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Published in:
Journal of Applied Meteorology and Climatology

Link to article, DOI:
10.1175/JAMC-D-12-0319.1

Publication date:
2013

Document Version
Publisher’s PDF, also known as Version of record

Link back to DTU Orbit

Citation (APA):
A Study on the Effect of Nudging on Long-Term Boundary Layer Profiles of Wind and Weibull Distribution Parameters in a Rural Coastal Area

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(Manuscript received 29 November 2012, in final form 22 January 2013)

ABSTRACT

By use of 1 yr of measurements performed with a wind lidar up to 600-m height, in combination with a tall meteorological tower, the impact of nudging on the simulated wind profile at a flat coastal site (Høvsøre) in western Denmark using the Advanced Research version of the Weather Research and Forecasting model (WRF) is studied. It was found that the mean wind speed, the wind direction change with height, and the wind power density profiles are underestimated with the configuration of WRF used and that the impact of nudging on the simulated mean values was minor. Nudging was found to reduce the scatter between the simulated and measured wind speeds, expressed by the root-mean-square error, by about 20% between altitudes of 100 and 500 m. The root-mean-square error was nearly constant with height for the nudged case ($2.2 \text{ m s}^{-1}$) and slightly increased with height for the unnudged one, reaching $2.8 \text{ m s}^{-1}$ at 300 and 500 m. In studying the long-term wind speed variability with the Weibull distribution, it was found that nudging had a minor effect on the scale parameter profile, which is closely connected to the mean wind speed. Improvement by nudging was seen on the profile of the shape parameter. Without nudging, the shape parameter was underestimated at all heights; with nudging, the agreement was good up to about 100 m and above that height the shape parameter was underestimated.

1. Introduction

The two-parameter Weibull distribution of the wind speed is commonly used in wind-energy investigations. The available wind power density is proportional to the mean cube of the wind speed, which depends on both the scale and shape parameters used to describe a Weibull distribution. These parameters can be estimated from long-term measurements or modeled data of the wind field.

Wind observations from within the boundary layer are often not assimilated because of large discrepancies between measurements and model counterparts that are due to local terrain effects (Hahmann et al. 2010; Boilley and Mahfouf 2012). Observed wind speeds at greater heights can show large differences when using different reanalysis data to reinitialize the Weather Research and Forecasting (WRF) model (Floors et al. 2013). Verification of data assimilation techniques is now possible with the advent of new types of instruments, such as wind Doppler lidars, that observe winds with high temporal and vertical resolution and that have become popular research tools for studying the boundary layer structure (O’Connor et al. 2010).

Nudging, as well as other types of assimilation, relaxes the regional-model solution toward the driving global analysis (Deng and Stauffer 2005; Otte 2007), which ensures that solutions of the regional model do not drift.
from the synoptic-scale structures captured by the analysis. Lo et al. (2008) found that applying nudging from the coarse-resolution analysis improved the skill of the regional model for pressure, temperature, geopotential height, wind, and humidity.

Another way to limit this drift relies on periodic re-initialization of the simulations (Lo et al. 2008). Because considerable spinup time is required for each reinitialization, such an approach is computationally expensive. Von Storch et al. (2000) showed that some slowly varying meteorological parameters (e.g., soil moisture) that are essential for long-term calculations might be lost when applying reinitializations.

Here we present a case study of the impact of nudging on the profiles of wind and Weibull distribution parameters at a coastal site. The simulations are compared with 1 yr of wind profile measurements performed with a wind lidar up to 600 m in height. The nudging was performed for wind, temperature, and humidity from a global model to the outermost domain in the WRF model. We investigate the ability of the WRF meteorological model to simulate the profiles of mean wind, power density, and the shape and scale parameters describing the Weibull distribution.

2. Site and measurements

The study covers the period 23 April 2010–31 March 2011. The measurements were carried out at the Danish National Test Station of Wind Turbines at Høvsøre (Gryning et al. 2007), Denmark, which is located on the western coast of Jutland. Except for the presence of the North Sea to the west and a shallow lake to the south, the terrain is flat and homogeneous, consisting of grass, various agricultural crops, and a few shrubs. The intensively instrumented 116.5-m meteorological mast (56°26′26.0″N, 8°9′3.1″E) is located about 1.8 km east of the coastline and 200 m south of the closest wind-turbine stands. Observations from the 160-m top level of the light mast 300 m north of the meteorological tower were also used. Wind speed is measured at 10, 40, 60, 80, 100, 116.5, and 160 m with Riso P2546 cup anemometers (Pedersen 2004), and the wind direction at 10, 60, 100, and 160 m is measured with wind vanes on booms directed to the south.

A pulsed wind Doppler lidar (Leosphere WLS70) was operated during the campaign and was located about 20 m west of the meteorological mast. The wind Doppler lidar is equipped with a rotating silicon prism that provides an optical scanning cone of 15° to zenith. The lidar scans the atmosphere at four azimuth angles separated by 90°. One 360° full scan (rotation) is performed approximately every 30 s. The Doppler shift–based measurements of the wind are available every 50 m from 100 m above the ground to approximately 1–2-km height; the maximum altitude is dependent on the attainable 10-min-averaged carrier-to-noise ratio (CNR). The maximum measuring height is often determined by cloud-base height, after which the lidar signal (1.55-nm wavelength) is rapidly attenuated.

