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Elimination of Second-Harmonics in CMUTs using Square Pulse Excitation

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Abstract—The harmonic imaging mode is today a fundamental part of ultrasound imaging; it is not only used for suppressing the grating lobe artifact, but also to reduce many other acoustical artifacts in the ultrasound image. A vital performance parameter for accepting CMUT probes as a clinical usable transducer technology is, that it can support harmonic imaging. The large bandwidth of the CMUT is a clear advantage for harmonic imaging, but the inherent nonlinear behavior of the CMUT poses an issue as it is difficult to dissociate the harmonics generated in the tissue from the harmonic content of the transmitted signal. This work presents how proper pulse coding of a bipolar pulser, which is present in most commercial ultrasound scanners, can reduce the intrinsic generated harmonic to fundamental pressure amplitude ratio to below −35 dB, making CMUT probes usable for clinical applications.

I. INTRODUCTION

Capacitive micromachined ultrasonic transducers (CMUTs) are a promising alternative to piezoelectric transducers for medical ultrasound. Among the advantages are design flexibility, compatibility with CMOS, and ease of fabrication resulting in a possible lowering of transducer cost. The main selling point is, however, the low mechanical impedance of the CMUT, which results in a large immersion bandwidth and therefore high axial resolution. A consequence of the low mechanical impedance is a lower output pressure compared to PZT, which for conventional imaging is counterbalanced by a higher receive sensitivity. The large bandwidth also makes CMUTs interesting for nonlinear imaging, where pressure is transmitted at the fundamental frequency and higher order harmonics are received. The CMUTs, however, have some characteristics that cause issues in the usability for efficient nonlinear imaging. The transmit pressure of a simplified 1-D CMUT is proportional to the electrostatic force [1]:

\[ F_e = \frac{1}{2} \varepsilon_0 A \frac{V^2(t)}{(g_{eff} - w(t))^2}, \tag{1} \]

where \( \varepsilon_0 \) is the vacuum permittivity, \( A \) is the electrode area, \( g_{eff} \) the effective gap, \( w(t) \) the displacement of the plate, and \( V(t) \) the applied voltage at time \( t \). If both a DC bias voltage \( V_{dc} \) and a harmonic excitation voltage \( V_{ac}(t) = V_{ac} \cos(\omega_0 t) \) are applied, the voltage term in the electrostatic force becomes

\[ V^2(t) = V_{dc}^2 + \frac{1}{2} V_{ac}^2 + \frac{1}{2} V_{ac}^2 \cos(2\omega_0 t) + 2V_{dc}V_{ac} \cos(\omega_0 t), \tag{2} \]

with \( \omega_0 \) being the harmonic angular frequency. There are two time-dependent terms: \( 2V_{dc}V_{ac} \cos(\omega_0 t) \) and \( \frac{1}{2} V_{ac}^2 \cos(2\omega_0 t) \). The first term is responsible for the pressure generated at the fundamental frequency \( f_0 = 2\pi \omega_0 \) and is equally proportional to both \( V_{dc} \) and \( V_{ac} \). The second term generates pressure at the second harmonic frequency \( 2f_0 \) and is proportional to \( V_{ac} \) squared. This inherent nonlinear behavior of the CMUT is naturally highly unwanted for harmonic imaging, as it is difficult to dissociate the harmonics generated in the tissue from the harmonic content of the transmitted signal. The plate displacement \( w(t) \) in (1) is in addition nonlinear and is contributing to the intrinsic generation of harmonics by the CMUT itself. The level of generated second harmonic pressure has been investigated for varying DC and AC voltages, with a maximum achievable harmonic to fundamental amplitude ratio (HFR) of −12 dB, clearly emphasizing the CMUTs inherent limitations in harmonic imaging [2].

