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Data Article

# Normalized performance and load data for the deepwind demonstrator in controlled conditions



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### ABSTRACT

Performance and load normalized coefficients, deriving from an experimental campaign of measurements conducted at the large scale wind tunnel of the Politecnico di Milano (Italy), are presented with the aim of providing useful benchmark data for the validation of numerical codes. Rough data, derived from real scale measurements on a three-bladed Troposkien vertical-axis wind turbine, are manipulated in a convenient form to be easily compared with the typical outputs provided by simulation codes. The here proposed data complement and support the measurements already presented in “Wind Tunnel Testing of the DeepWind Demonstrator in Design and Tilted Operating Conditions” (Battisti et al., 2016) [1].

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## Specifications Table

Subject area	Physics
More specific subject area	Wind engineering
Type of data	Tables, graphs, figure
How data was acquired	Precision torquemeter, absolute encoder, 2 full strain gauge bridges
Data format	Filtered and analyzed
Experimental factors	Raw data are normalized using coefficients typically adopted in wind turbine engineering
Experimental features	Open jet wind tunnel and high precision test bench
Data source location	Trento, Italy
Data accessibility	All the data are presented in this article

## Value of the data

- The primary objective of the measurement campaign conducted on the DeepWind reduced scale demonstrator is to provide information needed to quantify the three-dimensional aerodynamic behavior of a Troposkien wind turbine in both design (i.e. upright) and tilted (up to 15° with respect to the vertical axis, as shown in Fig. 1) operating conditions to quantify the impact of the tilting angle.
- Contrarily to open field testing, the here presented data allow numerical researchers to develop and validate enhanced engineering models on the basis of full-scale measurements conducted in an environment free from pronounced inflow anomalies.
- Great care is adopted in the description of the presented experimental data, in order to provide a useful benchmark for numerical simulations.

## 1. Data

Aerodynamic raw data measured during the wind tunnel campaign were rotor torque ( $Q_{\text{aero}}$ ), rotor thrust (both in the longitudinal direction  $T_X$  and in the transversal one  $T_Y$ ), rotor rotational speed ( $\omega$ ) and wind tunnel speed ( $V_\infty$ ). These data are here presented in a convenient form typically adopted in wind turbine engineering. As a matter of fact, to provide more insights on rotor behavior, aerodynamic torque ( $C_{Q,\text{aero}}$ ) and thrust ( $C_{TX}$  and  $C_{TY}$ ) coefficients are provided in Tables 1–4, as a function of the equatorial Tip Speed Ratio ( $\text{TSR}_{\text{eq}}$ ) computed at rotor equatorial diameter.

In order to disclose the influence of the blade Reynolds number ( $Re$ ) on aerodynamic torque, power and thrust coefficients, Figs. 2–6 show a comparison between the data obtained at two rotor angular velocities, respectively 200 rpm ( $Re = 1.38 \times 10^5$ ) and 300 rpm ( $Re = 2.05 \times 10^5$ ).

## 2. Experimental design, materials and methods

The experimental campaign was conducted at the Politecnico di Milano (IT) large scale wind tunnel, characterized by a working section of 4.00 m width and 3.84 m height. The wind tunnel was operated in a “free jet” (open) configuration with a central section of 6.00 m length. Rotor torque and thrust measurements were taken using a high precision test bench, which was instrumented using a precision torquemeter (to provide rotor aerodynamic torque), an absolute encoder (to provide rotor angular velocity) and 2 full strain gauge bridges (to provide rotor aerodynamic thrusts in both the longitudinal direction and in the transversal one).

Both upright and 15° tilted rotor configurations were tested in the open jet wind tunnel, as schematized in Fig. 1, showing also the local coordinate system for the longitudinal ( $X$ ) direction

