez et al. [301] are recommended.

- **Strengths:**
  - Based on a mechanistic model and validated in depth
  - Very simple to implement in CFD codes

- **Problems:**
  - Elastic properties ($E_i$ and $n_i$) are required as a function of temperature and chemistry
  - Only valid for smooth surfaces and cannot consider an existing powdery deposit layer
  - Does not consider the impact angle in the standard version

**Rebound behavior:** for all non-sticking particles impacting a wall

- **Recommendation:** Calculate the tangential and normal coefficient of restitution according to Eqs. (122) and (125), respectively. The friction coefficient is estimated by Eq. (134). The rebound angle should be a random number distributed evenly around a mean value calculated using (124). An improvement would be to calculate the normal restitution coefficient using Eqs. (118)–(120) or by using the energy conservation model of Section 6.3 with Eqs. (155) and (156). A promising approach might be the use of the discrete element method, which is able to describe the impact of particles on a powdery layer.

- **Strengths:**
  - This approach can predict a varying rebound angle
  - Relatively simple to implement in CFD codes

- **Problems:**
  - Empirical equations, which might not satisfy all situations
  - Particle rotation/spin is neglected
  - Particle kinetic energy does not change coefficient of restitution

The sticking behavior of wood ash is mostly unknown. Experimental data and detailed studies dealing with coarse wood ash particles are missing. This ash is rich in Ca and Mg with a relatively high melting point. Viscosity models fail in the case of Ca-rich ashes. Thermodynamic equilibrium calculations might be able to predict the melt fraction, however further studies and validations are needed in this field. A similar situation is found for ashes rich in P (found in manures) or S (for instance in lignites). In general, an energy conservation approach calculating a critical parameter is recommend. The viscosity might be a good parameter since it changes considerably with composition and temperature, and it is known to strongly affect the stickiness. The key is to find a correlation predicting the energy dissipated during particle deformation.

An exemplary calculation for silicate-rich ash particles is given in Fig. 99. Particle sticking or rebound behavior is predicted for different impact angles at an impact velocity of 2.5 m/s and a particle diameter of 20 μm. Grey values are either calculated using another equation or they give theoretical rebound behavior in case a particle sticks.

---

**Fig. 99.** Example calculation for particle sticking and rebound using the critical viscosity criterion. Soda-lime glass particle behavior is predicted for different impact angles at an impact velocity of 2.5 m/s and a particle diameter of 20 μm. Grey values are either calculated using another equation or they give theoretical rebound behavior in case a particle sticks.

