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Maximizing Entropy of Pickard Random Fields for 2x2 Binary Constraints

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Abstract—This paper considers the problem of maximizing the entropy of two-dimensional (2D) Pickard Random Fields (PRF) subject to constraints. We consider binary Pickard Random Fields, which provides a 2D causal finite context model and use it to define stationary probabilities for 2x2 squares, thus allowing us to calculate the entropy of the field. All possible binary 2x2 constraints are considered and all constraints are categorized into groups according to their properties. For constraints which can be modeled by a PRF approach and with positive entropy, we characterize and provide statistics of the maximum PRF entropy. As examples, we consider the well known hard square constraint along with a few other constraints.

I. INTRODUCTION

We consider the problem of determining and maximizing the entropy of image models with constraints. In applications such as 2D data storage, the encoding of information might be subject to a constraint related to the physical properties of the media. This can lead to complex data structures and data sources with memory. If such data sources are constrained, the possible patterns will be limited and the per symbol information capacity of the source will be reduced, but the density may be increased. In the 2x2 binary setting the problem can be regarded as filling a NxM 2D grid with binary symbols with maximum information. Under these circumstances, we seek the maximum entropy and the corresponding coding model to fill the grid without violating the given constraint. For block Pickard models of higher order see [1].

The capacity of the binary source in terms of how much information that can be stored per symbol in the grid is defined by the combinatorial entropy C:

\[
C = \lim_{N \to \infty} \log_2 \frac{E(N)}{N^2}
\]

where \(N\) is the width of a square grid with \(E(N)\) admissible outcomes [2, p. 122]. The maximum entropy of the Pickard Random Field (PRF) [3] subject to a constraint provides a causal model which provides a lower bound on the capacity of the constraint. The PRF also provides a probability distribution of the symbols that can be used for coding purposes.

We formulate the problem as follows: given a constraint in form of a set of binary 2x2 non-admissible configurations, decide if a PRF can be defined that does not have a non-admissible configuration as any subset of any possible outcome. If PRF can be defined, determine the maximum entropy of the PRF field and if the entropy of the field is greater than 0, determine the parameters of the PRF. In this setting, we define invalid constraints as constraints where there is a possibility of reaching a configuration that has no solution when filling the grid. A constraint which is not invalid is considered to be valid. We consider this problem for all \(2^{16}\) cases for 2x2 binary constraints and provide statistics for the cases with field entropy greater than 0. We also provide detailed examples.

II. PICKARD RANDOM FIELDS

PRF is defined as a 2D causal probabilistic model where the probability assignments for rows and columns share the property that the symbols are outcomes of the same irreducible Markov chain over a finite alphabet [3]. Our aim is to find a probability distribution for the symbols on a grid. If \(X\) denotes a random variable describing the field, we want to maximize the entropy \(H(X)\). The entropy on a \(N \times M\) rectangular grid can be expressed by the chain rule:

\[
H(X) = \sum_j H(x_j|x_1, x_2, \ldots, x_{j-1})
\]

where each symbol in the grid is assigned a one-dimensional index \(j\) e.g. in row-by-row order. However, in a 2D structure which can be expressed by a Markov Random Field (MRF), non-causal interaction might exist. Therefore we turn to PRFs, which provide us with causal 2D models in this environment.

PRFs are special cases of MRFs. PRFs have some desirable properties such as causality, sequential simulation of a random field and the property that the symbols in rows and columns are outcomes of irreducible Markov chains over a finite alphabet. A PRF is stationary and its joint probability can be determined by a 2x2 measure which must satisfy a constraint. The probability of each column or row is described by a Markov chain and transition probabilities which can be derived from the 2x2 measure. We assume the Markov chains for the rows to go from left to right and for the columns to go from bottom up. The PRF starting point is in the upper left corner. The Markov chains for rows and columns can be different.

We denote the 2x2 square consisting of random variables \(X_{i,j}\) from a finite alphabet on the 2D grid as follows:

\[
\begin{bmatrix}
X_{i,j} & X_{i,j+1} \\
X_{i+1,j} & X_{i+1,j+1}
\end{bmatrix}
\begin{bmatrix}
A & B \\
C & D
\end{bmatrix}
\]

After initializing the first row and column in the grid by using the Markov chains, the 2x2 square (3) can be moved one
The condition and columns which case (5-6) would be defined along the other diagonal. The starting point can also be the lower left corner [1], [3], in

With this assumption the top row of the grid can be modeled

probability distribution of the pair of symbols

information that can be stored in the grid by this approach.