The nonlinearity caused by the voltage term can be eliminated by operating the CMUT without a bias voltage and with an excitation signal at half the fundamental frequency \( (f_0/2) \). Removing the bias voltage, however, significantly reduces the coupling coefficient. This can in principle be counterbalanced in transmit by significantly increasing the excitation voltage, but the low coupling will inevitably decrease the receive sensitivity considerably. In addition, removing the bias voltage does not eliminate the nonlinear contribution from the plate displacement \( w(t) \). Other approaches such as the use of precompensated excitation waveforms [1], [3] and gap feedback linearization [4] for suppressing the intrinsic generated harmonic of the CMUT have been demonstrated. Most current ultrasound scanning equipment does, however, not facilitate these required advanced excitation signals. Alternative pulse-shape has proven successful [5], but with a requirement of individual transducer calibration. Both requirements pose an issue in successful commercialization of a CMUT based probe for harmonic imaging. In this work, it is demonstrated how proper pulse coding of a bipolar pulser, which is present in most commercial ultrasound scanners, can significantly reduce the intrinsic second harmonic content of the pressure emitted by a generic CMUT.
II. Pulse-shapes

A variety of different periodic pulse-shapes are used in ultrasound depending on the choice of pulser. Using a bipolar 5 MHz sinusoidal pulse-shape as shown in Fig. 1a), gives the highest transferred power at the fundamental frequency. However, the non-linear squared voltage term in (2) means the CMUT will also experience a force at twice the fundamental frequency as depicted by the squared sinusoidal signal in Fig. 1b) and the Fourier spectrum of the squared pulse in Fig. 2. Another used pulse-shape is the bipolar trapezoidal plotted in Fig. 1c). The rise/fall time for trapezoidal pulse is 1/3 of half the wavelength to reduce power loss at 3rd and 5th order harmonics. The squared outcome of the trapezoidal pulse (Fig. 1d)) also generates forces at higher frequency, more specifically around 12 MHz as seen in the spectrum Fig. 2. A common pulse-shape for a commercial pulser is the step pulse seen in Fig. 1e) with a duty-cycle of 66.6% and a 5% of half the wavelength rise/fall time. The squared outcome of the step pulse (Fig. 1f) is similar to that of the trapezoidal pulse with a peak at 12 MHz in the spectrum, Fig. 2. A bipolar tri-level pulser capable of generating the step pulse depicted in Fig. 1e) can also be used to generate a square pulse-shape seen in Fig. 1g) with a 5% of half the wavelength rise/fall time. The squared outcome of the square pulse seen in Fig. 1h) ends up being a low frequency square pulse (at the length of the pulse train) overlaid with narrow square pulses at 12 MHz. The very short duration (depending on the rise and fall slopes) of the 12 MHz pulses reduces the energy of these pulses, and thus the amount of second harmonic. The result in the Fourier spectrum is clearly that higher order frequency components are highly reduced, when using a square pulse over the other pulse-shapes: sinusoidal, trapezoidal, and step.

III. Experimental Method

The effect of using a sinusoidal and square pulse excitation, respectively, are tested on a CMUT fabricated using wafer bonding and double local oxidation similar to the process presented in [6]. The linear CMUT array consists of 128 elements with an element width of 296 µm and elevation height of 5 mm. Each element contains 546 closely packed circular
CMUT cells with a radius of 24.3 µm resulting in a fill factor of 69%. The CMUT plate thickness is 1.8 µm. The bump formed in the cavity of the CMUT by the double local oxidation has a radius comprising 2/3 of the cell plate. The center frequency in water immersion is 5 MHz and the pull-in voltage \( V_{pi} \) is 220 V. The interconnect is identical to previous presented work [7] and the CMUT is coated with a \( \sim 1 \mu m \) layer of polydimethylsiloxane (PDMS) for electrical insulation. The PDMS layer is flat and has no lens effect.

The measurements with a sine pulse-shape were performed in a water tank using the experimental Synthetic Aperture Real-time Ultrasound System (SARUS) [8]. The hydrophone used was a HGL-0400 hydrophone connected to a AC-2010 pre-amplifier (Onda Corporation, CA, USA). The acoustic pressure of a plane wave emission from 12 elements was measured at 10 mm distance to the CMUT surface for a bias voltage of 160 V and varying AC voltage levels. The hydrophone was positioned at the center of the emitting CMUT element area. A two period 5 MHz excitation was used, and the emission was repeated 10 times for each voltage level combination for noise reduction.