---

**Table:**

<table>
<thead>
<tr>
<th>Step</th>
<th>Symbol</th>
<th>Unit</th>
<th>Eq.</th>
<th>$\phi_i$</th>
<th>$\psi_i$</th>
<th>$\beta_i$</th>
<th>$\alpha_i$</th>
<th>$\eta_i$</th>
<th>$\tau_i$</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Calculate particle kinetic energy</td>
<td>$E_{p,kin}$</td>
<td>J</td>
<td>-</td>
<td>1.27 $\cdot 10^{11}$</td>
<td>1.27 $\cdot 10^{11}$</td>
<td>1.27 $\cdot 10^{11}$</td>
<td>1.27 $\cdot 10^{11}$</td>
<td>1.27 $\cdot 10^{11}$</td>
<td>1.27 $\cdot 10^{11}$</td>
</tr>
<tr>
<td>2. Critical viscosity</td>
<td>$\rho_{p,mt}$</td>
<td>Pa s</td>
<td>154</td>
<td>1.25 $\cdot 10^6$</td>
<td>3.31 $\cdot 10^6$</td>
<td>3.56 $\cdot 10^6$</td>
<td>5.44 $\cdot 10^6$</td>
<td>6.31 $\cdot 10^6$</td>
<td>1.30 $\cdot 10^8$</td>
</tr>
<tr>
<td>3. Sticking?</td>
<td>$P_{stck}$</td>
<td>-</td>
<td>153</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>4. Restitution coeff.</td>
<td>$\epsilon_i$</td>
<td>-</td>
<td>126</td>
<td>0.18</td>
<td>0.26</td>
<td>0.30</td>
<td>0.34</td>
<td>0.43</td>
<td>0.18</td>
</tr>
<tr>
<td></td>
<td>$\epsilon_i$</td>
<td>-</td>
<td>134</td>
<td>0.00</td>
<td>0.06</td>
<td>0.13</td>
<td>0.20</td>
<td>0.20</td>
<td>0.00</td>
</tr>
<tr>
<td></td>
<td>$\epsilon_i$</td>
<td>-</td>
<td>132</td>
<td>0.71</td>
<td>0.71</td>
<td>0.71</td>
<td>0.73</td>
<td>0.84</td>
<td>0.71</td>
</tr>
<tr>
<td>5. Rebound angle and velocity</td>
<td>$\psi_i$</td>
<td>o</td>
<td>124</td>
<td>90.0</td>
<td>54.0</td>
<td>35.8</td>
<td>24.6</td>
<td>16.5</td>
<td>90.0</td>
</tr>
<tr>
<td></td>
<td>$v_{rin}$</td>
<td>m/s</td>
<td>131</td>
<td>-0.45</td>
<td>-0.64</td>
<td>-0.65</td>
<td>-0.59</td>
<td>-0.54</td>
<td>-0.45</td>
</tr>
<tr>
<td></td>
<td>$v_{rout}$</td>
<td>m/s</td>
<td>-</td>
<td>-0.45</td>
<td>-0.79</td>
<td>-1.10</td>
<td>-1.42</td>
<td>-1.89</td>
<td>-0.45</td>
</tr>
</tbody>
</table>
improvement is needed, e.g. as suggested by Eq. (156). However, the calculation of energy loss during collision is complex. There are many different equations for the calculation of the spread factor $\xi$ and the energy dissipation of liquid droplets. Bennett and Poulikakos [533] compared different equations and give an overview on the calculation of the spread factor. In this area, more fundamental and experimental work is needed aiming at molten or partially molten ash particles.

8. Concluding remarks

The present work aims for a deeper understanding of ash deposition in particular the ash particle sticking and rebound behavior. The whole process of ash formation and ash deposition is discussed critically, and main findings and mechanisms are presented for a broad spectrum of solid fuels including coals, woody and herbaceous biomass.

Ash formation is a highly complex process, which can only be predicted when distribution, form and association of inorganic species in the fuel is known. Inorganics can be found as organically-bound inorganic elements, as dissolved salts, as mineral inclusions in the fuel matrix or as excluded mineral grains separated from the fuel. The chemical composition of individual mineral grains in a fuel sample differs significantly. This variation requires the use of sophisticated methods such as SEM/EDX or CCSEM characterizing the individual particle composition and revealing information on the amount and chemistry of inorganic species. A substantial number of particles has to be detected in order to obtain independent and statistically meaningful results. It is crucial to use SEM/EDX data instead of bulk ash chemistry when predicting ash formation and ash deposition. Otherwise, wrong conclusions concerning slagging and fouling behavior can be drawn. Often, single particle types with relatively low quantity in the fuel (individual minerals/inclusions or clusters of mineral grains) are causing ash related problems, whereas the majority of fly ash particles is unproblematic and harmless. For instance, when firing bituminous coal, pyrite in reducing conditions can be such a component leading to excessive slagging of heat exchangers. Another example are small, salt-rich particles in straw combustion systems. Therefore, bulk ash composition can be misleading and models should not be based on bulk ash analyses. Ash formation mechanisms are well understood for coal, however in the case of biomass further research is needed. The exact role of fusion, fragmentation and shedding during ash formation is more or less unknown. Relatively well understood is the vaporization and recondensation of inorganic elements for straw and wood combustion. A substantial quantity of the fuel, mainly elements such as Cl, P, Pb, S, Zn and to some extent Ca, K, Mg, Na, vaporizes, recondenses and forms aerosols during cooling.

