Abstract

This paper presents a simulation study of a low-complexity optical packet switching Quality of Service differentiation scheme, aiming at minimising the penalty of offering packet loss rate isolation in an optical packet switch with a wavelength converter pool. Special emphasis is given to potential improvements, impact of node dimensions and overload situations.

1 Introduction

Efficient contention resolution, avoiding excessive hardware counts, is an important target in Optical Packet Switching (OPS) and Optical Burst Switching (OBS) research. This has motivated Tuneable Wavelength Converter (TWC) pool designs, e.g. Shared Per Node (SPN) [1-2], and Shared Per Waveband Plane (SPWP) [3]. Moreover, asynchronous operation with variable length packets is attractive, avoiding complex synchronisers and providing a good match with Internet traffic [4]. Finally, differentiating Quality of Service (QoS) in the optical layer may facilitate the transition from a Best-Effort (BE) to a QoS aware Internet [4]. This paper addresses these issues, by investigating the performance of a recently proposed QoS differentiation algorithm, suitable for an SPN optical packet switch [5].

2 Best-Effort switch performance

We evaluate performance of a single optical packet switch by discrete event-driven numerical simulations in OPNET. Asynchronous operation is implemented by a per-wavelength Poisson packet arrival process with exponential packet length distribution, subject to per-wavelength FIFO buffers to emulate serialised packet output clocking. Packet CoS and output fibre are uniformly distributed. The generic node design is illustrated in Figure 1, where the Wavelength Conversion Ratio (WCR) denotes the relative size of the SPN TWC pool, thus governing TWC- and switch matrix port count. In a BE scenario, Figure 2 shows the impact of the node adjacency, F, the wavelength count on each fibre, W, and the WCR, with 95 % confidence intervals. For a fixed load, L=0.7, the PLR decreases down to a minimum, given by F and W, with increasing WCR. Hence, achievable TWC count reduction depends on the required PLR.

3 QoS differentiation algorithm

When the traffic consists of two Classes of Service (CoS) with different PLR requirements, QoS differentiation has two potential benefits: i) achieve lower minimum PLR than...
imposed by L, F and W in the BE case, and ii) operate with a lower WCR than the BE switch, whilst still comply with the most demanding CoS.

Figure 3 details the QoS algorithm, aiming at obtaining a good performance-complexity trade-off, by using an Access Restriction (AR) based approach. A TWC is only used if the packet cannot achieve Direct Mapping (DM). In this case, the scheduler only allocates CoS2 packets if the number of free output wavelengths (OWLs) on the requested output fibre, F, and the number of free TWCs in the pool, termed \(N_{\text{OWL}}(F)\) and \(N_{\text{TWC}}\) respectively, are above a threshold defined by the ratios \(R_{\text{WL}}\) and \(R_{\text{WC}}\) respectively. Ideally, any QoS motivated discard of the CoS2 packet should be rewarded by avoidance of loss of a CoS1 packet. However, in asynchronous operation, the scheduling is done without knowing its effects on later arriving packets. An optimum in asynchronous operation, the scheduling is done without saving TWCs. Figure 6 shows that the DM preference does reduce penalty for the node with \(W=128\), but its impact depends on the desired isolation for \(W=64\).

Figure 4 illustrates the PLR of CoS1 and of CoS2 as a function of the AR parameters, by scanning five RWC values, for \(W=64\) and for \(W=128\).

4 QoS algorithm performance

4.1 Single- vs. two dimensional AR schemes

Figure 4 illustrates the PLR of CoS1 and of CoS2 as a function of the AR parameters, by scanning five RWC values for each of the three \(R_{\text{WL}}\) values, for \(W=64\) and for \(W=128\). The WCR values are 0.625 and 0.57, respectively. In both cases, when both \(R_{\text{WC}}\) and \(R_{\text{WL}}\) are zero, PLR\(_{\text{CoS1}}\) and PLR\(_{\text{CoS2}}\) are approximately equal, and the resulting PLR\(_{\text{BE}}\) values of \((1.6\pm0.1)\times10^{-3}\) and \((1.1\pm0.1)\times10^{-3}\), respectively, match well corresponding curves in Figure 2.