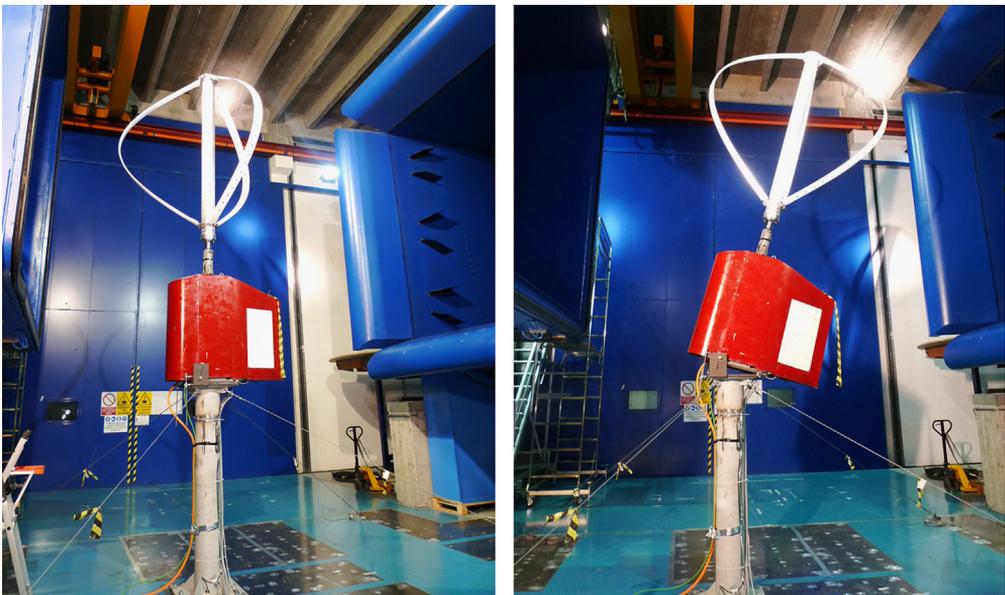
## Nomenclature

$A$	rotor swept area (m <sup>2</sup> )
$c$	blade chord length (m)
$C_{TX}$	$\frac{T_X}{0.5\rho AV_\infty^2}$ = X-thrust coefficient (dimensionless)
$C_{TY}$	$\frac{T_Y}{0.5\rho AV_\infty^2}$ = Y-thrust (dimensionless)
$C_{Q,aero}$	$\frac{Q_{aero}}{0.5\rho ARV_\infty^2}$ = torque coefficient (dimensionless)
$Q_{aero}$	aerodynamic torque (Nm)
$R$	maximum turbine radius (m)
$Re$	$\frac{\omega Rc}{\nu}$ = chord Reynolds number (dimensionless)
$T_X$	X-thrust (N)
$T_Y$	Y-thrust (N)
$TSR_{eq}$	$\frac{\omega R}{V_\infty}$ = equatorial Tip Speed Ratio (dimensionless)
$V_\infty$	free stream wind speed (m/s)

## Greek

$\nu$	freestream air kinematic viscosity (m <sup>2</sup> /s)
$\rho$	freestream air density (kg/m <sup>3</sup> )
$\Omega$	rotor angular speed (rpm)
$\omega$	rotor angular speed (s <sup>-1</sup> )

adopted during thrust measurements. It is worth observing that only the aerodynamic thrust is provided in all tables and graphs, i.e. no corrections have been introduced in order to avoid the rotor tower drag force. Furthermore, for tilted tests, the strain gauge offset has been recorded with tilted



**Fig. 1.** Side view of the Politecnico di Milano open chamber, showing also the tested rotor arrangement for both design (left) and tilted (right) operating conditions.

**Table 1**Upright rotor at  $\Omega=200$  rpm.

<b>TSR<sub>eq</sub></b> <b>[dimensionless]</b>	<b>C<sub>Q,aero</sub></b> <b>[dimensionless]</b>	<b>C<sub>TX</sub></b> <b>[dimensionless]</b>	<b>C<sub>TY</sub></b> <b>[dimensionless]</b>
1.42	0.022	0.362	-0.116
1.52	0.025	0.378	-0.119
1.63	0.028	0.401	-0.124
1.78	0.030	0.426	-0.132
1.94	0.035	0.454	-0.135
2.12	0.047	0.496	-0.126
2.35	0.056	0.552	-0.127
2.63	0.064	0.612	-0.134
3.00	0.074	0.685	-0.150
3.28	0.077	0.715	-0.167
3.41	0.077	0.734	-0.171
3.53	0.078	0.763	-0.166
3.72	0.074	0.767	-0.166
3.89	0.067	0.764	-0.165
4.07	0.059	0.781	-0.170
4.26	0.046	0.798	-0.172
4.77	0.014	0.761	-0.195
5.34	-0.023	0.774	-0.217