Ash deposition mechanisms are inertial impaction including eddy impaction, thermophoresis, diffusion of aerosols, condensation and reactions between deposit and inorganic vapors.
Temperature-driven effects, such as condensation, chemical reactions and thermophoresis dominate during early stages and mainly depend on the quantity of particles and inorganic vapors in the vicinity of the heat exchanging surfaces. Thermophoresis is shown to be a function of the particle and gas thermal conductivities and models found in literature differ significantly from each other.

Ash particles can be classified based on chemistry, size and shape. The first two classifications are often found in literature, however shape is rarely discussed or reviewed. Frequently observed particle shapes are:

- molten, perfectly spherical particles,
- cenospherical particles with variable wall thickness (hollow spheres),
- plerospherical particles (hollow spheres filled with small ash particles),
- angular, sharp and unmolten particles,
- loose, irregular shaped and highly porous solids, and
- agglomerations of small particles.

Ash particle shape and morphology is often studied when exploring utilization options. For modeling purposes it is often assumed that ash particles are perfectly spherical. Particle trajectories and the sticking and rebound behavior are typically calculated for spheres and shape variants are ignored. This might be valid for coal ash, at least to some extent. However, biomass ash particles are found to differ significantly from spherical particles. In case of wood, loosely bound and irregularly shaped Ca-rich particles are frequently reported together with sub-micron salt particles. Straw particles are often spherical with sub-micron particles attached to their surfaces.

**Ash particle properties** and their mathematical description are essential when modeling ash particle sticking and rebound behavior. Properties are temperature- and composition-dependent and thus often difficult to predict. The following list summarizes findings from an extensive literature review:

- Elastic properties such as Young's modulus and the Poisson number are more or less unknown for ash particles. Some rare numbers can be found, however temperature-dependence and correlations considering composition are non existent.
- The melt or solid fraction in an ash system can be calculated as a function of particle temperature, particle and surrounding gas composition using thermodynamic equilibrium calculations. Often, good accuracy is reported when comparing results with ash fusion tests or measured melting behavior from differential scanning calorimetry analysis. Nevertheless, the method has uncertainties in particular for exotic ash compositions. In addition, calculations assume infinite time, whereas in combustion systems, time scales can be very short.
- The particle viscosity is known as an important parameter for the particle sticking probability [395]. The viscosity spreads over a wide range from $10^{-7}$ to $10^9$ Pa·s. The particle viscosity can be calculated using empirical correlations. A huge number of models has been developed. However, the accuracy is often not very good. Vargas et al. [323] reviewed viscosity measurements and model predictions and recommended the model of Bottin and Weill [320] for silicate-rich ashes in the high-temperature regime, when the ash is perfectly molten and acts as a Newtonian fluid. A comparison in this work also revealed relatively good results for the model of Browning et al. [314]. When an ash particles cools down, crystals can form in the melt leading to a sharp increase in viscosity. There is only one model available incorporating this effect - the model of Senior and Srinivasachar [316]. This model is interesting and should be improved by correlating it to more measurements and a wider field of chemical compositions. Relatively good results are obtained when using a model accounting for the formation of crystals in the melt. The model of Roscoe [337], which goes back to Einstein [334] yields good results compared with measurements. The biggest concern with viscosity models is their limited range of applicability. Models easily under- or over-predict the actual viscosity by up to three orders of magnitude if used outside their validated range of composition or temperature. Models suitable for wood or herbaceous biomass are currently not available.
- Rheology of ash particles is an interesting field. But there are only few experimental studies indicating thixotropic flow behavior. Further work in this area is needed. The sintering and fusion behavior can be described using a modified equation of Mackenzie and Shuttleworth [354]. The particle density can be calculated using the method of partial molar densities as suggested for slags [345,353].
- The surface tension and contact angle of molten ash droplets can be estimated using a simple composition- and temperature-dependent approach. The surface tension varies within a narrow window (0.03 - 0.6 N/m) compared to the particle viscosity. The contact angle and thus the wetting behavior of ash particles with a solid surface is difficult to determine. Moza and Austin [349] developed a test procedure for measuring the contact angle with a supercooled substrate. Typical values are in the range of 50–150° strongly dependent on ash particle chemistry and the surface properties such as roughness, morphology and temperature.
- The thermal conductivity of ash particles and deposit strongly influences the surface temperature of a forming layer. The thermal conductivity of ash particles and/or deposits is dependent on the porosity, the temperature, the particle size, the chemical composition and radiative properties. Radiation is known to enhance thermal conductivity in porous media at high temperatures. The most important parameter is the porosity of the deposit or of particle agglomerates. Good agreement between predictions for the thermal conductivity of a porous layer with experimental data is observed when using the model of Brailsford and Major [381].

