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2.5-D Far-Field Diffraction Tomography Inversion Scheme for GPR That Takes into Account the Planar Air-Soil Interface

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Abstract — A new 2.5-D inversion scheme is derived for fixed-offset ground penetrating radar (GPR) that takes into account the planar air-soil interface. The inversion scheme is based upon the first Born approximation and a far-field approximation of the dyadic Green function for a two-layer medium.

1. Introduction

Linear inversion schemes based upon the concept of diffraction tomography have proven successful for ground penetrating radar (GPR) imaging [1, 2]. As illustrated in [2] it is important to incorporate in the inversion the presence of the air-soil interface. The inversion scheme in [2] was derived by inserting the plane-wave expansion of the two-layer dyadic Green function into the linearized Lippmann-Schwinger integral equation and performing an asymptotic expansion valid when the object is located deep in the soil and finally using the inverse Fourier transform. This procedure requires that the soil is lossless. It was shown in [2] that the procedure could be heuristically modified to include loss. However, since this heuristic modification is not exact, it gives rise to artifacts in the image.

In this paper another approach is presented to derive an inversion scheme for GPR that takes into account the planar air-soil interface. Here, the far-field approximation of the dyadic Green function for the two-layer medium is used rather than applying the asymptotic procedure outlined in [2]. Since the inverse Fourier transform is still applied to carry out the inversion, it must again be assumed in the derivation that the soil has no loss. Nevertheless, an heuristic modification is possible to include the loss and this modification does not give rise to artifacts in the image as was the case in [2]. A similar result was derived in [3] by using the generalized Radon transform. However, the inverse scheme to be presented below is more efficient than that in [3] since it can be implemented using fast Fourier transforms (FFT's).

For simplicity only the 2.5-D case is considered, that is, it is assumed that the scattered object in the soil is invariant in one direction, which for instance is the case for a pipe. Throughout the paper the time factor $\exp(-i\omega t)$ is assumed and suppressed.

2. The 2.5-D Forward Model

An example of the GPR configuration involving the planar air-soil interface is shown in Figure 1. A Cartesian xyz coordinate system is introduced such that the

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xy plane coincides with the interface and such that $z > 0$ is air. An object, which is assumed infinitely long in the \hat{x} direction, is buried in the soil. The propagation constant of air is $k_0 = \omega\sqrt{\mu_0\epsilon_0}$ and that of soil is $k_1 = \sqrt{\omega^2\mu_0\epsilon_1 + i\omega\mu_0\sigma_1}$. The position of the receiving antenna is described by $\mathbf{r}_r = \mathbf{R}_r + \hat{z}z_r$ and that of the transmitting antenna is $\mathbf{r}_t = \mathbf{r}_r + \mathbf{r}_\Delta$ with the fixed offset $\mathbf{r}_\Delta = \mathbf{R}_\Delta + \hat{z}z_\Delta$. It is assumed that the contrast in conductivity $\Delta\sigma(\mathbf{r}) = \sigma(\mathbf{r}) - \sigma_1$ is much less than the contrast in permittivity, i.e., $\Delta\sigma(\mathbf{r}) \ll \omega\Delta\epsilon(\mathbf{r})$ over the frequency band of interest $\omega_{\min} < \omega < \omega_{\max}$. Then, by assuming ideal dipole antennas, the output s_o of an \hat{x} -directed receiving antenna due to a transmitting antenna with dipole moment $\hat{x}I(\omega)$ can be related to $\Delta\epsilon(\mathbf{r})$ as [2, (11)]

$$s_o(\mathbf{r}_r, \omega) = i\omega^3\mu_0^2 I(\omega) \int_V \hat{x} \cdot \bar{\mathbf{G}}(\mathbf{r}_r, \mathbf{r}', \omega) \cdot [\hat{x} \cdot \bar{\mathbf{G}}(\mathbf{r}_t, \mathbf{r}', \omega)] \Delta\epsilon(\mathbf{r}') d^3\mathbf{r}' \quad (1)$$

where the dyadic Green function for the interface can be written as

$$\bar{\mathbf{G}}(\mathbf{r}, \mathbf{r}', \omega) = \frac{i}{8\pi^2} \int_{-\infty}^{\infty} \bar{\mathbf{F}}(\mathbf{K}, \omega) \exp(i\gamma_0(\mathbf{K})z) \exp(iR\Phi(\mathbf{K})) d^2\mathbf{K} \quad (2)$$