**Table 2**Upright rotor at  $\Omega=300$  rpm.

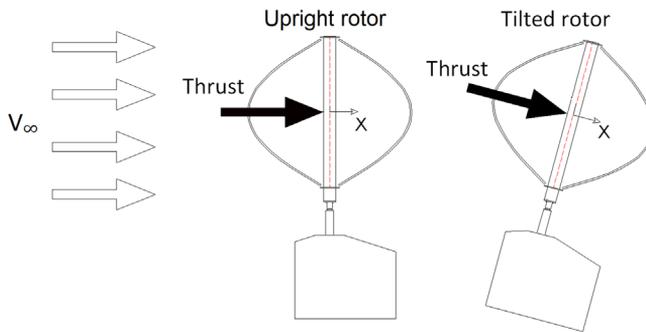
<b>TSR<sub>eq</sub></b> <b>[dimensionless]</b>	<b>C<sub>Q,aero</sub></b> <b>[dimensionless]</b>	<b>C<sub>TX</sub></b> <b>[dimensionless]</b>	<b>C<sub>TY</sub></b> <b>[dimensionless]</b>
2.12	0.063	0.505	-0.150
2.27	0.070	0.539	-0.154
2.45	0.078	0.579	-0.158
2.68	0.091	0.634	-0.160
2.92	0.101	0.692	-0.164
3.18	0.104	0.738	-0.167
3.38	0.102	0.763	-0.169
3.54	0.097	0.785	-0.165
3.76	0.088	0.798	-0.171
3.98	0.078	0.814	-0.166
4.26	0.062	0.817	-0.178
4.56	0.044	0.818	-0.181
4.91	0.024	0.806	-0.197
5.33	0.000	0.781	-0.205
6.39	-0.060	0.735	-0.246
8.17	-0.146	0.759	-0.338

**Table 3**Tilted rotor at  $\Omega=200$  rpm.

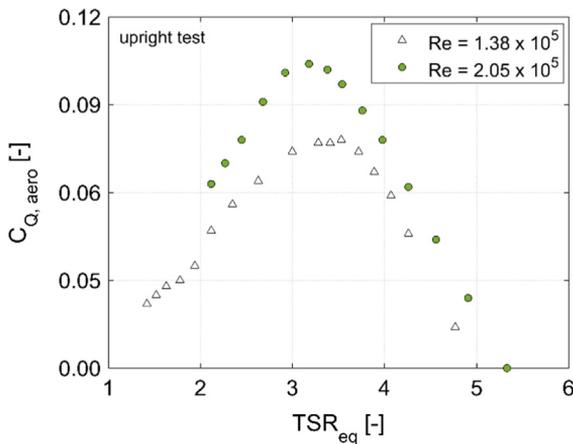
<b>TSR<sub>eq</sub></b> <b>[dimensionless]</b>	<b>C<sub>Q,aero</sub></b> <b>[dimensionless]</b>	<b>C<sub>TX</sub></b> <b>[dimensionless]</b>	<b>C<sub>TY</sub></b> <b>[dimensionless]</b>
1.52	0.024	0.367	-0.123
1.64	0.027	0.388	-0.129
1.78	0.032	0.411	-0.132
1.94	0.035	0.441	-0.139
2.12	0.044	0.483	-0.134
2.36	0.053	0.527	-0.136
2.64	0.061	0.583	-0.147
3.03	0.069	0.664	-0.162
3.29	0.071	0.708	-0.175
3.54	0.065	0.733	-0.175
3.87	0.059	0.764	-0.185
4.21	0.041	0.766	-0.176
4.77	0.012	0.789	-0.203

**Table 4**  
Tilted rotor at  $\Omega=300$  rpm.

$TSR_{eq}$ [dimensionless]	$C_{Q,aero}$ [dimensionless]	$C_{Tx}$ [dimensionless]	$C_{Ty}$ [dimensionless]
2.14	0.062	0.489	-0.146
2.29	0.068	0.521	-0.152
2.46	0.075	0.556	-0.156
2.67	0.082	0.602	-0.162
2.92	0.091	0.657	-0.165
3.20	0.094	0.709	-0.171
3.54	0.089	0.753	-0.173
4.01	0.059	0.783	-0.171
4.55	0.040	0.796	-0.181
5.28	-0.002	0.773	-0.201
6.25	-0.054	0.732	-0.240



