Contingency Estimation of States for Unmanned Aerial Vehicle using a Spherical Simplex Unscented Filter - DTU Orbit (11/03/2019)

Contingency Estimation of States for Unmanned Aerial Vehicle using a Spherical Simplex Unscented Filter. / Hahn, Tobias; Hansen, Søren; Blanke, Mogens.
Research output: Research - peer-review › Article in proceedings – Annual report year: 2012