where $z > 0$, $z' < 0$, $\mathbf{K} = \hat{x}k_x + \hat{y}k_y$, $\gamma_i(\mathbf{K}) = \sqrt{k_i^2 - k_x^2 - k_y^2}$, $i = 0, 1$, $\Phi(\mathbf{K}) = k_x \frac{x-x'}{R} + k_y \frac{y-y'}{R} + \gamma_1(\mathbf{K}) \frac{z'}{R}$, and $R = \sqrt{(x-x')^2 + (y-y')^2 + z'^2}$. The expression for the dyadic $\bar{\mathbf{F}}(\mathbf{K})$ can be found in [2, (6)]. We now focus on the 2.5-D case in which the buried object is invariant in the \hat{x} -direction, i.e., $\Delta\epsilon(\mathbf{r}) = \Delta\epsilon(y, z)$. To this end the far-field expression of $\bar{\mathbf{G}}$, that is, the asymptotic expansion as $R \rightarrow \infty$, is inserted into (1). For $x_r = 0$ this yields

$$s_o(y_r, \omega) = \frac{i\omega^3\mu_0^2 I(\omega)}{(4\pi)^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(y_r, y', z', \omega) \Delta\epsilon(y', z') dy' dz' \quad (3)$$

where

$$F(y_r, y', z', \omega) = \int_{-\infty}^{\infty} (\hat{x} \cdot \bar{\mathbf{F}}(\mathbf{K}_r, \omega)) \cdot [\hat{x} \cdot \bar{\mathbf{F}}(\mathbf{K}_t, \omega)] \gamma_1(\mathbf{K}_r) \gamma_1(\mathbf{K}_t) \cdot \exp(i[\gamma_0(\mathbf{K}_r)z_r + \gamma_0(\mathbf{K}_t)z_t]) \frac{\exp(ik_1[R_r + R_t])}{R_r R_t} dx' \quad (4)$$

where $R_r = \sqrt{x'^2 + \rho_r^2}$, $\rho_r = \sqrt{(y_r - y')^2 + z'^2}$, $\mathbf{K}_r = \hat{x}k_{xr} + \hat{y}k_{yr} = \hat{x}k_1 \frac{-x'}{R_r} + \hat{y}k_1 \frac{y_r - y'}{R_r}$, and similarly for R_t and \mathbf{K}_t . Using the substitution $u = \rho_r^{-1}x'$, F in (4) takes on the form $\int_{-\infty}^{\infty} F_u(u) \exp(ik_1\rho_r[\sqrt{1+u^2} + \sqrt{\rho_t^2/\rho_r^2 + u^2}]) \rho_r du$. A simple asymptotic calculation as $\rho_r \rightarrow \infty$ then gives $F \sim F_u(0) \exp(ik_1[\rho_r + \rho_t]) \exp(i\frac{\pi}{2}) \sqrt{2\pi\rho_r}/(k_1(1 + \rho_r/\rho_t))$. Following the procedure of [1] ρ_r and ρ_t are next expanded around a fixed point o in the vicinity of the object and with

position vector ρ_o as $\rho_r \approx \rho_{ro} - \hat{\rho}_{ro} \cdot (\rho' - \rho_o) \approx \rho_{ro}$ with $\rho_{ro} = \rho_{ro} \hat{\rho}_{ro} = \hat{y}(y_r - y_o) - \hat{z}z_o$, and similarly for ρ_l . This yields

$$s_o(y_r, \omega) = D(y_r, \omega) \exp(ik_1 \rho_o \cdot [\hat{\rho}_{ro} + \hat{\rho}_{lo}]) \widetilde{\Delta\epsilon}(k_1[\hat{\rho}_{ro} + \hat{\rho}_{lo}]) \quad (5)$$

where $\widetilde{\Delta\epsilon}$ is the 2-D spatial Fourier transform of $\Delta\epsilon$ and

$$D(y_r, \omega) = \frac{i\omega^3 \mu_0^2 I(\omega) z_o^2 \exp(i\frac{\pi}{4})}{2\pi \sqrt{2\pi k_1 \rho_{ro} \rho_{lo} (\rho_{ro} + \rho_{lo})}} \exp(ik_1[\rho_{ro} + \rho_{lo}]) \cdot \exp\left(ik_1 \left[\sqrt{\left(\frac{k_0}{k_1}\right)^2 + \left(\frac{z_o}{\rho_{ro}}\right)^2} - 1z_r + \sqrt{\left(\frac{k_0}{k_1}\right)^2 + \left(\frac{z_o}{\rho_{lo}}\right)^2} - 1z_l \right] \right) \cdot \left(\sqrt{\rho_{ro}^2 \left[\left(\frac{k_0}{k_1}\right)^2 - 1\right] + z_o^2 + |z_o|} \right)^{-1} \left(\sqrt{\rho_{lo}^2 \left[\left(\frac{k_0}{k_1}\right)^2 - 1\right] + z_o^2 + |z_o|} \right)^{-1} \quad (6)$$