The **ash particle sticking behavior** is influenced by a number of parameters. The most important ones are: the particle properties (such as melt fraction, viscosity, surface tension/energy), the particle kinetic energy and the particle deformation upon impact, the particle shape and surface roughness, the angle of impaction, the cleavage kinetic energy and the particle deformation upon impaction, the parameters describing the sticking tendency of solidified particles. Problems arise when describing the sticking tendency of solidified particles such as sub-
micron particles, which experience rapid cooling in the boundary layer or ash particles in the economizer region. Here, other approaches are required. A further missing effect is the angle of impact. It has been shown that particles impacting under a small angle of impact are very likely to rebound. Thus, a massive molten particle, which slightly touches a superheater tube at 90°, will not stick - it will rebound.

Another quite popular approach is to use the viscosity of an ash particle at contact with a surface. This approach, however, is often applied inaccurately. There are two concepts: the reference viscosity suggested by Walsh et al. [395] and the critical viscosity first proposed as a criterion by Srinivasachar et al. [1,407]. The reference viscosity is the value at which particles start to stick partially. The critical viscosity on the other hand is the value at which the whole particle will stick. The model of Walsh et al. [395] is often used as a theoretical case for bulk ash. An intermediate sticking probability, where only a small portion of the particle will stick might occur for liquids, however for high surface tension ash particles, it is unlikely. Frequently, the reference and critical viscosity are mixed up and bulk ash composition is used. Bulk ash composition will give an inaccurate and misleading deposition rate. Furthermore, the deposit composition will equal the bulk ash composition, which is known to be incorrect. Srinivasachar et al. [1] presented an interesting approach, where the critical viscosity for glass particles was measured to be a function of the particle kinetic energy. With this approach, small particles will still adhere even at lower temperatures. The problem with this approach is that a viscosity model is required. Models have been developed for silicate-rich ashes found in coal and to some extent in straw; however, not for wood ash or waste-based fuel ashes. Furthermore, these models do not consider the angle of impaction.

Energy conservation methods have been applied in two research fields: the impaction of liquid droplets and of solid, elastic spheres. In general, these methods use energy balances in order to calculate whether a particle sticks - kinetic energy of the incoming particle is completely dissipated - or a particle rebounds - particle kinetic energy is not completely dissipated. In the case of liquid droplets, the crucial parameters are the work of deformation (against the particle viscosity) and the adhesion to the substrate (surface tension, the wetted area and contact angle). Here, the theory of Mao et al. [390] proved to be a good approach. In the case of solid particles, a critical velocity is typically measured or predicted. Here it is commonly distinguished between elastic and elastic-plastic impaction processes. In the latter case, the particle is deformed permanently. A frequently used and accurate model is presented by Thornton and Ning [290], which requires Young’s modulus and Poisson number of both collision partners.