Figure 5 illustrates resulting penalty as a function of the AR parameters, by scanning five RWC values, for \(W=64\) and for \(W=128\). For each of the three \(R_{\text{WL}}\) values, for \(W=64\) and for \(W=128\).

4.2 Impact of Direct Mapping

A peculiarity of the algorithm is that it allows CoS2 packets to be allocated even when either of the AR thresholds is violated, provided that the packet can find its own wavelength free at the requested output fibre. This Direct Mapping (DM) preference is introduced in order to save TWCs. Figure 6 shows that the DM preference does reduce penalty for the node with \(W=128\), but its impact depends on the desired isolation for \(W=64\).

4.3 Impact of Node Adjacency

Figure 2 shows that increasing \(F\) from 4 to 8, improves TWC sharing, and enables a lower WCR for the same PLR\(_{\text{BE}}\). WCRs of 0.57 and 0.54 were chosen for \(W=64\) and \(W=128\), enabling PLR\(_{\text{BE}}\) of \((2.8\pm0.4)\times10^{-3}\) and \((1.4\pm0.1)\times10^{-3}\), respectively. Figure 7 shows that, in spite of the reduced WCR, increasing \(F\) lowers the penalty; otherwise the behaviour of the QoS algorithm is quite similar.
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4.4 Impact of overload situations

For statistical input traffic, the instantaneous input load at an optical packet switch fluctuates around the average value during simulations. In a real network, in periods of increased client layer traffic, the average load of the optical network may increase, unless a strict access policy is applied. Even so, it may also be that certain nodes experience higher average load than the network as a whole, in periods where unusually large portions of traffic passes by these nodes. On a BE network, increased network load increases PLR, as can be seen in Figure 8, for an isolation degree of 1. After this initial penalty, the overload situation has a limited impact on the QoS algorithm differentiation so that the PLR of CoS1 can be kept below $10^{-5}$, by adjusting the AR parameters.

Figure 7. Impact of node adjacency.

Figure 8. Impact of 5 and 10% overload.

5 Discussion

The granularity in the parameter scan was somewhat limited, and we expect increased granularity to demonstrate a slight performance improvement of the QoS differentiation schemes. Nevertheless, the study clearly shows that the two-dimensional QoS differentiation scheme outperforms single-dimensional systems.

Whether DM is beneficial or not was found to depend on the system parameters and the desired isolation ratio; hence, this issue should be studied in each case. It is expected that DM is more favourable when TWCs are scarce, and when the node adjacency is low, since DM packets also increases the probability of DM for later arriving packets that should be switched between the same fibres, thereby saving even more TWCs.

It was shown that performance improved when increasing F and W, when maintaining or even lowering the WCR. However, hardware realisation issues limit scalability, such as limited switch matrix port counts and/or TWC wavelength operation range.

Considering load variations, decreases in load would lead to decreased penalties, particularly when the parameters of the QoS differentiation scheme are optimised, idem to overload situations. Hence, to make the QoS differentiation scheme as efficient as possible, the QoS scheme requires either capability of signalling such changes of load by the management system, or distributed load monitoring with associated parameter adjustment.

The choice of Poisson arrival will for most systems yield a better performance than more bursty traffic patterns [6]. On the other hand, high priority packets constitute as much as 50 % of overall load. Lowering this ratio would significantly relax system requirements, enabling lower overall PLR and/or hardware savings in terms of WCR.

6 Conclusion

The AR-based QoS differentiation scheme is suitable for a SPN based TWC pool design. It is scalable with respect to node dimensions, and can maintain the PLR of the high-priority CoS, at the expense of an increase in the PLR of the low-priority CoS, during overload situations.

REFERENCES