3. Inversion

Using the fact that $\Delta\epsilon$ is real, this function can be found from its Fourier transform through

$$\Delta\epsilon(\rho_o) = \frac{1}{2\pi^2} \text{Re} \left[\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \widetilde{\Delta\epsilon}(\mathbf{K}) \exp(i\mathbf{K} \cdot \rho_o) d^2\mathbf{K} \right]. \quad (7)$$

To use the relation between the measured data s_o and $\widetilde{\Delta\epsilon}$ in (5) we must assume that k_1 is real. Then, substituting in (7) $\mathbf{K} = k_1(\hat{\rho}_{ro} + \hat{\rho}_{lo})$, and using that

$$d^2\mathbf{K} = J(y_r, \omega) dy_r d\omega = \left| \frac{k_1^2 z_o (\rho_{ro}^2 + \rho_{lo}^2)}{\omega \rho_{ro}^2 \rho_{lo}^2} \left(1 + \frac{z_o^2 + (y_o - y_r)(y_o - y_l)}{\rho_{ro} \rho_{lo}} \right) \right| dy_r d\omega \quad (8)$$

we obtain

$$\Delta\epsilon(\rho_o) = \frac{1}{2\pi^2} \text{Re} \left[\int_0^{\omega_{\max}} \int_{y_{\min}}^{y_{\max}} \frac{s_o(y_r, \omega) J(y_r, \omega)}{D(y_r, \omega)} dy_r d\omega \right]. \quad (9)$$

Since the dependence of the factor $J(y_r, \omega)/D(y_r, \omega)$ on y_r is of the form $y_o - y_r$, the integration over y_r is a convolution and thus, it can be calculated efficiently using FFT's.

4. Numerical Example

The inversion scheme of Section 3 is now tested on synthetic GPR data. Figure 1 shows a dielectric pipe with outer diameter 16cm and inner diameter 8cm located 1m below the interface. The conductivities of the soil and the two regions of the pipe are 0.005 S/m. The permittivities of the soil, the inner and outer regions of the pipe are $8\epsilon_0$, $8.1\epsilon_0$, and $8.2\epsilon_0$, respectively. The synthetic GPR data

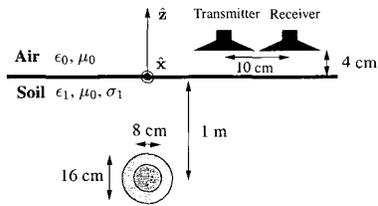


Figure 1: The configuration involving a two-region pipe.

is calculated from an eigenfunction expansion. It is assumed that the radar uses 60 frequencies equally spaced in the range $20 \text{ MHz} < f < 1.3 \text{ GHz}$. Figure 2 shows the image of $\Delta\epsilon(y, z)/\epsilon_0$ obtained from (9), heuristically modified to include loss by using $k_1 = \sqrt{\omega^2\mu_0\epsilon_1 + i\omega\mu_0\sigma_1}$ in the exponential function in the first line of (6). It is noted that there are no severe artifacts in the image below the pipe as was the case in [2].

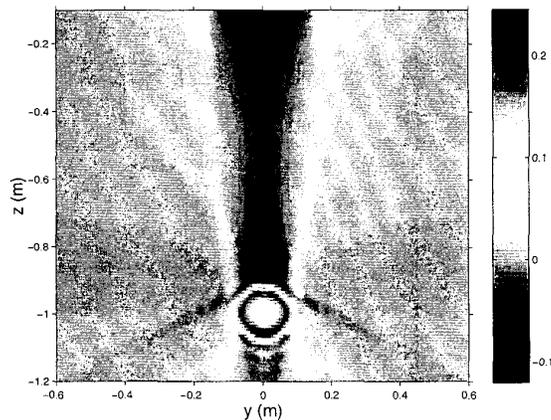


Figure 2: The image of $\Delta\epsilon(y, z)/\epsilon_0$.

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