A review on modeling studies reveals that most studies use the model of Walsh et al. [395] in combination with the bulk ash composition. Here, the latter is seen as problematic. In order to evaluate the accuracy, eight different sticking criteria based on all three methods and variants of these models are implemented in a CFD code and compared with measurements conducted in an entrained flow reactor. The mass deposited on probes is measured using three narrow size grades of soda-lime glass particles at three different temperatures mimicking coal ash particles. The best performance is found for the model of Srinivasachar et al. [1], where the critical viscosity, below which particle will stick, depends on the particle kinetic energy. A mechanistic explanation based on energy conservation and the work of Mao et al. [390] is extended in order to explain the dependence of the critical viscosity on the particle kinetic energy. Furthermore, the model now considers the impact angle and the stickiness of the substrate similar as it is proposed by Walsh et al. [395].

The particle rebound behavior is summarized for different scenarios: normal impact on a smooth surface including elastic and elastic-plastic deformation, oblique impact on a smooth surface, impact on a powdery layer, and impact on a liquid layer with an underlying solid substrate. Selected models from literature are discussed and equations are presented. These models are based on impact mechanics and require knowledge of material strength properties. Several experimental studies suggest that there is a distribution of rebound angles caused by the microscopic rough surface area. For small impact angles, rolling and sliding effects can become important depending on the friction coefficient. Interesting are the results of small spheres impacting a powdery layer. At high particle kinetic energy there is an increased chance, that particles are ejected from the bed depending on the connectivity between resting particles. A promising approach is the discrete element method for predicting the deposit formation at low temperatures, e.g. economizer region with solidified particles.

In the end, a holistic modeling approach including solid fuel combustion, ash formation and deposition is presented and recommendations for predicting particle sticking and rebound behavior are given. Currently, different approaches are recommended depending on the physical state of the particles, i.e. molten or solid, and, depending on the fuel ash chemistry. Research needs are identified and summarized in the following two sections.

8.1. Future experimental questions

Future experimental work should be directed towards a number of issues and research fields. The morphology, association and distribution of inorganic species within biomass fuels should be studied using advanced methods, such as SEM/EDX. Individual particle composition is essential for a relying ash formation model. This data should then be used as a model input. Sophisticated ash formation models, such as the percolation models developed for coal, should be applied for biomass and/or waste-based fuels. Mechanisms forming coarse fly ash particles are still not understood. Since biofuels are rich in volatile species, ash formation should be studied during devolatilization, and results should be compared to final ash composition. This helps in order to understand the interaction of Ca, Si and K species and the formation of coarse fly ash. Another crucial field of research are material properties. Viscosity measurements for typical biomass ashes, rich in Ca and/or salts are needed. Currently, viscosity measurements focus strongly on aluminosilicates. Material properties including Young’s modulus, yield strength and Poisson number are more or less unknown for ash particles. These properties should be quantified for different chemical compositions and as a function of temperature focusing on higher temperatures in the range of 300°C to 1000°C. In order to find a generally valid sticking criteria, fundamental particle impaction studies are required. High speed cameras should record the impaction process. These fundamental studies should be carried out for other materials such as salt particles (pure salts or mixtures of two or more salts), Ca-rich or Fe-rich particles. It is crucial to use uniform particle size and chemistry. The particle sticking threshold should be determined for each size and chemical composition, and be related to particle properties such as viscosity, melt fraction and the particle kinetic energy. Furthermore, the role of cenospheres and non-spherical particles should be studied. A difficult field is the particle sticking behavior of sub-micron particles. Experimental studies are rare and should be carried out. In addition, studies on particles impacting on a powdery layer have to be extended. They are valuable since clean tubes never appear in a power plant. Another controversy parameter is the impact angle. Models and experimental results often disagree here and more fundamental work on the role of impact angle on the sticking tendency is needed, in particular at high temperatures. Most of the above mentioned fields cover fundamental research. Today, the majority of studies found in literature use fuels and/or bulk ash, and try to relate their findings to empirical correlations. However, computational
methods, such as CFD or DEM, require more fundamental data and no empirical equations or indices.