Since the contribution to the entropy will be dominated by

rows are described by the same Markov chain [3]:

\[ P(ABC) = P(B|A)P(A|C)P(C) \] (5)

With this assumption the top row of the grid can be modeled as a single Markov chain by the distribution of \( AB \). We use the condition \( P(C|BD) = P(C|D) \) to assure that the other rows are described by the same Markov chain [3]:

\[ P(BCD) = P(B|D)P(D|C)P(C) \] (6)

The starting point can also be the lower left corner [1], [3], in which case (5-6) would be defined along the other diagonal.

B. Consistency conditions

We denote the matrices for the Markov chains of the rows and columns \( R \) and \( S \), respectively. For consistency with the joint measure \( (ABCD) \) the two distributions \( (ABC) \) and \( (BCD) \) must have identical marginal distribution on \( (BC) \). Since the transition from \( C \) to \( B \) can be achieved in two ways (i.e. either by going right and then up or vice versa) due to (5-6) the transition matrices must commute [1]:

\[ RS = SR \] (7)

The last requirement is that the joint conditional probability \( P(AD|bc) \) should be consistent with the marginal conditional probabilities \( P(A|bc) \) (5) and \( P(D|bc) \) (6), which gives us [1]:

\[ \sum_d P(A, D = d|bc) = P(A|bc) \] (8)

\[ \sum_a P(A = a, D|bc) = P(D|bc) \] (9)

The entropy of the PRF will converge to \( H(D|ABC) \) since the interior of the field will dominate over the boundaries. In the general case this can be solved by iterative scaling [1].

\[ H(D|ABC) = -\sum_{abcd} P(abcd) \log_2 P(d|abc) \] (10)

For values \( (bc) \) of \( (BC) \) where \( (abcd) \) is admissible for all \( (ad) \), the maximum entropy is simply obtained by

\[ P(D|Abc) = P(D|bc) = P(bcD)/P(bc) \] (11)

C. Probabilistic aspects of binary PRF

We solve the PRF in general using (7-9) over the binary alphabet. With a binary alphabet the transition matrices \( R, S \) for rows and columns, respectively, can be defined as:

\[ R = \begin{bmatrix} p & 1-p \\ 1-s & s \end{bmatrix} \quad S = \begin{bmatrix} q & 1-q \\ 1-r & r \end{bmatrix} \] (12)

Since the matrices \( R \) and \( S \) have to commute (7) we can set each element in \( RS \) equal to the corresponding element in \( SR \). Solving any of these equations gives us the following relation between the variables:

\[ r + p - rp = s + q - sq \] (13)

This relation can be used to express one of the variables by the other variables. This ensures that the commutation requirement (7) is fulfilled and it also reduces the number of free variables by one. Under certain constraints with positive entropy, one or two of the variables \( p, s, q, r \) can be set to 0 (but not 1) reducing the complexity of the entropy maximization; e.g. for the straightforward formulation of the hard-square constraint 4 one would set \( r = s = 0 \) and would only need to determine the value for \( p = q \) that maximizes the entropy.

The stationary probabilities \( p_t = p_t R \) and \( p_t = p_t S \) of the two Markov chains should be equal. In the binary case this leads to the same relation as (13). Thus, in a 2x2 binary PRF the equality condition for the stationary probabilities is equivalent to the commutation condition (7).

Some requirements follows from this formulation of the problem. The variables \( p, s, q, r \), including the one expressed by the relation in (13), should be constrained to the range \([0, 1]\). Let \( \bar{a} \) be the inverted value of the binary symbol \( a \).

By definition it is required that \( (A, B = b, C = c, D) \) configurations for pairs of \( (bc) \) where \( A = a, D = d \) is invalid, but \( (AbcD) \) still contributes to the entropy should satisfy:

\[ P(bcd) \leq P(\bar{a}bc) \] (14)

This inequality can be used to bound our choice of starting points for the free variables before applying maximization.

