Publications:

**Novel Levenberg–Marquardt based learning algorithm for unmanned aerial vehicles**
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**Modeling level change in Lake Urmia using hybrid artificial intelligence approaches**
Publication: Research - peer-review › Journal article – Annual report year: 2017

**Model of car wing active control in order to increase stability of the car on corners of roads**
Publication: Research - peer-review › Article in proceedings – Annual report year: 2017

**Sliding mode fuzzy rule base bilateral teleoperation control of 2-DOF SCARA system**
Publication: Research - peer-review › Article in proceedings – Annual report year: 2017

**A multi-objective genetic type-2 fuzzy extreme learning system for the identification of nonlinear dynamic systems**
Publication: Research - peer-review › Article in proceedings – Annual report year: 2017

**Comparative analysis of three approaches of antecedent part generation for an IT2 TSK FLS**
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**Multi objective optimal allocation of fault current limiters in power system**
Publication: Research - peer-review › Journal article – Annual report year: 2017

**Learning Control of Fixed-Wing Unmanned Aerial Vehicles Using Fuzzy Neural Networks**
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**Artificial bee colony optimization of interval type-2 fuzzy extreme learning system for chaotic data**
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