8.2. Challenges for future modeling studies

An urgent need is a more sophisticated ash formation model in CFD codes. This is particular challenging for lower-grade fuels such as biomass or when fuel mixtures are fired, e.g. co-firing of coal and biomass. Here, various chemical reactions and interactions are possible leading to further complexity. The are numerous studies using a constant mineral matter content per fuel particle. Furthermore, it is assumed that mineral matter equals ash content. Therefore, standalone tools should be developed and subsequently be included in the code. There is also a need for a more fundamental viscosity model considering the network former theory. The applicability of viscosity models should be widened for straw ashes (salt-rich and K-aluminosilicates), wood ashes (Ca-rich), and SRF ashes (various compositions). An interesting aspect is, the particle cooling and deceleration within boundary layers.

CFD methods should be used to accurately predict particle behavior in the vicinity of heat exchanging surfaces. Here, the criterion of Weber et al. [206] has to be considered when constructing computational grids. Furthermore, the cooling behavior and deformation of molten droplets upon impact could be studies using volume of fluid methods. Mechanistic models based on energy conservation should be investigated and improved. A general method valid for liquids and solids is desirable. This model could be implemented in DEM simulations predicting ash deposition with a high level of detail. More work is needed in order to predict the deposit structure, erosion and shedding, as well as the collection efficiency of a porous layer.

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Appendix A

The following section summarizes different empirical viscosity models in a chronological order. Equations are empirical in nature and try to relate slag or ash composition to measured viscosity values. Values for the viscosity μ are given in Pa·s, and for the temperature T in K, if not stated otherwise.

Watt and Fereday model: A simple correlation was proposed by Watt and Fereday in 1969 [319]. It was developed for British coal ash slags and uses an Arrhenius-type equation:

$$\log \mu = - \frac{10^7 \cdot \alpha}{(T - 423.15)^2} + \beta$$

The coefficients α and β are defined as:

$$\alpha = 0.00835 \cdot SiO_2 + 0.00601 \cdot Al_2O_3 - 0.109.$$ (159)

$$\beta = 0.0415 \cdot SiO_2 + 0.0192 \cdot Al_2O_3 + 0.0276 / (equiv. Fe_2O_3) + 0.0160 \cdot CaO - 3.92,$$ and (160)

$$equiv. Fe_2O_3 = Fe_2O_3 + 1.11 \cdot FeO + 1.43 \cdot Fe.$$

where slag components are expressed as normalized weight percentages and sum up to 100% (SiO_2 + Al_2O_3 + equiv. Fe_2O_3 + CaO + MgO = 100). This correlation was suggested for high silica (> 80%) and high iron contents (> 15%) [314].

S² Correlation: The so-called S² correlation was also developed for British coal ash slags with silica contents less than 55% and iron oxide contents below 5% [314]. The equation is given by:

$$\log \mu = 4.468 \cdot \left( \frac{S_i}{100} \right)^2 + 1.265 \cdot \left( 10^6 \cdot \frac{1}{T} \right) - 7.44.$$ (162)

The silica ratio is defined by $S_i = SiO_2 / (SiO_2 + Fe_2O_3 + CaO + MgO)$. Ash oxides are in wt.% and sum up to 100%, and the Fe₂O₃ content is expressed by Eq. (161).

Bottlinga and Weill: Bottlinga and Weill [320] use the abundance of viscosity data for the development of mathematical relation. The viscosity of anhydrous silicate liquids is calculated using tabulated constants $D_i$ in the following form:

$$\log \mu = \sum_i x_i \cdot D_i - 1$$

where $x_i$ is the molar fraction, and $D_i$ a tabulated constant of species $i$. $D_i$ values are typically given for different levels of SiO₂ and temperatures in the range of 1200–1800°C. They can be found e.g. in the work of Vargas et al. [323].