D. Calculating and maximizing the entropy

We characterize all possible contributions to the maximum entropy in a binary 2x2 PRF. The contributions to the entropy (10) can be calculated as follows. For pairs of \( (bc) \) for which all combinations are admissible following (11) the contribution to the maximum PRF entropy can be expressed by:

\[ H_{bc}(D|ABC) = P(bc)H \left( \frac{P(bcd)}{P(bc)} \right) \] (15)

For pairs of \( (bc) \) where one of the combinations of \( AD, A = a, D = d \), is non-admissible we may solve (8-9) directly and the entropy contribution is calculated as:

\[ H_{bc}(D|ABC) = P(\bar{a}b, A = a)H \left( \frac{P(bcd, D = d)}{P(\bar{a}b, A = a)} \right) \] (16)

as \( P(\bar{a}bcd) = P(bcd) \) and for \( abc \) the entropy contribution is 0. For pairs of \( (bc) \) where \( A = a \) is non-admissible i.e. for
both $D = 0$ and $D = 1$, we get $P(\overline{abcd}) = P(bcd)$, $P(\overline{abc}) = P(bc)$ so (15) can be used again.

In other cases for the pairs of $(bc)$ there is no contribution to the entropy. Using (5-6) the contributions in (15-16) can be calculated directly from the Markov chains $R$ and $S$.

Finally the maximum conditional entropy is calculated as the sum of the non-zero contributions given by (15) and (16):

$$H(D|ABC) = \sum_{bc} H_{bc}(D|ABC)$$  \hspace{1cm} (17)

For given parameters $p, s, q, r$ this provides the maximum PRF entropy of the constraint. Depending on the constraint there will be 1 to 3 free parameters. We can maximize the conditional entropy (17) over the space given by the free parameters and restricted by (13) and (14).

III. Constraint Analysis

Our goal is to analyze all $2^{16}$ possible 2x2 binary constraints and identify those for which we can define a PRF with positive entropy, i.e. in (10) $H(D|ABC) > 0$. To achieve this we can start by identifying constraint sets for which it is not possible to define a PRF with positive probabilities of all admissible $(abcd)$. We will take a closer look at what can be considered to be degenerate cases and why they occur.

We start out by introducing the concept of a constraint family. Some constraints can be characterized by having one or more configurations which can not appear in the PRF, but removing these provides a subset $F$ for which all admissible configurations appear. We call this set the father set and the sets with identical fathers form a family. Let $i, j$ be indexes, then a constraint $c_i$ belongs to the same family as the constraint $c_j$ if $F$ of the non-admissible configurations in $c_i$ is equal to $F$ of the non-admissible configurations in $c_j$:

$$F_i = F_j$$  \hspace{1cm} (18)

In other words, the set of non-admissible configurations $N_i$ for the constraint $c_i$ is a subset of $F_i$:

$$N_i \subseteq F_i$$  \hspace{1cm} (19)

Inverting the binary symbols of a configuration may change the values but we consider the structure to be the same and extend the family definition such that the members of a family have $F$ or the inverted set $F'$ as their father set.

A. Analysis of configurations

We consider whether a PRF with positive entropy can be achieved for different categories of constraints and from the categories we derive necessary conditions. The categories are presented in the order which they are used to classify the constraints. Classified constraints are not considered again, thus the categories are disjoint. The first type of classification can be done solely on the constraints without considering Markov chains. They are denoted Bk for bit-stuffing, where $k$ is an index. We define bit-stuffing as a PRF without imposing (5-9) and where all admissible configurations are possible.

Let $N_i$ be the set of non-admissible configurations and the compliment set $A_i$ the set of admissible configurations defining the constraint $c_i$. Let $N_i^*$ be the union of $N_i$ and the subset of configurations $(\overline{abcd})$ in $A_i$ where:

$$\overline{cd} = ab \quad \text{if} \quad abed \in N_i, \forall ab$$

$$\overline{ab} = cd \quad \text{if} \quad abed \in N_i, \forall cd$$

$$\overline{bd} = ac \quad \text{if} \quad abed \in N_i, \forall ac$$

$$\overline{ac} = bd \quad \text{if} \quad abed \in N_i, \forall bd$$  \hspace{1cm} (20)

Let $A_i^*$ be the complementary set of $N_i^*$. Repeat this process with $N_i^*$ and $A_i^*$ and denote the resulting sets $N_i^{**}$ and $A_i^{**}$. A constraint $c_i$ is considered to contain a trap if:

$$(abc, D = 0) \land (abc, D = 1) \in N_i^{**}$$

$$\exists a'b' : (a'b', C = a, D = b) \in A_i^{**}$$

$$\exists a'c' : (a'c', B = a, D = c) \in A_i^{**}$$  \hspace{1cm} (21)

We consider constraints to be invalid if they contain a trap since there is a non-zero probability of reaching the trapping configuration. This set of constraints is denoted B1.

