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Published in:
IEEE Communications Letters

Link to article, DOI:
10.1109/LCOMM.2017.2697428

Publication date:
2017

Document Version
Peer reviewed version

Link back to DTU Orbit

Citation (APA):

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Error Concealment for 3-D DWT Based Video Codec Using Iterative Thresholding

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Abstract—Error concealment for video coding based on a 3-D discrete wavelet transform (DWT) is considered. We assume that the video sequence has a sparse representation in a known basis different from the DWT, e.g., in a 2-D discrete cosine transform basis. Then, we formulate the concealment problem as $l_1$-norm minimization and solve it utilizing an iterative thresholding algorithm. Comparing different thresholding operators, we show that video block-matching and 3-D filtering provide the best reconstruction by utilizing spatial similarity within a frame and temporal similarity between neighbor frames. Experimental results show that the proposed error concealment provides up to 6-dB improvement in the peak signal-to-noise ratio in comparison with existing recovery methods.

Index Terms—Video error concealment, iterative thresholding.

I. INTRODUCTION

THERE exist many applications where video data is compressed and transmitted over unreliable wireless channels, e.g., video transmission for space missions, video delivery from drones, vehicle-to-vehicle video delivery, multimedia wireless sensor networks and so on. In such applications, a video coding algorithm should generate a bit stream, which is robust to packet losses. Video coding standards, such as H.264/AVC [1] and H.265/HEVC [2], can be utilized for the transmission. Due to the motion estimation and compensation they achieve very high compression efficiency at the expense of a high sensitivity of the video stream to packet loss. As an alternative, video coding based on a 3-D discrete wavelet transform (3-D DWT) [3]–[6] encodes each group of wavelet coefficients independently. It provides a good balance between compression efficiency and robustness to packet loss.

In a DWT-based video transmission, an inverse DWT can be performed assuming that all lost coefficients are zero. This approach gives relatively good reconstruction performance, especially if the lowest subbands coefficients are delivered using additional protection, such as duplication of lowest subband coefficients [3]–[5], [7], multiple description coding [8] and/or inter-packet forward error-correction [3]–[5]. If neighbor coefficients are delivered, then a lost coefficient can be interpolated [6], [9] utilizing local correlation of a subband coefficient. This recovery method can improve the reconstruction quality without significant increase of computational complexity, but it cannot be efficiently used when many or even all coefficients of a subband are lost.

In this letter, we consider the error concealment (ERC) problem as a problem of signal recovery from incomplete measurements. The main contributions are the following:

1) We introduce a simplified video loss model where each frame is represented by 2-D DWT and transmitted over an unreliable channel, such that each coefficient is either delivered without any distortion or lost. Then we formulate the concealment problem as $l_1$-norm minimization and solve it via iterative thresholding [10]. Finally, we extend the simplified model to a realistic scenario of video streaming using the 3-D DWT codec applying 3-D transform, quantization of wavelet coefficients, bit stream packetization and packet loss.

2) We apply the proposed error concealment for 3-D DWT codecs and show that it provides up to 6 dB improvement in Peak Signal-to-Noise Ratio (PSNR) for a packet loss rate in the range from 0 to 40%.

The rest of the letter is organized as follows. In Section II we introduce the simplified video transmission model and recovery via iterative thresholding. In Section III we propose an extension of this model for a realistic scenario. The experimental results are presented in Section IV. Conclusions are drawn in Section V.

II. SIMPLE LOSS MODEL AND RECOVERY

A. Wavelet Coefficients Loss Model

Let us assume the following image transmission model.

Consider an image $X \in \mathbb{R}^{H \times W}$ as a 2-D signal of size $H \times W$ pixels. Each pixel is represented by an integer value in the range $0, \ldots, 255$. At the encoder side the image is represented via a $l$-level 2-D discrete wavelet orthogonal transform as

$$
\mathbf{w} = \mathbf{W} \cdot \mathbf{x} = [w_{ll}^1; w_{lh}^1; w_{lh}^2; w_{hh}^2; \ldots; w_{ll}^l; w_{lh}^l; w_{lh}^{l+1}; w_{hh}^{l+1}; \ldots] = \mathbf{W} \cdot \mathbf{x},
$$

where $\mathbf{X} = \text{vec}(\mathbf{X}), \mathbf{W}$ is the transform matrix, and subvectors $w_{ll}^{i+1}, w_{lh}^{i+1}, w_{lh}^{i+1}$ and $w_{hh}^{i+1}$ are called subband vectors at level $i + 1$, which are calculated as

$$
\begin{bmatrix}
w_{ll}^{i+1} \\
\vdots \\
\vdots \\
w_{ll}^{i+1}
\end{bmatrix} =
\begin{bmatrix}
w_{ll}^i \\
\vdots \\
\vdots \\
w_{ll}^i
\end{bmatrix}
\mathbf{W}^{i+1}
$$

where $w_{ll}^i = \mathbf{x}$, $\mathbf{W}^i$ is a matrix corresponding to low-pass filtering and sub-sampling for rows and columns.