Urbain Model: Urbain [321] developed a frequently used equation. They fitted measurements of SiO₂-Al₂O₃-CaO-MgO systems to a Weymann-type equation [314]:

$$\mu = 0.1 \cdot \alpha \cdot T \cdot e^{(-259.63 \cdot T^{-1/4})}$$

In Eq. (164) the viscosity is in Pa·s and the temperature in K. The coefficient α is a function of β in the form of:

$$\alpha = e^{(-296.3 \cdot \beta - 11.6725)}.$$ (165)

The coefficient β can be calculated according to the following equations:

$$\beta = \beta_0 + \beta_1 \cdot N + \beta_2 \cdot N^2 + \beta_3 \cdot N^3$$

$$\beta_0 = 13.8 + 39.9355 \cdot \delta - 44.049 \cdot \delta^2$$

$$\beta_1 = 30.481 - 117.1505 \cdot \delta + 129.9978 \cdot \delta^2$$

$$\beta_2 = -40.9429 + 234.0486 \cdot \delta - 300.04 \cdot \delta^2$$

$$\beta_3 = 60.7619 - 153.9276 \cdot \delta + 211.1616 \cdot \delta^2$$

The parameter N in Eq. (166) stands for the mole fraction of SiO₂. The quantity δ is the ratio of the mole fractions of CaO and the sum of CaO and Al₂O₃:

$$\delta = \frac{CaO}{CaO + Al_2O_3}$$

(171)
Kalmanovitch model: Kalmanovitch and Frank [322] modified Eqs. (165) and (171) and included oxides of iron, magnesium, sodium, potassium, and titanium (again as mole fractions) [314]:

$$\alpha = e^{-0.2812 \beta - 11.827}$$

$$(172)$$

$$\delta = \frac{CaO + MgO + Na_2O + K_2O + FeO + TiO_2}{CaO + Al_2O_3 + MgO + Na_2O + K_2O + FeO + TiO_2}$$

$$(173)$$

Senior and Srinivasachar model: The model proposed by Senior and Srinivasachar [316] aims at the prediction of ash particle viscosities in a broad temperature range. They therefore introduced a low and high temperature regime and use the same type of equation for the temperature-dependence as proposed by Urbanb [321]:

$$\mu = 0.1 \cdot T^{-0.5} (\text{Ng}^{0.4})$$

$$(174)$$

The coefficient $\alpha$ is defined as:

$$\alpha = a_0 + a_1 \cdot \beta + a_2 \cdot \frac{NBO}{T}$$

$$(175)$$

where $NBO/T$ is the ratio of non-bridging oxygens to tetrahedral oxygens given by:

$$NBO/T = \frac{CaO + MgO + FeO + Na_2O + K_2O - Al_2O_3 - Fe_2O_3}{SiO_2 + TiO_2 + 2 Al_2O_3 + 2 Fe_2O_3}$$

$$(176)$$

This parameter describes the behavior of glass melts and their network, explained in Section 3.3. A negative value of $NBO/T$ indicates that there is an insufficient number of modifier ions to stabilize $Al^{3+}$ and $Fe^{3+}$, which are known to act as amphoteric, i.e. they either act as glass formers or modifiers. Modifiers are known to disrupt the glass structure and thus tend to lower the viscosity [316]. Coefficients $a_i$ in Eq. (175) are given in Table 28. Values depend on the regime (low or high temperature) and on the value of $NBO/T$. The coefficient $\beta$ is derived by multiple regression analysis and can be calculated using the following equation [316]:

$$\beta = b_0 + b_1 \delta + b_2 \delta^2 + b_3 N + b_4 N^2 + b_5 N^2 \delta + b_6 N^2 \delta^2 + b_7 N^2 + b_8 N^3 + b_9 N^3 \delta + b_{10} N^3 \delta^2 + b_{11} N^3 \delta^2$$

$$(177)$$

where $N$ is again the mole fraction of $SiO_2$, $\delta$ is computed as shown in Eq. (171), and the coefficients $b_i$ can be taken from Table 26. The viscosity is calculated using Eqs. (174)–(177) for low and high temperature coefficients. The higher value of $\mu$ is then used as the viscosity at a given temperature.