3. Numerical modeling

Wind profiles are predicted using the Advanced Research version of the WRF model, version 3.2.1, developed by the National Center for Atmospheric Research (Skamarock et al. 2008). It is a numerical weather prediction and atmospheric simulation system that is designed for both research and operational applications. Here, the model simulations are performed in long-term analysis mode. The model setup includes the “Noah” land surface scheme (Chen and Dudhia 2001), the Thompson microphysics scheme (Thompson et al. 2004), the planetary boundary layer scheme of Mellor–Yamada/Nakanishi and Niino, level 2.5 (Nakanishi 2001), and its corresponding surface-layer scheme. The WRF model is configured to calculate the meteorological parameters at 41 vertical levels from the surface to the 100-hPa pressure level. Eight of these levels are within the 600-m height extent of interest to this study, with the first model level at 14 m. Initial and boundary condition are taken from the Global Final Analyses data (FNL) every 6 h on a 1° × 1° grid. The real-time global sea surface temperature analysis from the National Centers for Environmental Prediction was used. Two domains were used, one with a horizontal grid size of 18 km ranging from 7.12°W to 22.9°E and from 49.1°N to 65.2°N with a time step of 120 s and one with a horizontal grid size of 6 km ranging from 3.57° to 17.4°E and from 53.1° to 59.7°N with a time step of 40 s. The simulations are initialized every 10 days at 1200 UTC, and, after a spinup time of 24 h, a time series of 10-min simulated meteorological forecast data from 25 to 264 h is generated. The model is run both without nudging and with nudging toward the FNL analysis. Nudging is applied for the wind, temperature, and humidity above the 10th model level, which approximately corresponds to 1400 m, on the outermost model domain during the whole simulation period. Except for the nudging, the configurations of the model simulations are the same.

4. Climatological description of the wind profile

The wind rose and total distribution of the wind speed from the lidar at 100 m are shown in Fig. 1, from which it is seen that the wind at Høvsøre is predominantly from
a westerly direction, corresponding to wind from the sea. As a consequence, the results from the analysis were influenced by the formation of internal boundary layers downwind from the abrupt change between sea and land. Floors et al. (2011) showed that the height of the internal boundary layer was typically 100 m at the measuring site. The study required coincident model and measurement (mast and lidar) profiles. To achieve high-quality data, a threshold sensitivity limit was imposed on the lidar data; this limit required that all lidar measurements within a profile up to 600 m have a CNR > −22 dB, in accordance with Floors et al. (2013). At least 31% of profiles satisfied this criterion, corresponding to 15,359 ten-minute mean profiles.

a. Mean wind profile

Figure 2 shows the profiles of the mean wind speed and wind direction. The wind direction of the lidar is relative to the direction at the mast at 100 m. It can be seen that the effect of nudging on these profiles is small. Near the ground, the agreement between the measured and modeled values of the wind speed is good; above approximately 60 m, the model underestimates the mean wind speed. For the wind direction above 100 m,
Fig. 3. Scatterplots of wind speed measurements and WRF model simulations at 100, 300, and 500 m height (left) without nudging and (right) with nudging. Only every 60th data point is shown for clarity.
the WRF analysis produced a smaller change with height than observed.

b. Scatterplots

The scatter between wind speed measurements and model results at 100, 300, and 500 m is shown in Fig. 3, and a comparison between model and measurements is provided in Table 1. It can be seen that both model simulations (with and without nudging) underpredict the wind speed, but the nudged simulations are somewhat closer to the measurements. The underprediction increases with height, being around 3% (normalized bias) at 100 m and increasing to 4%–5% at 300 and 500 m. Accordingly, the slope coefficient is always less than 1 and is nearly constant with height.

The root-mean-square error (RMSE) is used to illustrate the comparison between the individual measurements and the model prediction. There is a clear improvement in the performance of the model when it is nudged; RMSE is approximately 2.2 m s$^{-1}$ at 100 m when the model is nudged and is approximately 2.6 m s$^{-1}$ when the model is not nudged, RMSE slightly increases with height, reaching 2.3 m s$^{-1}$ at 300 m for the nudged model and 2.9 m s$^{-1}$ at 500 m for the model with no nudging.

5. Weibull distribution

The long-term frequency distribution of the horizontal wind speed is often presented in the form of a two-parameter Weibull distribution:

$$f(u) = \frac{k}{A} \left(\frac{u}{A}\right)^{k-1} \exp\left[-\left(\frac{u}{A}\right)^k\right],$$

where $f(u)$ is the frequency of occurrence of the wind speed $u$. In this Weibull distribution, the scale parameter $A$ has the same units as the wind speed and $k$ is the shape parameter.

The $A$ and $k$ parameters are related to the average wind speed $\bar{u}$ for the entire distribution through the gamma function $\Gamma$:

$$\bar{u} = A\Gamma(1 + 1/k).$$

For typical wind speed distributions over homogeneous terrain, $k$ falls in the range of 1.5–3 (Wieringa 1989; Lun and Lam 2000), and $A$ is near proportional to the mean wind speed for typical $k$ values (Bhattacharya and Bhattacharjee 2010).