We use the following notation. The column vectors and matrices are denoted by boldfaced lowercase and uppercase letters, respectively, e.g., $\mathbf{v}$ and $\mathbf{A}$. The superscript $(\cdot)^T$ denotes the transpose operation, $\text{vec}(\mathbf{A})$ concatenates columns of $\mathbf{A}$ into a vector, $[v_1; v_2]$ concatenates the column vectors $v_1$ and $v_2$ into a vector, $\lfloor x \rfloor$ denotes mapping $x$ to the nearest integer value not higher than $x$.
Building on this similarity, to reconstruct the video sequences not by a sensor, i.e., the sensing is performed by the channel.

\[ y = CWx. \]  

**B. Reconstruction via Iterative Soft Thresholding**

The basic reconstruction can be performed assuming that all lost wavelet coefficients are zero. In this case the image is reconstructed as

\[ \hat{x} = W^T C^T y. \]

Clearly, such a simplistic approach is suboptimal. To outperform it, let us consider the error-concealment problem as signal recovery from incomplete measurements, which is well-known in image super-resolution [14] and in compressive sensing [15]. In compressive sensing linear measurements are acquired for an image as \( y = \Phi x \), where \( \Phi \in \mathbb{R}^{M \times WH} \), \( M < WH \), denotes the measurement matrix composed by \( M \) rows which are randomly selected by a sensor from some matrix of size \( WH \times WH \). Then it is assumed that the signal has a sparse representation in a known basis, i.e. \( x = \Psi^{-1} \theta \), where \( \Psi \) is a \( WH \times WH \) representation matrix and \( \theta \) is the sparse vector of the transform coefficients. Under this assumption, the recovery is formulated as searching for the sparsest vector \( \theta \) which satisfies \( y = \Phi \Psi^{-1} \theta \). Herewith, the \( l_1 \)-norm can be used as a sparsity metric. In our model, the measurement matrix is \( \Phi = CW \) and \( M \) rows are randomly selected from matrix \( W \) by a communication channel, not by a sensor, i.e., the sensing is performed by the channel. Building on this similarity, to reconstruct the video sequences we solve the \( l_1 \) minimization problem utilizing the iterative soft thresholding (IST) algorithm [10]. A frame at iteration \( k \) is estimated as:

\[ \hat{x}^k = soft \left( \hat{x}^{k-1} + \Delta \hat{x}^k, \sigma_k \right), \]

where \( \Delta \hat{x}^k = W^T C^T (y - CW \hat{x}^{k-1}) \), an initial estimate \( \hat{x}^0 \) is zero-vector or a frame provided by other recovery method, and the operator \( soft (x, \sigma) \) includes three main steps:

1. A sparsifying transform with matrix \( \Psi \) is applied for a frame as \( \hat{\theta} = \Psi x \).
2. Soft thresholded transform coefficients \( \hat{\theta} = \{ \hat{\theta}_i \} \) are calculated as
   \[ \hat{\theta}_i = \begin{cases} 0, & \text{if } |\theta_i| < \sigma, \\ (1 - \frac{1}{\sigma} |\theta_i|) \theta_i, & \text{otherwise}. \end{cases} \]
3. A soft thresholded frame is calculated as \( \hat{x} = \Psi^{-1} \hat{\theta} \).

An optimal selection of \( \sigma_k \) and a number of iterations \( K \) for a given sparsifying transform is an open research problem. Experimental results show that increase of \( K \) provides better reconstruction performance of IST, but also increases computational complexity. At the same time, threshold value \( \sigma_k \) should be reduced from iteration to iteration. In this letter, we use a quadratic function [12], i.e., \( \sigma_k = \sigma_0 \left( \frac{K-k+1}{K} \right)^2 \), where an initial threshold value \( \sigma_0 \) is experimentally selected to provide the maximum reconstruction quality for a given \( K \).