Browning Model: Browning et al. [314] recently published an interesting approach, in which they investigated 1715 data points for 117 slag compositions and came up with an empirical equation in the form of:

$$\log \frac{\mu}{T - T_s} = \frac{14788}{T - T_s} \cdot 10.931$$

$$(178)$$

The temperature shift $T_s$ in Eq. (178), is computed with $T_s = 306.63 - \ln(A) - 574.31$, 

$$(179)$$

where $A$ is a molar ratio according to:

$$A = \frac{3.195Si^{4+} + 0.855Al^{3+} + 1.60K^{+} + 0.93Ca^{2+} + 1.50Fe^{3+} + 1.21Mg^{2+} + 0.69Na^{+} + 1.35Mn^{4+} + 1.47Ti^{4+} + 1.91S^{2-}}{180}$$

The quantities of each component in Eq. (160) are mole fractions, where all components sum up to unity.

**Appendix B**

Soda-lime glass is used to simulate ash for the development of a particle sticking and rebound criterion. The chemical composition in terms of oxides from different studies is given in Table 25. Only minor differences are found and it can be assumed that glasses from different studies behave similarly. The particle size distribution for different size-fractions is given in Table 27. Particles are in a relatively narrow window with the $d_{50}$ being 43, 63 and 171 $\mu$m. Ash fusion temperatures are determined for all three size-fractions. It can be seen that the fluid temperature is almost identical. Furthermore, it is observed that smaller particle sizes lead to lower IDT and ST. This is probably caused by a higher packing factor and thus an increased sintering rate at lower temperatures. The conditions and settings of different glass particle experiments from literature (shown in Fig. 60), are summarized in Table 28. Srinivasachar et al. [1] and Richter [222] used an uncooled probe composed of Al$_2$O$_3$, Schulze et al. [201] used a cooled steel probe. The particle diameters range from 40 up to 105 $\mu$m. Particle velocities range from relatively low values of 0.33 up to 4 m/s. The soda-lime glass particle properties as a function of temperature are shown in Figs. 100(a)–(f). Measurements are not found for all properties over a broad temperature range.

### Table 26

<table>
<thead>
<tr>
<th>Sample</th>
<th>Unit</th>
<th>Al$_2$O$_3$</th>
<th>CaO</th>
<th>FeO$_2$</th>
<th>K$_2$O</th>
<th>MgO</th>
<th>Na$_2$O</th>
<th>SiO$_2$</th>
<th>TiO$_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Srinivasachar et al. [1]</td>
<td>wt.%</td>
<td>0</td>
<td>8.0</td>
<td>0</td>
<td>5.0</td>
<td>15.0</td>
<td>72.0</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>Richter [222]</td>
<td>wt.%</td>
<td>0.8</td>
<td>9.3</td>
<td>0.2$^a$</td>
<td>0.2</td>
<td>3.6</td>
<td>12.9</td>
<td>72.9</td>
<td>0.1</td>
</tr>
<tr>
<td>Schulze et al. [201]</td>
<td>wt.%</td>
<td>1.0</td>
<td>8.0</td>
<td>0</td>
<td>0.5</td>
<td>4.0</td>
<td>14.2</td>
<td>72.3</td>
<td>0</td>
</tr>
</tbody>
</table>

$^a$ FeO instead of FeO$_2$.

$^b$ data from the glass manufacturer.
ture range. In such cases, extrapolations are carried out, e.g. for the Young's modulus as shown in Fig. 100(f). Properties of the substrate Al2O3 are assumed to be constant due to missing literature data. A comparison of the chosen values with soda-lime glass is given in Table 29.

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