B2 is defined as constraints which forces one or more parameters $p, r, s, q$ in (12) to 1, in which case the underlying Markov chain only has one state or is an absorbing Markov chain. In the latter case, the entropy of the field degenerates to 0, since the absorbing Markov state cannot be left. This can be determined by looking at the rows or columns where this occurs separately i.e. either 0 or 1 can never change in one direction. Disregarding the two uniform cases, the constraints in this category are non-stationarity.

B3 is defined by the constraint forcing one of the following pairs of parameters to $\{0,0\}$:

$$\{p, s\}, \{q, r\}, \{p, r\}, \{s, q\}$$  \hspace{1cm} (22)

or by all four parameters

$$\{p, s, q, r\}$$  \hspace{1cm} (23)

forced to $\{0,0,0,0\}$. This results in a trivial field with a checkerboard pattern, interchanging column/row pattern, or a combination hereof. In all cases the entropy of the field is equal to 0 since the only decisions are made either in the upper left corner or in the top left edge. This can be seen directly from the admissible configurations since they will be limited to a subset of either $abcd = \{01[10], 10[01], 11[00], 00[11]\}$ or $abcd = \{0[010], 1[101], 0[101], 1[011]\}$.

B4 are absorbing fields which are defined as constraints where $p = q = 0$ and the non-admissible configurations additionally contains $abcd = [a11d]$, where $s = r = 0$ and the non-admissible configurations additionally contains $abcd = [a00d]$, where $r = 0$ or $q = 0$ and the non-admissible configurations additionally contains $abcd = [0b1d] \land \overline{abcd} = [1b0d]$, or where $s = 0$ or $p = 0$ and the non-admissible configurations additionally contains $abcd = [01cd] \land \overline{abcd} = [10cd]$. In these cases the probability of the occurrence of a symbol using bit-stuffing depends on the distances to the starting edges; a structure which cannot be reflected by PRF. This category
implies non-stationarity. An example is a modified hard-square constraint where \((A, B = 0, C = 0, D = 1)\) is added to the non-admissible configurations. In this example the PRF will degenerate to uniform zeros.

Finally, B5 is defined by constraints \(c_i\) where the set of non-admissible configurations \(F_i\) includes all possible combinations of \((ABC)\) without belonging to a prior category:

\[(abcd) \in F_i \quad \lor \quad (abcd) \notin F_i\]

\[\text{for } abc = \{[000],[001],\ldots,[111]\} \quad (24)\]

In this case the field is defined only by the top and left edge and the per symbol field entropy is equal to 0.

A necessary condition to construct a PRF with positive entropy for a given constraint is that the constraint does not belong to any of the categories listed in this subsection. This can be determined without introducing probabilities. Fields constructed under the constraints in these categories can not contain all admissible configurations (B1), are not stationary (B1,B2,B4) and/or have a field entropy equal to 0 (B2,B3,B5). If the constraint is not categorized by now, we need to apply PRF analysis as described in the next section to determine whether the entropy of the PRF is non-zero.

B. PRF analysis

After analyzing the constraints within 2x2 blocks, we proceed and analyze any uncategorized constraints as PRF. For this reason the categories listed next are denoted \(P_k\) where \(k\) is an index. The first category P1 we define as the constraints where the only PRF solution is:

\[p = r = s = q = 0.5 \quad (25)\]

due to the requirements given by (13) and (14). In this case the entropy contribution calculated in (16) will be 0 and the calculated maximum entropy will only depend on contributions from (15) (of which there might be none). The 354 constraints in this category can be separated into 186 families, in which 3 family fathers have maximum entropy equal to 0.5, 34 family fathers have maximum entropy equal to 0.25 and the rest have maximum entropy equal to 0.