This distribution has received considerable attention in relation to wind-energy applications because it attempts to account for the frequency of high wind speeds, which has an important contribution to wind power yield. Here, we derive the $A$ and $k$ parameters in the Weibull distribution from measurements and simulations using the Climate Analyst utility in the Wind Atlas Analysis and Application Program (WAsP), version 10 (Troen and Petersen 1989). The results were checked by a graphical method described in Scholz (2008).

a. Scale parameter

The comparison of the modeled scale parameter $A$ with measurements shows similarities with the wind speed. Below 60 m, simulations predict the $A$ parameter well. Above 60 m, the simulated scale parameter gradually decreases relative to the measurements. As with the mean wind speed, it can be seen that the sensitivity to nudging is minor (Fig. 4, left panel).

b. Shape parameter

Contrary to the scale parameter, which has a mostly smooth vertical profile, the shape parameter $k$ has a very characteristic vertical profile. It increases from the surface value to a maximum located at around 100–200 m, and then above this layer it decreases toward its tropospheric value. The shape of the profile is related to the balance between the diurnal variation of the meteorological conditions near the surface and the variability of the synoptic conditions prevailing in the region. An assessment of the $k$ profile from model output illustrates the ability of the model to simulate this balance.

We found that nudging has a large impact on the shape parameter. When nudged, the simulation agrees

<table>
<thead>
<tr>
<th>Simulation</th>
<th>With nudging</th>
<th>Without nudging</th>
</tr>
</thead>
<tbody>
<tr>
<td>Height = 100 m</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Slope coef</td>
<td>0.95</td>
<td>0.94</td>
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<tr>
<td>Bias (m s$^{-1}$)</td>
<td>−0.28</td>
<td>−0.37</td>
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<td>Normalized bias (%)</td>
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<td>−3.45</td>
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<tr>
<td>Height = 300 m</td>
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<td></td>
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<tr>
<td>Slope coef</td>
<td>0.95</td>
<td>0.94</td>
</tr>
<tr>
<td>Bias (m s$^{-1}$)</td>
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<td>−0.58</td>
</tr>
<tr>
<td>Normalized bias (%)</td>
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<td>−4.63</td>
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<tr>
<td>RMSE (m s$^{-1}$)</td>
<td>2.30</td>
<td>2.83</td>
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<tr>
<td>Height = 500 m</td>
<td></td>
<td></td>
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<tr>
<td>Slope coef</td>
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<td>0.94</td>
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<tr>
<td>Bias (m s$^{-1}$)</td>
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<td>−0.57</td>
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<tr>
<td>Normalized bias (%)</td>
<td>−4.44</td>
<td>−4.45</td>
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<tr>
<td>RMSE (m s$^{-1}$)</td>
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<td>2.86</td>
</tr>
</tbody>
</table>
very well with the measurements up to 100 m while it continues to underestimate the shape parameter above this height. The height of the internal boundary layer at Høvsøre is approximately 100 m and can influence the scale and shape parameter. When there is no nudging in the model, the underprediction is greater at all heights (Fig. 4, right panel).

6. Power density

Wind power density is a function of height and is roughly proportional to the cube of the wind speed. We calculated wind power densities using the Climate Analyst utility in WAsP. Near the ground (Fig. 5), we found good agreement between the power density estimated from the measurements and the model simulations. Above 60 m, the power density began to be underestimated by the simulations. Nudging displayed no impact on the simulations up to 300 m, although there was evidence for some slightly negative effect from nudging above this level.

7. Discussion and conclusions

A full year of measurements of the wind profile performed at a rural coastal site in a windy climate has been analyzed and compared with simulations made with the WRF model. The measurements were carried out with a 600-m-range wind Doppler lidar in combination with a tall meteorological mast. In this study, we focused on the impact of nudging on the profiles of wind and Weibull distribution parameters. We found that 1) nudging had a minor effect on the profiles of the scale parameter in the Weibull distribution, the mean wind speed, the change of wind direction with height, and the wind power density and 2) nudging had a major effect on the profile of the shape parameter in the Weibull distribution and the RMSE between modeled and measured wind speed.

The wind speed and its Weibull distribution are key elements in wind-energy studies. From Fig. 4 it can be seen that nudging reduces the underestimation of both the scale and shape parameters. Underestimation of the scale parameter suggests underestimation of the power density. In contrast, underestimation of the shape parameter...
parameter signifies higher variability of the wind speed and hence larger power density. The combination of these two effects results in nudging having very little influence on the power density estimations up to 300 m.

Acknowledgments. The study was supported by the Danish Council for Strategic Research, Project 2104-08-0025 named “Tall Wind,” the Nordic Centre of Excellence program CRAICC, and the Danish Environmental Agency Project M 112-00270. We are thankful to the Test and Measurements section of DTU Wind Energy for the maintenance of the Høvsøre database and to Dr. Ewan O’Connor, who kindly read through the manuscript.

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