DETAILED MODELLING OF CHARGING BEHAVIOUR OF SMART SOLAR TANKS

Fan, Jianhua; Andersen, Elsa; Furbo, Simon; Perers, Bengt

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- Aim:** to validate detailed models for calculation of temperature distribution and thermal stratification in smart solar tanks for solar combisystems during charging
- Method:** Computational Fluid Dynamics (CFD) modelling, temperature and Particle Image Velocimetry (PIV) measurements.
- Why smart solar tank?**

Smart solar tank charged with a variable auxiliary volume

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Lower heat loss and higher system thermal performance
- The solar tank can be charged either by an electric heating element situated in the tank or by an electric heating element in a side-arm mounted on the side of the tank.

The PIV test facility of the smart solar tank with one heating element and a side-arm.

Tank with an internal electric heating element

The CFD model of the tank with an internal electric heating element

(a). Vertical middle plane of the model (b). Cross section of the model (View A)

Thermal stratification in the tank with an internal heating element

Tank with electric heating element built in a side-arm

The CFD model of the tank with electric heating element built in a side-arm

(a) Middle plane of the model (c) Cross section of the model

Thermal stratification in the tank with a side-arm

PIV measured flow field on the middle plane of the tank 5 min after the start

CFD predicted flow field on the middle plane of the tank 5 min after the start

Conclusions:

- A mesh interval size of 0.03 m and 0.006 m is sufficient for CFD modeling of charging behavior of the tank and the side-arm, respectively. The most appropriate time step size is 3 s.
- The CFD model predicts well thermal stratifications in the tank, but gives underestimated temperatures due to incorrect heat loss of the tank which should be further investigated.
- The CFD model predicts successfully the flow pattern in the tank, although the velocity magnitude of the flow is higher than the PIV measurements.