**Fig. 2.** Scheme of the local coordinate system in the longitudinal direction.



**Fig. 3.**  $C_Q$  curves for the upright rotor at 200 rpm ( $Re=1.38 \times 10^5$ ) and 300 rpm ( $Re=2.05 \times 10^5$ ).

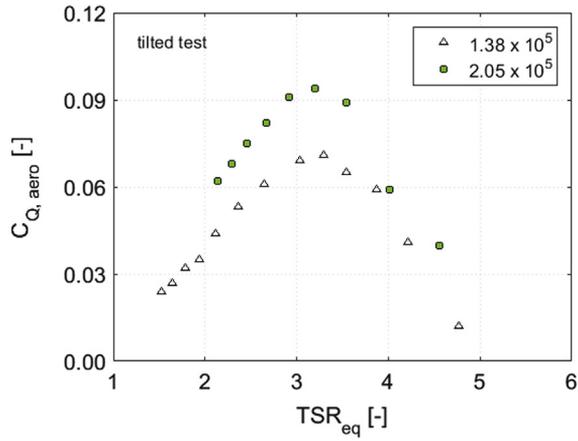


Fig. 4.  $C_Q$  curves for the tilted rotor at 200 rpm ( $Re=1.38 \times 10^5$ ) and 300 rpm ( $Re=2.05 \times 10^5$ ).

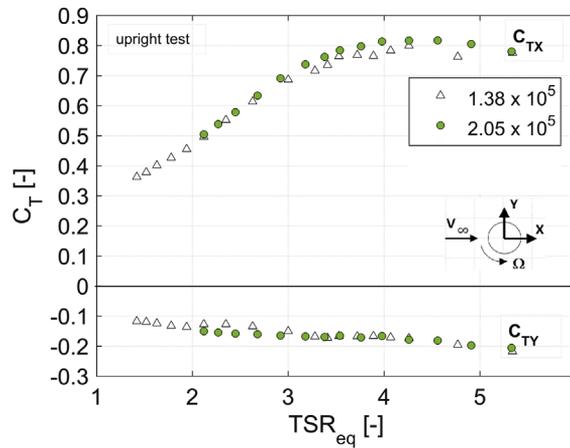


Fig. 5.  $C_{TX}$  and  $C_{TY}$  curves for the upright rotor at 200 rpm ( $Re=1.38 \times 10^5$ ) and 300 rpm ( $Re=2.05 \times 10^5$ ).

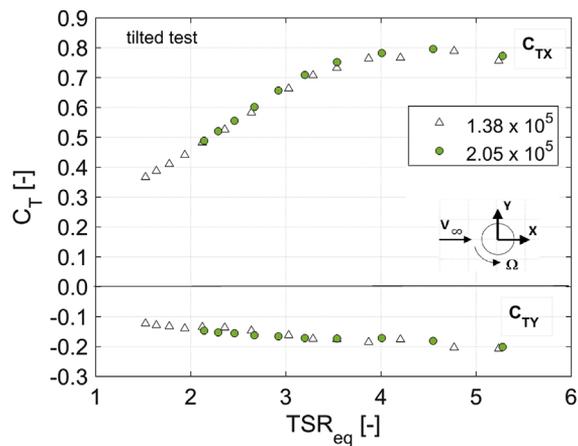


Fig. 6.  $C_{TX}$  and  $C_{TY}$  curves for the tilted rotor at 200 rpm ( $Re=1.38 \times 10^5$ ) and 300 rpm ( $Re=2.05 \times 10^5$ ).

rotor: it was therefore possible to measure the wind thrust avoiding the component due to rotor weight bending moment.

See [1,2] for more details regarding data acquisition and data processing techniques.

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## Transparency document. Supporting information

Transparency data associated with this article can be found in the online version at <http://dx.doi.org/10.1016/j.dib.2016.07.029>.

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