Fig. 1 shows an example of reconstruction using the biorthogonal 4.4 wavelet transform with \( l = 3 \) levels at the encoder to represent 16 frames of a video sequence. The loss of wavelet coefficients is simulated in the following way. Each subband is divided into blocks of \( 2 \times 2 \) coefficients. Then, each block is lost with say 40% probability. At the decoder side, we recover the video sequence utilizing a basic reconstruction where all lost coefficients are estimated as zeros (Fig. 1 a), using linear interpolation [9] (Fig. 1 b) and using IST with \( \sigma_0 = 200 \), \( K = 40 \) and \( H \times W \) discrete cosine transform (DCT) as the sparsifying transform (Fig. 1 c). One can see that both linear interpolation and IST provide much better visual quality than the basic reconstruction.

**C. Thresholding via BM3D and VB3M3**

A higher sparsity level of a signal representation achieved by \( \Psi \) in the iterative thresholding algorithm means better quality of reconstruction. The \( H \times W \) DCT considered above achieves only a moderate sparsity level, because it only takes local similarity between pixels into account. However, it is well-known that many images have non-local self-similarity as well, i.e., there are similar blocks at different locations. In [13], an image denoising algorithm called Block-Matching and 3D filtering (BM3D) exploiting both local and non-local image similarities was proposed. First, BM3D achieves a highly sparse representation of an image using a transform which depends on an image. Then it utilizes hard thresholding and empirical Wiener shrinkage of transform coefficients depending on the noise level. As it is shown in [11] and [12], BM3D can also be used as a thresholding operator \( soft (.) \) for other applications, such as image super-resolution and compressive sensing. Finally, we can apply the thresholding operator for a group of frames to achieve an even higher sparsity level utilizing temporal similarity between frames. For this purpose we use an extension of BM3D called Video Block-Matching and 3D filtering (VB3M3) [15] as the thresholding operator. As it is shown in Fig. 1 d), VB3M3 provides much higher visual quality than other approaches.

**III. ERROR CONCEALMENT FOR 3-D DWT VIDEO CODEC**

The loss model from Section II cannot be directly applied to the 3-D DWT codec [3]–[5] due to the following differences:
headers (RTP, UDP headers etc.) and payload with video bit stream. Due to resynchronization in the arithmetic decoder, if packet $n$ of a subband is not delivered, then all packets $n+1$, $n+2$, ... belonging to the subband cannot be used for decoding (see Fig. 2). Therefore, the following three events can occur:

1) The first packet of a subband is not delivered. In this case all coefficients of the subband cannot be decoded and are marked as lost. Notice, that linear interpolation is not applicable for this model since all neighbor coefficients are also lost.

2) The encoder truncated a subband at the highest bit plane, i.e., the subband is not transmitted (skipped). In this case all coefficients of the subband are also marked as a lost coefficients.

3) One or more packets of a subband are lost, but the first packet is delivered. In this case we decode the subband until the first loss is detected, and then output the higher fully decoded bit planes. This situation is equivalent to a higher quantization level at the encoder side. In the example in Fig. 2, the original quantization step is $2^4$, but because of packet loss, we can fully decode only bit plane 3. It is equivalent to the situation when the encoder uses quantization step $2^3$ and loss does not occur.

Thus, processing of events 1 and 2 for each subband gives us coefficient loss matrix $C_{3D}$, and processing of event 3 gives us equivalent quantization steps for all delivered wavelet coefficients. Therefore, the model (3) is modified as

$$
\begin{bmatrix}
    y_1 \\ 
    \vdots \\ 
    y_F
\end{bmatrix}
= \tilde{Q}_{3D}
\begin{bmatrix}
    Q_{3D} C_{3D} W_{3D} \\
    x_1 \\ 
    \vdots \\ 
    x_F
\end{bmatrix},
$$

where $Q_{3D}$ and $\tilde{Q}_{3D}$ are the forward and inverse equivalent quantization matrices. The basic recovery (4) is modified as

$$
\begin{bmatrix}
    x_1 \\ 
    \vdots \\ 
    x_F
\end{bmatrix}
= \tilde{W}_{3D} C_{3D}^T
\begin{bmatrix}
    y_1 \\ 
    \vdots \\ 
    y_F
\end{bmatrix},
$$

where $\tilde{W}_{3D}$ is a matrix of inverse wavelet transform. Let us define $\Phi_{3D} = C_{3D} W_{3D}$ and $\tilde{\Phi}_{3D} = \tilde{W}_{3D} C_{3D}^T$. Then, utilizing (5), (8) and (9), the error concealment for the 3-D DWT codec is obtained by Algorithm 1.