The measurements with a square pulse-shape were performed in a water tank using a commercial bipolar square pulser from Hitachi (HDL6V5582). The hydrophone used was a Optel 10 MHz hydrophone (Optel Ultrasonic Technology, Poland). The acoustic pressure of a plane wave emission from 12 elements was measured at 10 mm distance to the CMUT surface for varying DC and AC voltage levels. The hydrophone was positioned at the center of the emitting CMUT element area. A two period 5 MHz excitation was used, and the emission was repeated 10 times for each voltage level combination for noise reduction.

A. Calculation of HFR level af CMUT surface

The measured acoustic response of the hydrophone consist of both the fundamental \((f_0)\) and harmonic \((2f_0)\) parts. To evaluate the fundamental pressure at the CMUT surface, the medium attenuation and loss of energy to higher harmonics must be added. The plane wave emission and absence of focusing lens allows for direct mapping without a diffraction compensation factor. Determining the second harmonic pressure at the CMUT surface likewise involves medium attenuation, but also the build-up of seconds harmonics caused by the nonlinear medium. For a pressure wave with constant energy (non-attenuating medium), the amplitudes of the harmonics are given by [9]

\[
p_n(\sigma) = \frac{2p_0}{n\sigma} J_n(n\sigma),
\]

(3)

where \( p_0 \) is the unperturbed pressure, \( n \) is the number of the harmonic, \( J_n \) is the Bessel function of order \( n \), and \( \sigma = z/\bar{z} \) with

\[
\bar{z} = \frac{\rho_0 \omega_0^3}{\beta \omega p_0},
\]

(4)

where \( z \) is the propagation distance of the waveform, \( \rho_0 \) is the density of the undisturbed medium, \( c_0 \) is the speed of sound for linear waves, \( \beta \) is the nonlinearity parameter (3.6 for water), and \( \omega \) is the angular frequency of the transmitted plane wave. The fundamental and second harmonic amplitudes are determined separately from the measured acoustic signal by using a low-pass and high-pass digital filter respectively. Ignoring the medium attenuation of 0.0543 dB cm\(^{-1}\) at 5 MHz, the fundamental surface pressure can be calculated directly from (3) as the unperturbed pressure \( p_0 \). The second harmonic surface pressure \( p_{HSP} \) can subsequently be calculated from

\[
P_2 = p_2 + p_{HSP} - \alpha,
\]

(5)

where \( P_2 \) is the second harmonic pressure measured at 10 mm. \( p_2 \) is the second harmonic pressure generated in the medium (calculated from (3) using \( p_0 \) and \( \alpha \) is the attenuation of 0.2170 dB cm\(^{-1}\) at 10 MHz. The harmonic to fundamental amplitude ratio at the CMUT surface can then be calculated by

\[
HFR = \frac{p_{HSP}}{p_0}.
\]

(6)

IV. EXPERIMENTAL RESULTS AND DISCUSSION

The generated pressure is measured for both the two period sinusoidal and square pulse-shape with excitation voltages
The HFR level at CMUT surface, dB

-40
-30
-20
-10
0
10
20
30
40

Peak excitation voltage, V

-40 dB and −35 dB, a level which can enable CMUT transducer square pulse-shape. The HFR level is measured to be between −10 dB depending on the excitation voltage magnitude. For HFR level for the sinusoidal pulse is between −15 dB and −10 dB the level is decreased around 25 dB to between −40 dB and −35 dB for the square pulse-shape. Not only is the difference in HFR level between a sinusoidal and square pulse-shape examined with hydrophone measurements at 10 mm distance in a water tank with 5 MHz plane wave emission and compensated to evaluate surface pressures. The HFR level for the sinusoidal pulse is between −15 dB and −10 dB depending on the excitation voltage magnitude. For the square pulse-shape the HFR level is measured to be between −40 dB and −35 dB, a level which can enable CMUT transducer use in clinical applications. A reduction achieved without the need for complex multi stage linear transmitters for advanced waveforms or specific transducer tuned pulse-shapes.

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