Research outputs:

**Bicycles and Wheelchairs for Locomotion Control of a Simulated Telerobot Supported by Gaze- and Head-Interaction**
Research output: Chapter in Book/Report/Conference proceeding › Article in proceedings – Annual report year: 2018 › Research › peer-review

**Head and gaze control of a telepresence robot with an HMD**
Research output: Chapter in Book/Report/Conference proceeding › Article in proceedings – Annual report year: 2018 › Research › peer-review

**Impact of task complexity on driving a gaze-controlled telerobot**
Research output: Contribution to conference › Conference abstract for conference – Annual report year: 2019 › Research › peer-review