IV. EXPERIMENTAL RESULTS

Experimental results were obtained for the first 128 frames of the video sequence 'Foreman' with frame resolution $288 \times 352$, and frame rate 30 Hz. In the 3-D DWT codec [3]–[5], the input video sequence was divided into groups of 16 frames. Thereafter 1-D Haar wavelet transform with 4 levels of decomposition was applied in the temporal direction for each group, and $5/3$ LeGall 2-D wavelet transform with 3 levels of decomposition was applied for each frame. Finally, bit plane coding and packetization were applied for each wavelet subband as it is described in Section III. At the encoder side, packets corresponding to the most important low-frequency subbands $w_{LL}^j$ were duplicated similarly to [7]. The video bit rate was 820 kbps including duplicated packets.

Packet loss simulation was done in the following way. The video codec generated the video stream as a set of packets with length not higher than 800 bytes. Then, we randomly

Fig. 2. Bit plane coding, packetization and packet loss.
Algorithm 1 Error Concealment for 3-D DWT Codec

Input: \( y_1, \ldots, y_M, K, \sigma_0 \)

1: for all \( k = 1, \ldots, K \) do
2: \[ \Delta y^k_1, \ldots, \Delta y^k_F \leftarrow y^k_1, \ldots, y^k_F \]
3: \[ \Delta x^k_1, \ldots, \Delta x^k_F \leftarrow \Phi_{3D} \Delta y^k_1, \ldots, \Phi_{3D} \Delta y^k_F \]
4: \[ \tilde{x}^k_1, \ldots, \tilde{x}^k_F \leftarrow \tilde{x}^k_1, \ldots, \tilde{x}^k_F \]
5: if \( k \neq K \) then
6: \[ \sigma_k \leftarrow \sigma_0 \left( \frac{K-k+1}{K} \right)^2 \]
7: \[ [\tilde{x}^k_1, \ldots, \tilde{x}^k_F] \leftarrow VBM3D([\tilde{x}^k_1, \ldots, \tilde{x}^k_F], \sigma_k) \]
8: end if
9: end for

Fig. 3. Performance comparison of different ERC’s.

removed packets from this set utilizing the independent packet loss model. The resulting bit stream was used for decoding and ERC by 3-D DWT decoder [3]–[5] to provide the recovered video sequence. Then this sequence was used as initial estimates \( \tilde{x}^1_1, \ldots, \tilde{x}^F_F \) for ERC by Algorithm 1 with \( \sigma_0 = 200, K = 40 \). The reconstructed video quality was estimated utilizing Peak Signal-to-Noise Ratio (PSNR). Since the PSNR depends on packet loss realization, we simulated 100 realizations at loss rates 10, 20 and 40 percent.

Fig. 3 a) illustrates comparison of ERC performance for each packet loss realization. Here on the x-axis we show the PSNR value after ERC provided by the 3-D DWT codec [3]–[5], while the y-axis shows the corresponding PSNR achieved by Algorithm 1. The proposed algorithm increases the PSNR by 1.8 dB in average and from 1 to 3 dB depending on packet loss realization. Furthermore, 1.1 dB improvement is achieved even for the case when all packets are delivered. This is because in our model, when the encoder skips a subband, all coefficients of this subband are marked as lost and recovered by Algorithm 1 as well.

In order to provide comparison with ERC via linear interpolation as in [6], we applied biorthogonal 4.4 2-D DWT with 3 levels of decomposition for each input frame, then 1-D Haar DWT with 4 levels of decomposition for each group of 16 frames, and SPIHT [16] encoding for each frame. The packetization was simulated in the following way. Each packet contains 11 interleaved coefficients with an interval of 4 for the root subband and all corresponding spatio-temporal descendant coefficients. As result, at the video bit rate equal to 820 kbps, the packet size was approximately 700 bytes. Then we simulated packet loss using the independent loss model, recovered the video sequence utilizing root subband averaging [6] (Fig. 3 b), x-axis) and further used the recovered video as initial estimates \( \tilde{x}^1_1, \ldots, \tilde{x}^F_F \) for Algorithm 1 with \( \sigma_0 = 200, K = 40 \) (Fig. 3 b), y-axis). Notice, that in the packetization considered all delivered coefficients are not affected by packet losses, i.e., additional quantization as in [3], [4] does not occur. Therefore, in line 2 of Algorithm 1 we use identity matrices instead of \( \tilde{Q}_{3D} \) and \( \tilde{Q}_{ID} \). Comparing to the root subband averaging the proposed ERC increases the PSNR by 4.9 dB in average, from 3 to 6 dB depending on packet loss realization and by 1.5 dB when all packets are delivered.

V. Conclusion

In this letter we presented an error concealment algorithm based on iterative thresholding which can be utilized in 3-D DWT video codecs for both coding performance improvement and transmission over unreliable channels.

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