Category P2 is defined as constraints where the only configurations that can possibly contribute to the entropy is of the form (16) and satisfy \(\hat{a} = d, b = c\). Due to (13) this will lead to a maximum PRF entropy equal to 0. Constraints belonging to P1 or P2 can be analyzed by choosing e.g. the lower left corner as starting point for the PRF (corresponding to a rotation of the configurations), which might lead to a better PRF solution.

P3 contains the constraints which can be modeled by the PRF approach with positive field entropy less than 1. For these constraints we search for the maximum entropy over 1 to 3 of the free parameters from \(p, q, r, s\). We provide test statistics and examples for this in Section IV.

Finally, P4 is the unconstrained case in which all configurations are admissible. In this case the maximum field entropy is equal to 1 with i.i.d. row and column distributions.

IV. RESULTS

We classify each of the \(2^{16}\) possible constraints as belonging to one of the categories listed in Table I and as detailed in the previous section. In these categories, B1 is considered to be invalid, B2-5 have field entropy equal to 0, P1-2 are special cases for the PRF model and P4 is the single unconstrained case. We apply the PRF to the fathers of the families in P3.

<table>
<thead>
<tr>
<th>Index</th>
<th>Short Description</th>
<th>Number of cases</th>
</tr>
</thead>
<tbody>
<tr>
<td>B1</td>
<td>Invalid due to traps</td>
<td>115502</td>
</tr>
<tr>
<td>B2</td>
<td>(H = 0), Absorbing Markov chain</td>
<td>9661</td>
</tr>
<tr>
<td>B3</td>
<td>(H = 0), Checkerboard and/or rows/cols</td>
<td>275</td>
</tr>
<tr>
<td>B4</td>
<td>(H = 0), Absorbing field</td>
<td>484</td>
</tr>
<tr>
<td>B5</td>
<td>(H = 0), all ((ABC))</td>
<td>600</td>
</tr>
<tr>
<td>P1</td>
<td>(p = r = s = q = 0.5)</td>
<td>354</td>
</tr>
<tr>
<td>P2</td>
<td>(H = 0) due to commutation</td>
<td>324</td>
</tr>
<tr>
<td>P3</td>
<td>(H &gt; 0), PRF applied</td>
<td>5972</td>
</tr>
<tr>
<td>P4</td>
<td>(H = 1), unconstrained</td>
<td>1</td>
</tr>
</tbody>
</table>

P3 consists of a total of 5972 constraints which were separated into 2645 families. For each family in P3, the optimal distributions and maximum PRF entropy were estimated as shown in Fig. 1. Most of the families in P3 have 2 members due to constraints being equal only through binary inversion. There exist 2584 of such families in P3. Only 38 constraints are completely unique (family size equal to 1) e.g. the uniform squares configuration (where \([0000]\) and \([1111]\) are the non-admissible configurations). There are 22 families where one of the variables \(p, q, r, s\) is forced to 0 and they all have size equal to 30. The biggest family size is equal to 106 (of which there is only 1). This is the family corresponding to the hard square problem. It should be noted that families can have members which belongs to category B1, but these are not part of the analysis since they are considered invalid.

Fig. 1: Histogram of the estimated maximum PRF entropies.

V. EXAMPLES

In this section, some specific examples of the implemented PRF methodology is shown. To get an approximate value of the capacity we use bands, extending the binary alphabet to an alphabet with \(2^{M}\) elements. We can now create the transfer (or adjacency) matrix \(T_M\) of the band and (when \(T_M\) is
C. No 1 columns

This was used to generate the image in Fig. 3 (a).

The non-admissible configurations are:

\[
\begin{bmatrix}
1 & 0 \\
0 & 1
\end{bmatrix}
\]

and also analyzed in [6] by shifting the bottom row of (3) to the left by one place, the non-admissible configurations are:

\[
\begin{bmatrix}
1 & 0 & 1 & 0 \\
0 & 1 & 1 & 1
\end{bmatrix}
\]

Future work could include a refined separation of categories with more strict description of the defining structure e.g. the category of constraints classified as invalid could be further divided depending on whether it is possible to fill the grid with a subset of the admissible configurations or not.

**REFERENCES**


